



# Universe and Matter conjectured as a 3-dimensional Lattice with Topological Singularities

Gérard Gremaud  
2016

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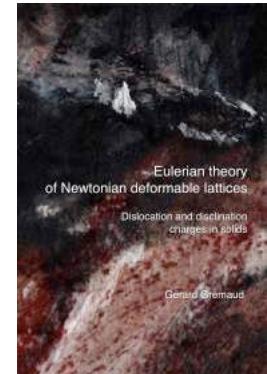
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Presses Polytechniques et Universitaires Romandes (PPUR),  
Lausanne, 2013, 750 pages  
(ISBN 978-2-88074-964-4)



Amazon Press,  
Charleston (USA),  
2016, 312 pages  
(ISBN 978-2-8399-1943-2)

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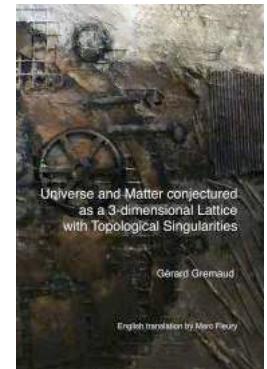
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Amazon Press,  
Charleston (USA),  
2016, 664 pages  
(ISBN 978-2-8399-1940-1)



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2016, 650 pages  
(ISBN 978-2-8399-1934-0)

# ***Part I – Eulerian theory of deformable media***

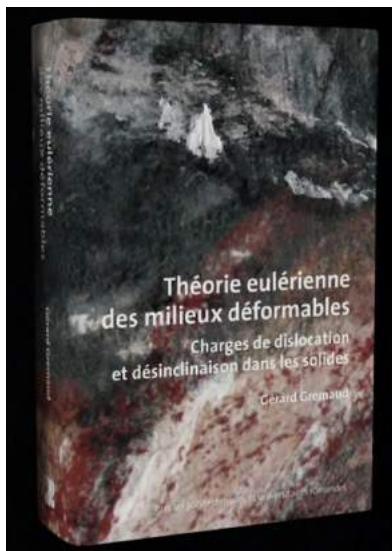
***I A - Eulerian theory of newtonian deformable media***

***I B - Application: phenomenologies of usual fluids and solids***

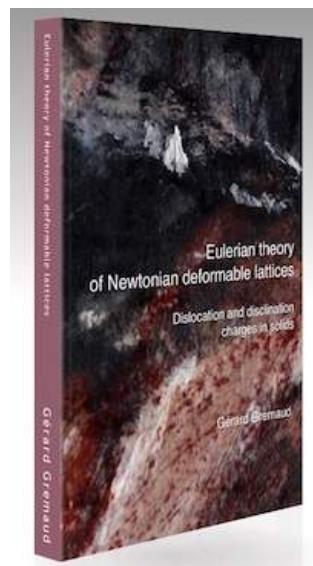
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***Conclusion of the first part***



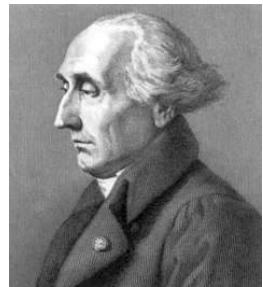
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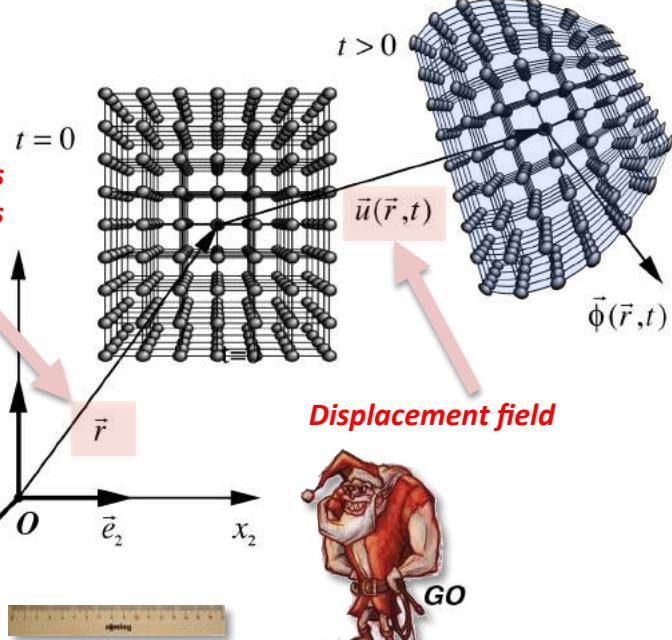
# IA - Eulerian theory of newtonian deformable medias

## Coordinates systems



Joseph Louis Lagrange  
(1736-1813)

### Lagrange coordinates



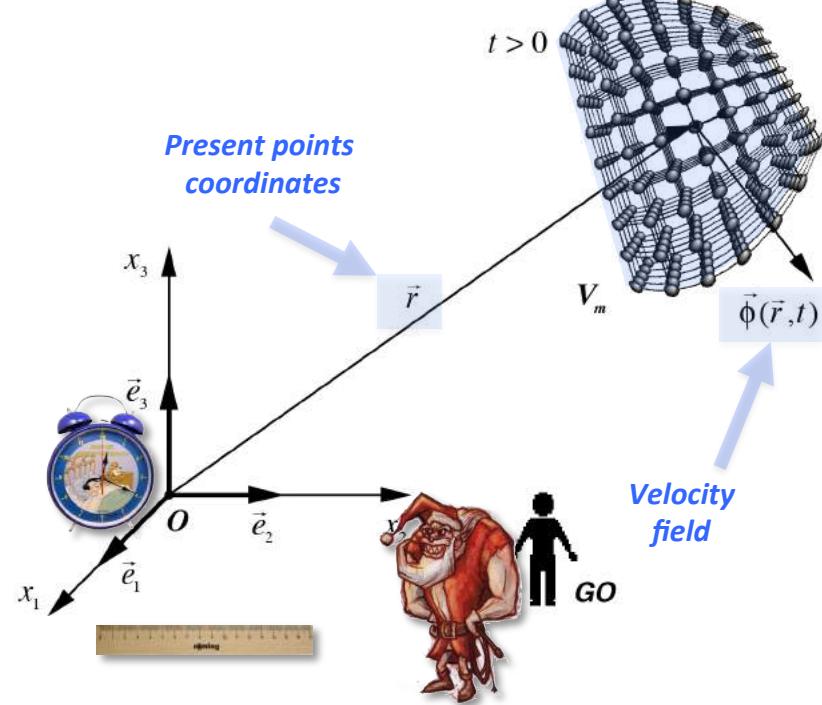
Differential geometries  
(Riemann-Cartan, Finsler, Kawaguchi, ...)



### Euler coordinates

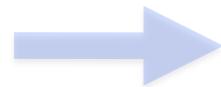


Leonhard Euler (1707-1783)

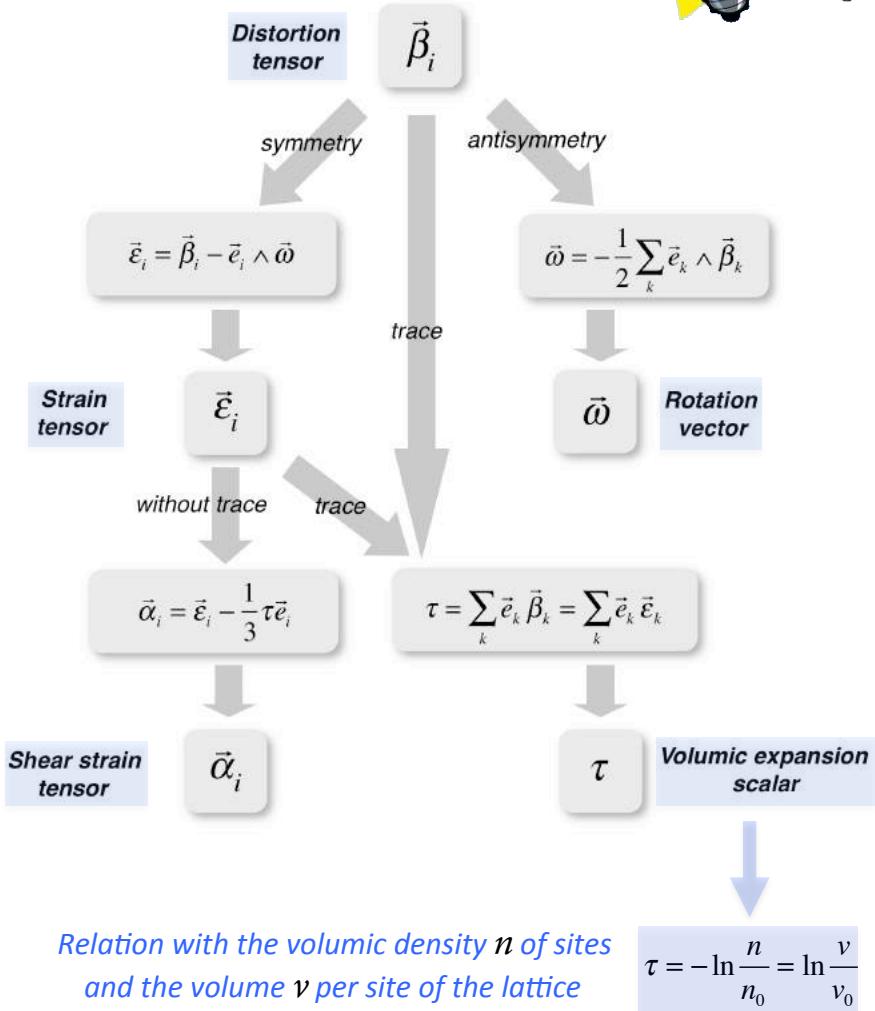
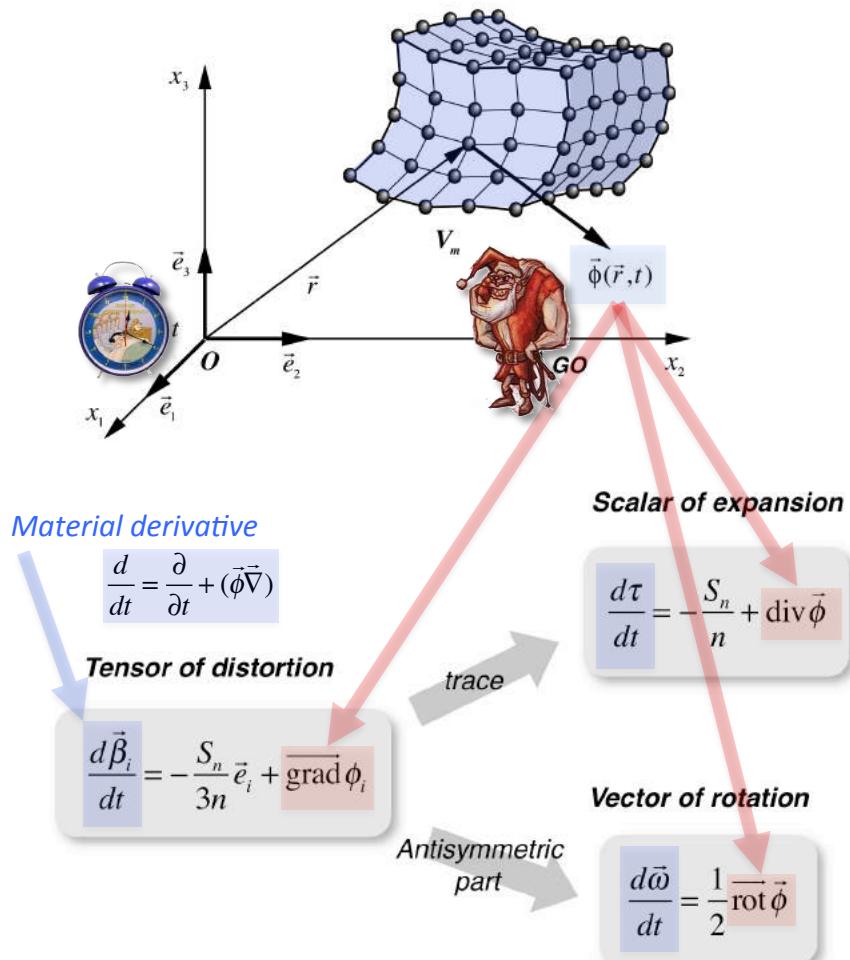


# Geometrokinetic equations and distortion tensors in Euler coordinates

Temporal variations of the lattice « distortions »  
are linked to the spatial variations of the velocity field



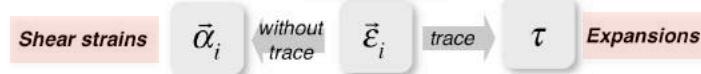
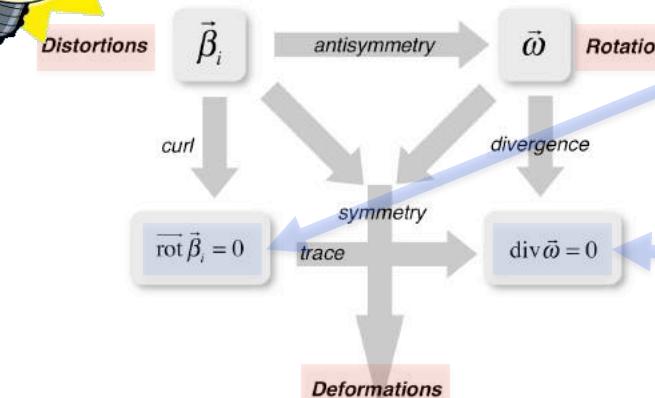
Vectorial representation  
of the distortion tensors



# Geometrocompatibility equations and contortion tensors in Euler coordinates



## Distortion and contortion tensors and geometrocompatibility equations



**Contortions**  $\vec{\chi}_i = [\vec{\text{rot}} \vec{\epsilon}_i]^T = \vec{\text{grad}} \omega_i$

transposition of curl  $\rightarrow \vec{\chi}_i$

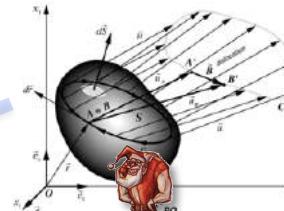
antisymmetry of curl  $\rightarrow \vec{\chi}_i$

curl  $\rightarrow \vec{\text{rot}} \vec{\chi}_i = 0$

divergence  $\rightarrow \text{div} \vec{\chi}_i = 0$

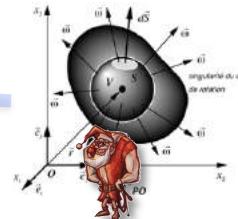
antisymmetry  $\rightarrow \vec{\chi}_i = -\sum_k \vec{e}_k \wedge \vec{\text{rot}} \vec{\epsilon}_k = \vec{\text{rot}} \vec{\omega}$

**Torsions**  $[\vec{\chi}_i]^S \rightarrow \sum_k \vec{\chi}_k \equiv 0$



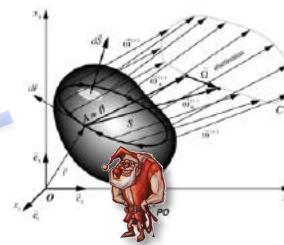
Continuity of the displacement field

$$\oint_C d\vec{u} = - \sum_k \vec{e}_k \iint_S \vec{\text{rot}} \vec{\beta}_k d\vec{S} = 0 \quad ; \quad \forall C$$



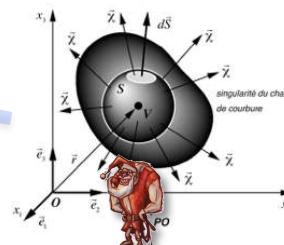
No singularity by divergence of the rotation field

$$\iint_S \omega_{\perp} dS = \iint_S \vec{\omega} d\vec{S} = \iiint_V \text{div} \vec{\omega} dV = 0 \quad ; \quad \forall S$$



Continuity of the rotation field associated to the deformations

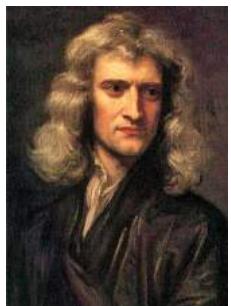
$$\oint_C d\vec{\omega}^{(\varepsilon)} = \sum_k \vec{e}_k \iint_S \vec{\text{rot}} \vec{\chi}_k d\vec{S} = \sum_k \vec{e}_k \iint_S \vec{\text{rot}} [\vec{\text{rot}} \vec{\epsilon}_k]^T d\vec{S} = 0$$



No singularity by divergence of the flexion field

$$\iint_S \chi_{\perp} dS = \iint_S \vec{\chi} d\vec{S} = \iiint_V \text{div} \vec{\chi} dV = \sum_k \vec{e}_k \iiint_V \vec{\text{rot}} \vec{\text{rot}} \vec{\epsilon}_k dV = 0$$

## The only three necessary physical principles in Euler coordinates



Isaac Newton  
(1643-1727)

*Axiom of  
newtonian  
dynamics*

$$e_{cin} = \frac{1}{2} m \vec{\phi}^2$$



*Continuity principle  
for the newtonian inertial mass*

$$\frac{\partial \rho}{\partial t} = S_m - \operatorname{div}(\rho \vec{\phi} + \vec{J}_m) = S_m - \operatorname{div}(n \vec{p}) \quad (1)$$

*Axiom of  
the first principle + kinetic energy  
of thermodynamics*

$$dU = \delta W + \delta Q \quad e_{cin} = \frac{1}{2} m \vec{\phi}^2$$



*Continuity principle for the total energy*

$$n \frac{du}{dt} + n \frac{de_{cin}}{dt} = S_w^{ext} - \operatorname{div} \vec{J}_w - \operatorname{div} \vec{J}_q - u S_n - e_{cin} S_n \quad (2)$$



Sadi Carnot  
(1837-1894)

*Axiom of  
the second principle  
of thermodynamics*

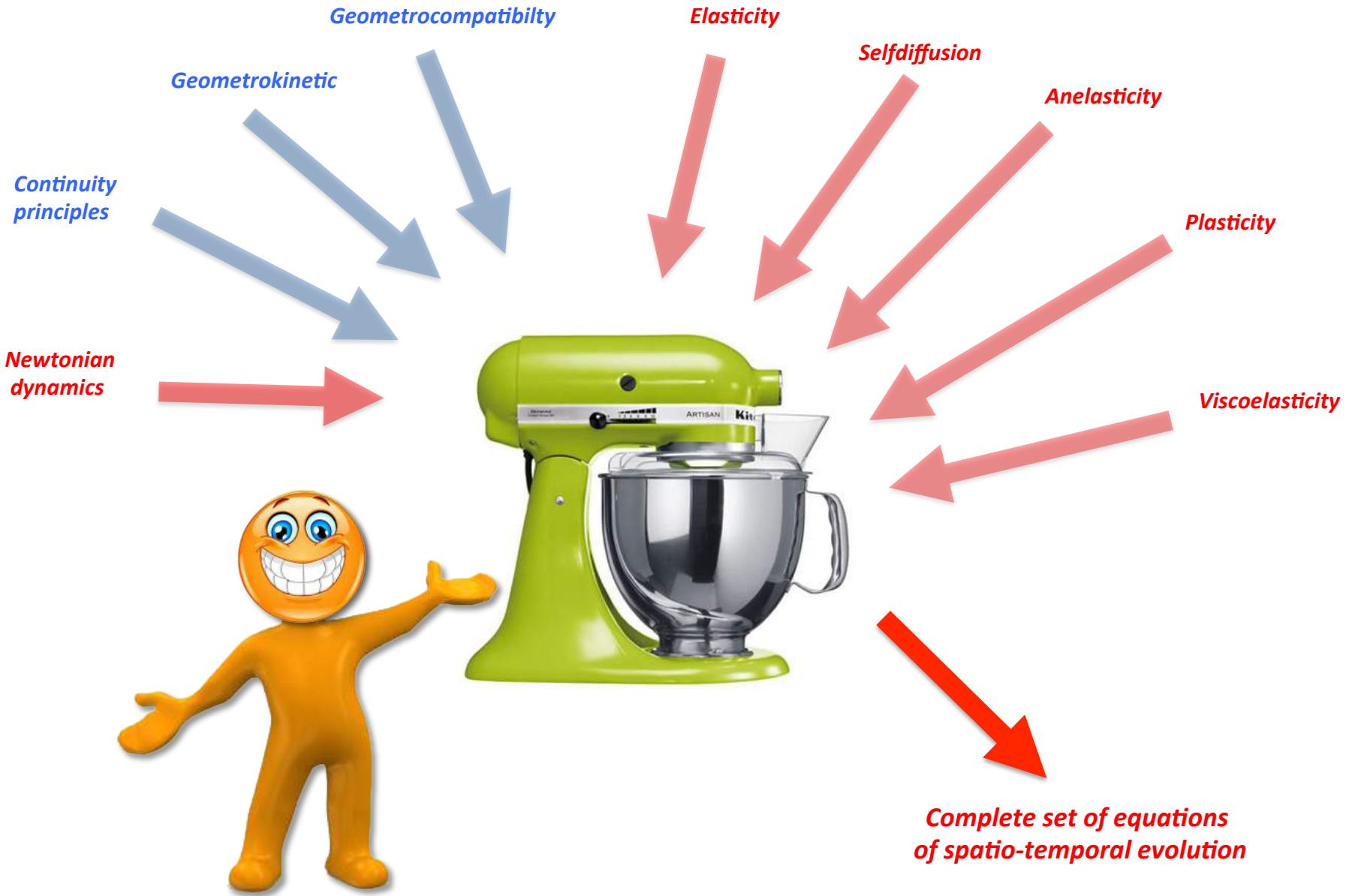
$$dS \geq \frac{\delta Q}{T}$$



*Continuity principle for the entropy*

$$n \frac{ds}{dt} = S_e - \operatorname{div} \left( \frac{\vec{J}_q}{T} \right) - s S_n \quad (3)$$

Mix all these ingredients



# The complete set of equations of spatio-temporal evolution in Euler coordinates

Topological  
equations



## Fundamental equations

Heat  
equation



Topology

*Equations topologiques*

$$\begin{cases} \frac{d\vec{\beta}_i}{dt} = \overline{\text{grad}} \phi_i & (1) \\ \frac{d\vec{\omega}}{dt} = \frac{1}{2} \overline{\text{rot}} \vec{\phi} & (2) \\ \frac{d\tau}{dt} = \text{div} \vec{\phi} & (3) \end{cases}$$

$$\begin{cases} \overline{\text{rot}} \vec{\beta}_i = 0 & (4) \\ \text{div} \vec{\omega} = 0 & (5) \\ d/dt = \partial/\partial t + (\vec{\varphi} \vec{\nabla}) & (6) \\ \vec{\varphi} = \vec{\phi} - \vec{\phi}_0(t) - \vec{\omega}_0(t) \wedge \vec{r} & (7) \end{cases}$$

$$\begin{cases} \vec{\beta}_i = \vec{\beta}_i^{(\delta)} + \vec{e}_i \wedge \vec{\omega}_0(t) = \vec{\beta}_i^{\text{cl}} + \vec{\beta}_i^{\text{an}} + \vec{\beta}_i^{\text{pl}} + \vec{e}_i \wedge \vec{\omega}_0(t) & (8) \\ \vec{\omega} = -\frac{1}{2} \sum_k \vec{e}_k \wedge \vec{\beta}_k = \vec{\omega}^{(\delta)} + \vec{\omega}_0(t) = \vec{\omega}^{\text{cl}} + \vec{\omega}^{\text{an}} + \vec{\omega}^{\text{pl}} + \vec{\omega}_0(t) & (9) \\ \tau = \sum_k \vec{\beta}_k \vec{e}_k = \sum_k \vec{\beta}_k^{(\delta)} \vec{e}_k = \tau^{\text{cl}} + \tau^{\text{pl}} \quad (\tau^{\text{an}} = 0 \text{ par hypothèse}) & (10) \\ \vec{e}_i = \vec{\beta}_i - \vec{e}_i \wedge \vec{\omega} = \vec{\beta}_i^{(\delta)} - \vec{e}_i \wedge \vec{\omega}^{(\delta)} = \vec{e}_i^{\text{cl}} + \vec{e}_i^{\text{an}} + \vec{e}_i^{\text{pl}} & (11) \\ \vec{\alpha}_i = \vec{e}_i - \frac{1}{3} \tau \vec{e}_i = \vec{\alpha}_i^{\text{cl}} + \vec{\alpha}_i^{\text{an}} + \vec{\alpha}_i^{\text{pl}} & (12) \end{cases}$$

*Equations dynamique*

$$n \frac{d\vec{p}}{dt} = \rho \vec{g} + \sum_k \vec{e}_k \text{div} \vec{s}_k - \frac{1}{2} \overline{\text{rot}} \vec{m} - \overline{\text{grad}} p + nm\vec{\phi}_i \frac{dC_i}{dt} - nm\vec{\phi}_L \frac{dC_L}{dt} \quad (13)$$

$$\begin{cases} n = 1/v = n_0 \exp(-\tau^{\text{cl}}) & (14) \\ \vec{p} = m(\vec{\phi} + C_i \vec{\phi}_i - C_L \vec{\phi}_L) = m\vec{\phi} + m(C_i - C_L)\vec{\phi} + \frac{m}{n}(\vec{J}_i - \vec{J}_L) & (15) \\ \rho = mn(1 + C_i - C_L) & (16) \end{cases}$$

Dynamics

Thermic

*Equations thermiques*

$$nT \frac{ds}{dt} = -(\mu_L^* + \mu_i^*) S_{i-L} - (\mu_L^* + h^*) S_L^{\text{pl}} - (\mu_i^* - h^*) S_i^{\text{pl}} + T \vec{J}_L \vec{X}_L + T \vec{J}_i \vec{X}_i + \vec{s}_k^{\text{dis}} \frac{d\vec{\beta}_k^{\text{an}}}{dt} + \vec{m}^{\text{dis}} \frac{d\vec{\omega}_k^{\text{an}}}{dt} + \vec{s}_k \frac{d\vec{\beta}_k^{\text{pl}}}{dt} + \vec{m} \frac{d\vec{\omega}_k^{\text{pl}}}{dt} - \text{div} \vec{J}_q \quad (21)$$

$$\mu_L^* = \mu_L - \frac{1}{2} m(\vec{\phi}_L^2 - 2\Delta\vec{\phi}_L^2) \quad (22)$$

$$\mu_i^* = \mu_i + \frac{1}{2} m\vec{\phi}_i^2 \quad (23)$$

$$\vec{X}_q = \overline{\text{grad}} \frac{1}{T} \quad (24)$$

$$\vec{X}_L = \frac{1}{T} \left( -\overline{\text{grad}} \mu_L^* + m \frac{d}{dt} (\vec{\phi}_L - 2\Delta\vec{\phi}_L) - m\vec{g} \right) \quad (25)$$

$$\vec{X}_i = \frac{1}{T} \left( -\overline{\text{grad}} \mu_i^* - m \frac{d}{dt} (\vec{\phi}_i) + m\vec{g} \right) \quad (26)$$

$$h^* = f + Ts + pv + \frac{1}{2} m\vec{\phi}^2 - \mu_L C_L - \mu_i C_i \quad (27)$$

Diffusion



Newton  
equation

*Equations de diffusion*

$$\begin{cases} n \frac{dC_L}{dt} = (S_{i-L} + S_L^{\text{pl}}) - C_L (S_L^{\text{pl}} - S_i^{\text{pl}}) - \text{div} \vec{J}_L & (17) \\ n \frac{dC_i}{dt} = (S_{i-L} + S_i^{\text{pl}}) - C_i (S_L^{\text{pl}} - S_j^{\text{pl}}) - \text{div} \vec{J}_i & (18) \end{cases}$$

$$\begin{cases} \vec{J}_L = nC_L \Delta\vec{\varphi}_L = nC_L (\vec{\varphi}_L - \vec{\varphi}) = nC_L (\vec{\varphi}_L - \vec{\varphi}) & (19) \\ \vec{J}_i = nC_i \Delta\vec{\varphi}_i = nC_i (\vec{\varphi}_i - \vec{\varphi}) = nC_i (\vec{\varphi}_i - \vec{\varphi}) & (20) \end{cases}$$

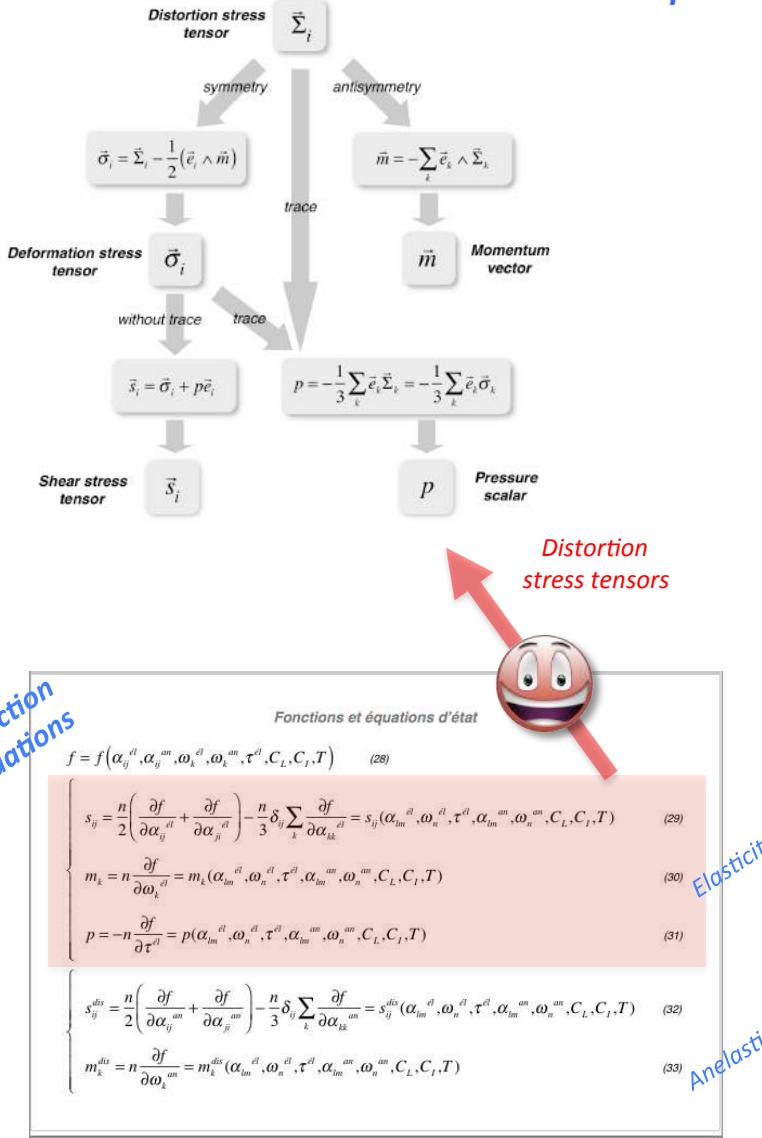


Selfdiffusion  
equations

# The complete set of equations of spatio-temporal evolution in Euler coordinates

## Phenomenological equations : state equations and dissipative equations

State function  
and equations



Elasticity  
Anelasticity  
Plasticity

State  
equations

Selfdiffusion

Anelasticity

Plasticity

Thermicity

Selfdiffusivity

Equations de dissipation: auto-diffusion et création-annihilation de paires

$$\left\{ \begin{array}{l} s = -\frac{\partial f}{\partial T} = s(\alpha_{lm}^{\text{el}}, \omega_n^{\text{el}}, \tau^{\text{el}}, \alpha_{lm}^{\text{an}}, \omega_n^{\text{an}}, C_L, C_I, T) \\ \mu_L = \frac{\partial f}{\partial C_L} = \mu_L(\alpha_{lm}^{\text{el}}, \omega_n^{\text{el}}, \tau^{\text{el}}, \alpha_{lm}^{\text{an}}, \omega_n^{\text{an}}, C_L, C_I, T) \end{array} \right. \quad (34)$$

$$\left\{ \begin{array}{l} \mu_I = \frac{\partial f}{\partial C_I} = \mu_I(\alpha_{lm}^{\text{el}}, \omega_n^{\text{el}}, \tau^{\text{el}}, \alpha_{lm}^{\text{an}}, \omega_n^{\text{an}}, C_L, C_I, T) \end{array} \right. \quad (35)$$

$$\left\{ \begin{array}{l} S_{I-L} = S_{I-L}(\mu_L^*, \mu_I^*, n, T, C_L, C_I, \dots) \end{array} \right. \quad (40)$$

Creation-annihilation  
of point defect pairs

$$\left\{ \begin{array}{l} \vec{J}_q = \vec{J}_q(\vec{X}_q, \vec{X}_L, \vec{X}_I, n, T, C_L, C_I, \dots) \\ \vec{J}_L = \vec{J}_L(\vec{X}_q, \vec{X}_L, \vec{X}_I, n, T, C_L, C_I, \dots) \end{array} \right. \quad (37)$$

$$\left\{ \begin{array}{l} \vec{J}_I = \vec{J}_I(\vec{X}_q, \vec{X}_L, \vec{X}_I, n, T, C_L, C_I, \dots) \end{array} \right. \quad (38)$$

$$\left\{ \begin{array}{l} S_{I-L} = S_{I-L}(\mu_L^*, \mu_I^*, n, T, C_L, C_I, \dots) \end{array} \right. \quad (40)$$

Equations de dissipation: anélasticité

$$\left\{ \begin{array}{l} \vec{s}_i = \vec{s}_i^{\text{cons}}(\vec{\alpha}_m^{\text{an}}, v, T, \dots) + \vec{s}_i^{\text{dis}}\left(\frac{d\vec{\alpha}_m^{\text{an}}}{dt}, v, T, \dots\right) \end{array} \right. \quad (41)$$

$$\left\{ \begin{array}{l} \vec{m} = \vec{m}^{\text{cons}}(\vec{\omega}^{\text{an}}, v, T, \dots) + \vec{m}^{\text{dis}}\left(\frac{d\vec{\omega}^{\text{an}}}{dt}, v, T, \dots\right) \end{array} \right. \quad (42)$$

Equations de dissipation: plasticité

$$\left\{ \begin{array}{l} \frac{d\tau^{pl}}{dt} = \frac{S_n}{n} = \frac{1}{n} (S_L^{pl} - S_I^{pl}) \end{array} \right. \quad (43)$$

$$\left\{ \begin{array}{l} S_L^{pl} = S_L^{pl}[(\mu_L^* + g^*), v, T, C_L, C_I, \dots] \end{array} \right. \quad (44)$$

$$\left\{ \begin{array}{l} S_I^{pl} = S_I^{pl}[(\mu_I^* - g^*), v, T, C_L, C_I, \dots] \end{array} \right. \quad (45)$$

$$g^* = f + pv + m\vec{\phi}^2/2 - \mu_L C_L - \mu_I C_I \quad (46)$$

$$\left\{ \begin{array}{l} \frac{d\vec{\alpha}_i^{pl}}{dt} = \frac{d\vec{\alpha}_i^{pl}}{dt}(\vec{s}_m, v, T, \dots) \end{array} \right. \quad (47)$$

$$\left\{ \begin{array}{l} \frac{d\vec{\omega}^{pl}}{dt} = \frac{d\vec{\omega}^{pl}}{dt}(\vec{m}, v, T, \dots) \end{array} \right. \quad (48)$$

Creation-annihilation  
of point defects

# The complete set of equations of spatio-temporal evolution in Euler coordinates

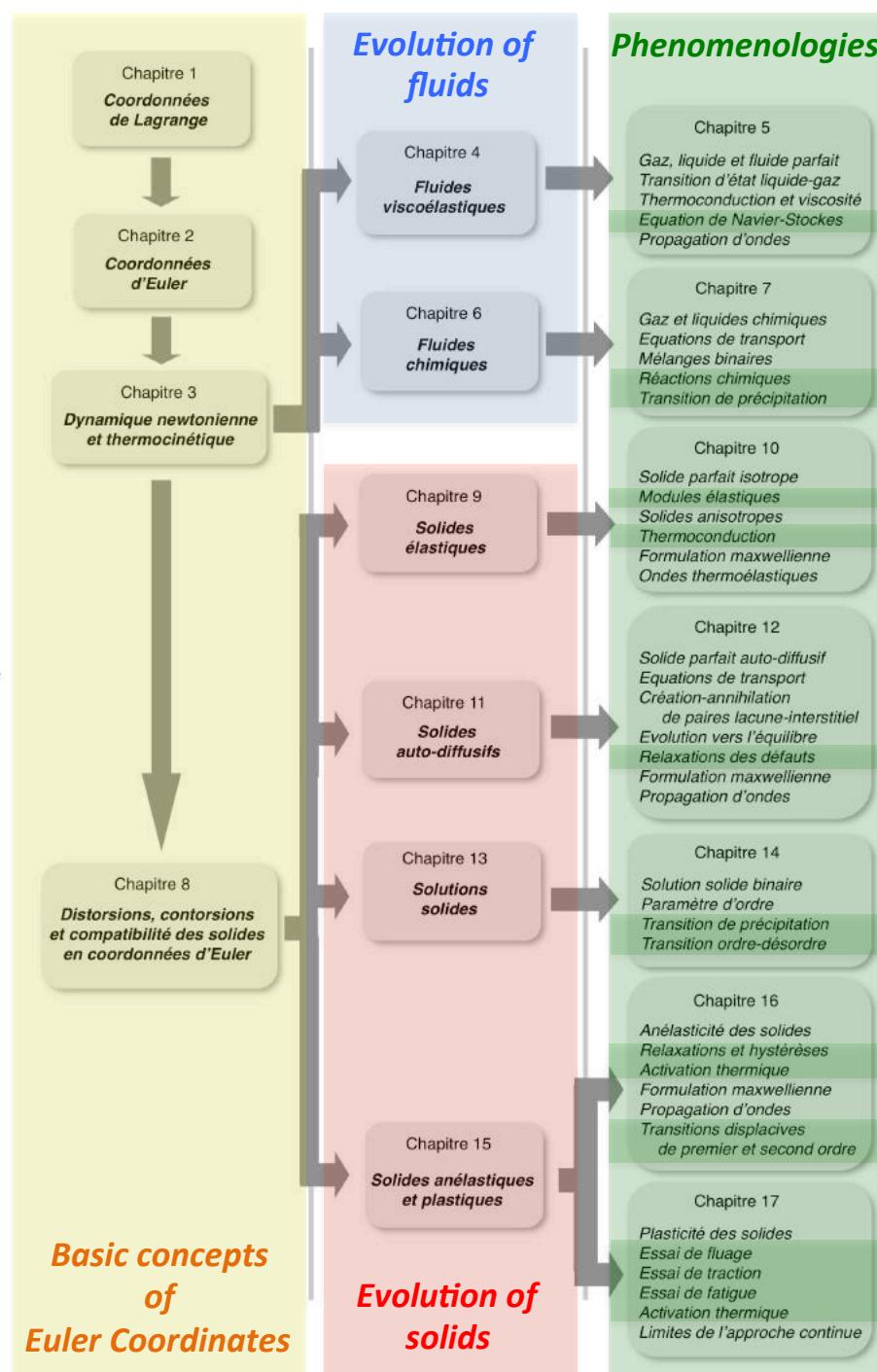
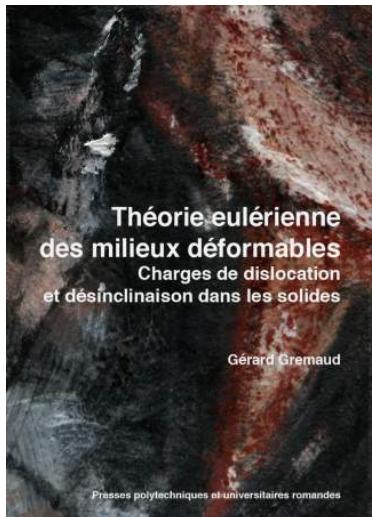
## Additional equations

<i>Continuité de la masse</i> $\frac{\partial \rho}{\partial t} = -\operatorname{div}[\rho \vec{\phi} + m(\vec{J}_I - \vec{J}_L)] = -\operatorname{div}(n \vec{p}) \quad \text{dans } Q_{\xi_1 \xi_2 \xi_3} \quad (49)$	<i>Inertial mass continuity</i>  <i>Work flux</i> <i>Surface forces</i>  <i>Entropy source</i>  <i>Energy balance</i>
<i>Flux de travail et force de surface</i> $\left\{ \begin{array}{l} \vec{J}_w = \mu_L^* \vec{J}_L + \mu_I^* \vec{J}_I - \phi_k \vec{s}_k - \frac{1}{2} (\vec{\phi} \wedge \vec{m}) + p \vec{\phi} \\ \vec{F}_s = \sum_k \vec{e}_k (\vec{s}_k \vec{n}) + \frac{1}{2} (\vec{m} \wedge \vec{n}) - \vec{n} p \end{array} \right. \quad (50) \quad (51)$	
<i>Source d'entropie</i> $S_e = -\frac{1}{T} (\mu_L^* + \mu_I^*) S_{I-L} - \frac{1}{T} (\mu_L^* + g^*) S_L^{pl} - \frac{1}{T} (\mu_I^* - g^*) S_I^{pl} \\ + \vec{J}_L \vec{X}_L + \vec{J}_I \vec{X}_I + \frac{1}{T} \left( \vec{s}_k^{dis} \frac{d \vec{\beta}_k^{an}}{dt} + \vec{m}^{dis} \frac{d \vec{\omega}^{an}}{dt} + \vec{s}_k \frac{d \vec{\beta}_k^{pl}}{dt} + \vec{m} \frac{d \vec{\omega}^{pl}}{dt} \right) \quad (52) \\ + \vec{J}_q \overline{\operatorname{grad}} \left( \frac{1}{T} \right)$	
<i>Bilan énergétique</i> $n \vec{\phi} \left( \frac{d \vec{p}}{dt} - m \vec{\phi}_I \frac{d C_I}{dt} + m \vec{\phi}_L \frac{d C_L}{dt} \right) + \vec{s}_k \frac{d \vec{\beta}_k}{dt} + \vec{m} \frac{d \vec{\omega}}{dt} - p \frac{d \tau}{dt} \\ = \rho \vec{g} \vec{\phi} - \operatorname{div} \left[ -\phi_k \vec{s}_k - \frac{1}{2} (\vec{\phi} \wedge \vec{m}) + p \vec{\phi} \right] \quad (53)$	



Poynting  
vector

# I B - Application: phenomenologies of usual fluids and solids

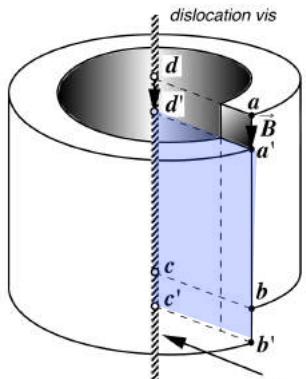


# I C – Dislocation and disclination charges

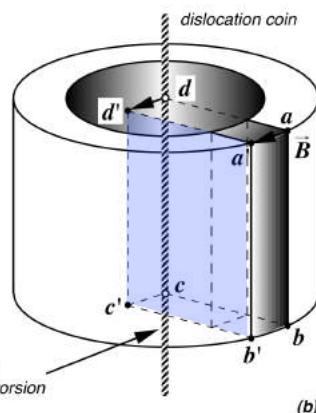
What's a line of topological singularity?

Singularity line  
by translation

Screw dislocation

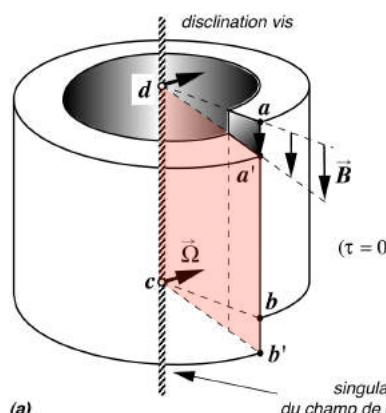


Edge dislocation

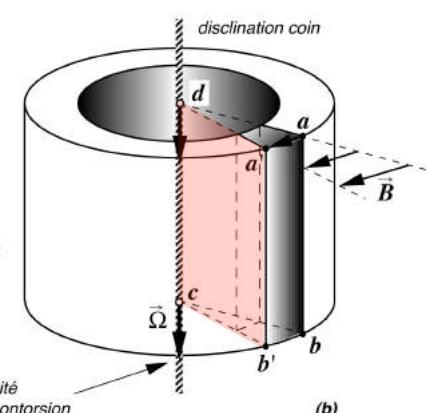


Singularity line  
by rotation

Twist disclination

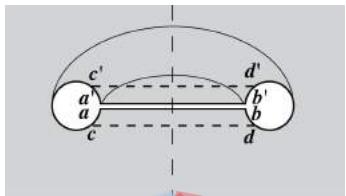


Wedge disclination

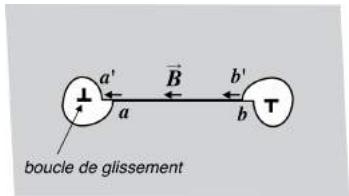


Vito Volterra  
(1860-1940)

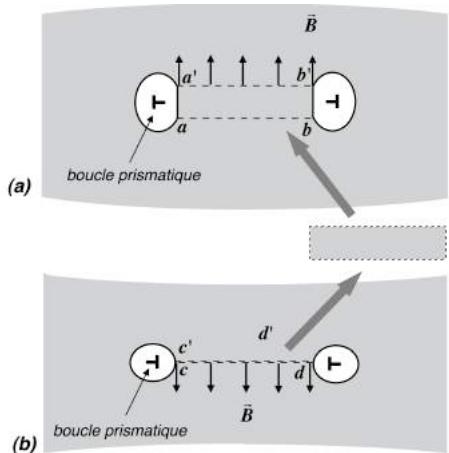
# What's a loop of topological singularity?



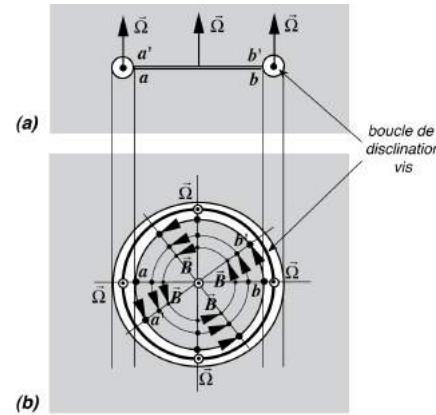
**Mixed dislocation loop  
by translation**



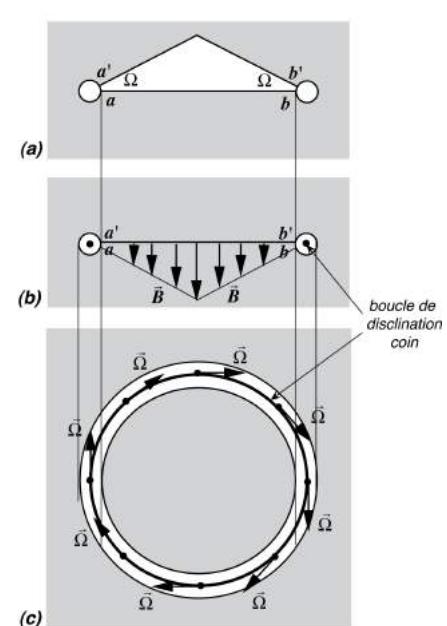
**Edge dislocation loop  
by material  
addition or subtraction**



**Twist disclination loop  
by rotation**

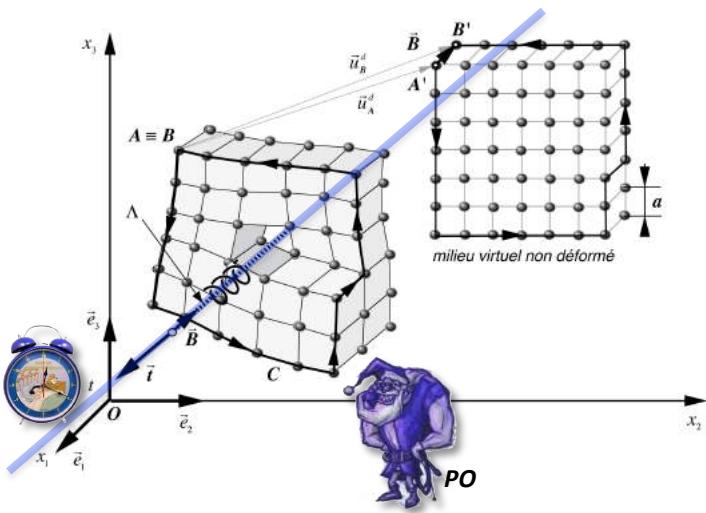


**Wedge disclination loop  
by material  
addition or subtraction**

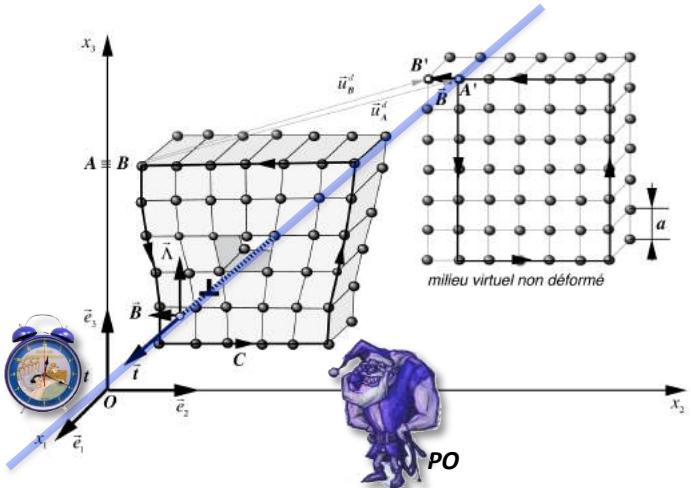


# Quantification of the topological singularities as strings or membranes in solid lattices

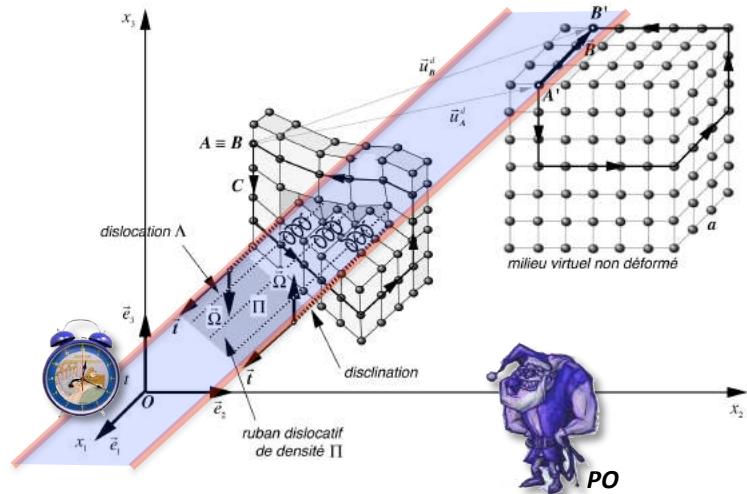
Screw dislocation string



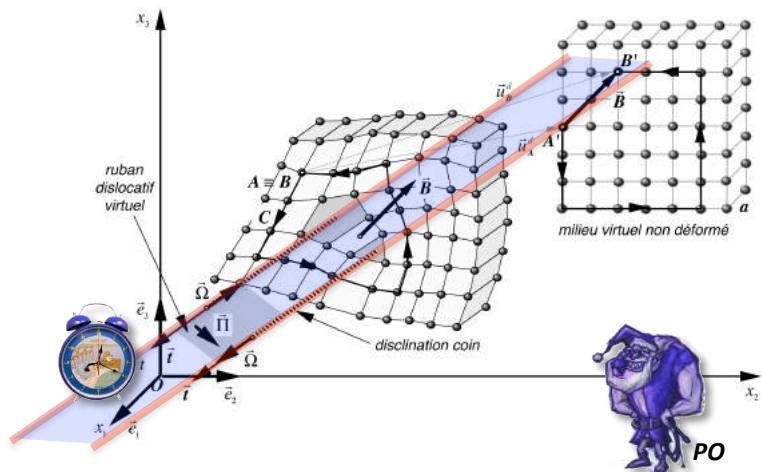
Edge dislocation string



Screw dislocation membrane limited by two twist disclination strings

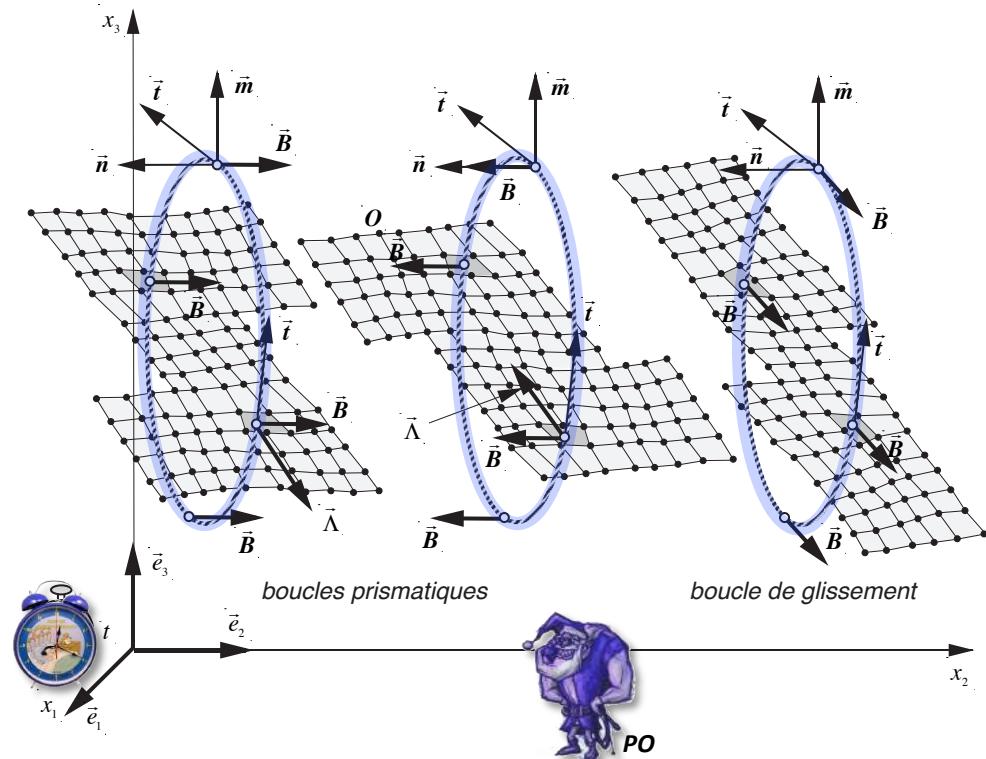


Edge dislocation membrane limited by two wedge disclination strings

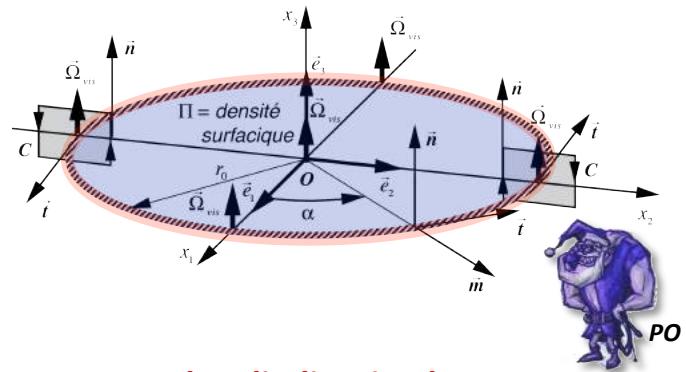


# Quantification of the topological singularities as loops and membranes in solid lattices

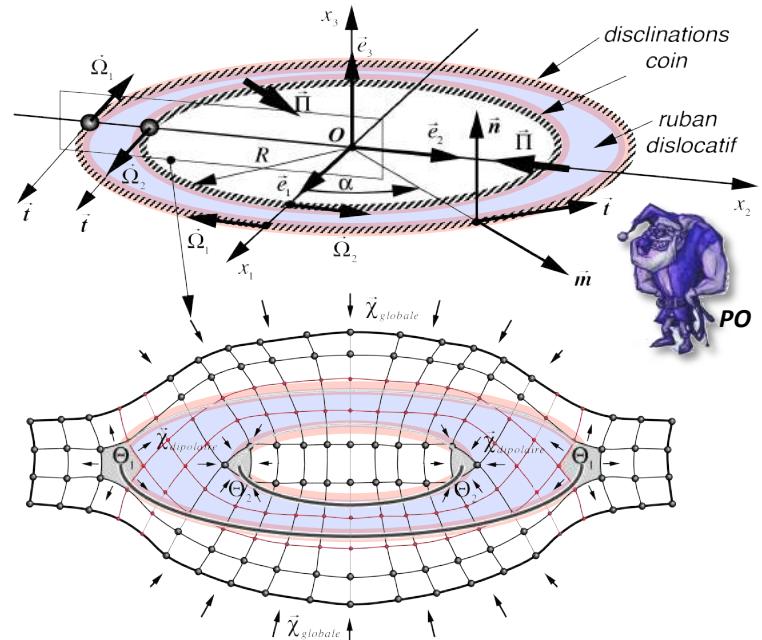
## Edge and mixed dislocation loops



## Twist disclination loop with screw dislocation membrane



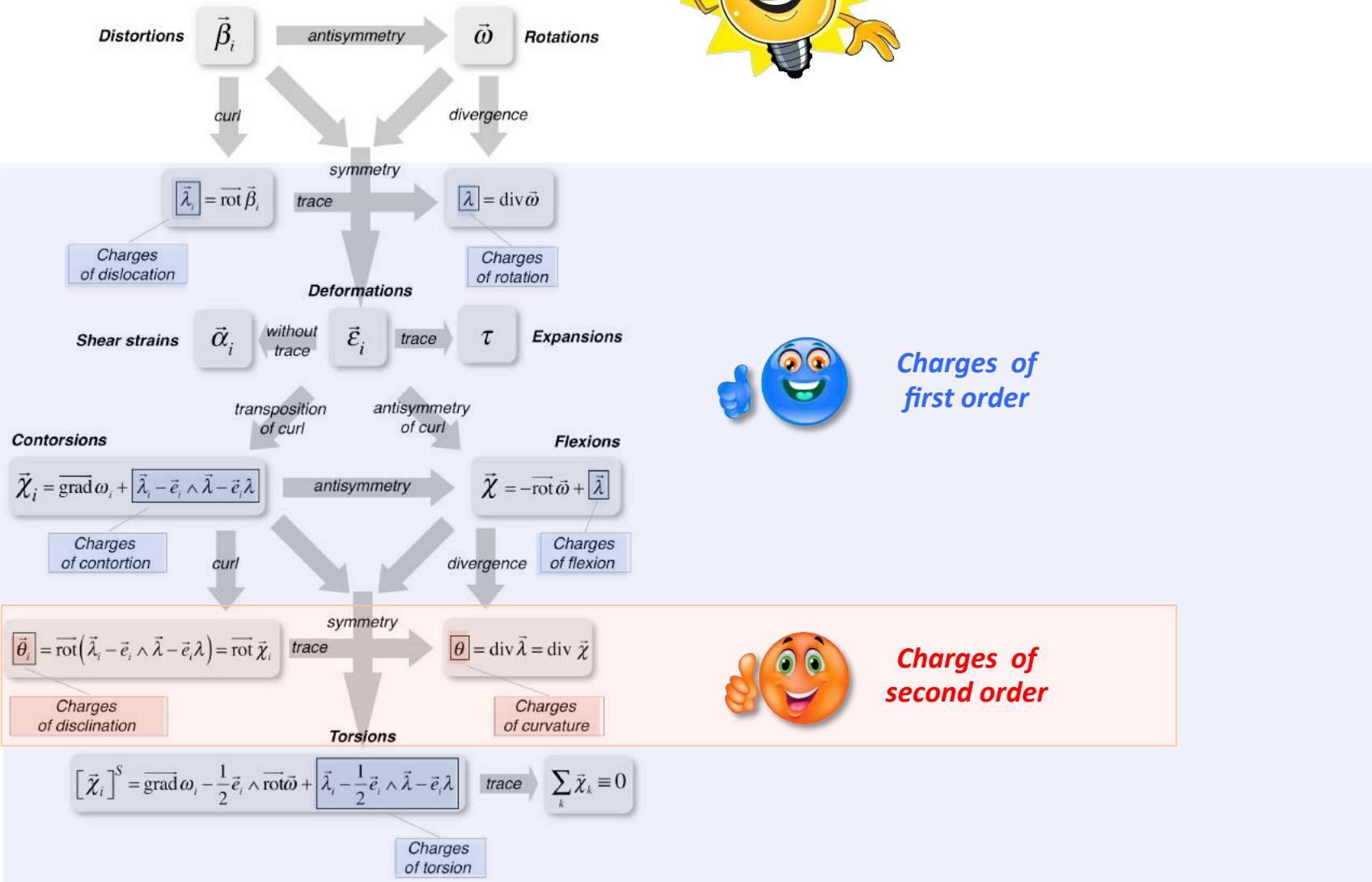
## Wedge disclination loop with edge dislocation membrane



## Incompatibility charges

associated to the topological singularities (strings, membranes and loops) of a solid lattice

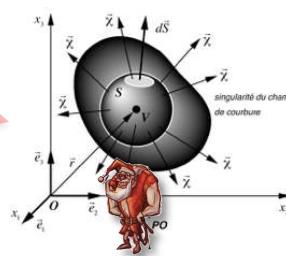
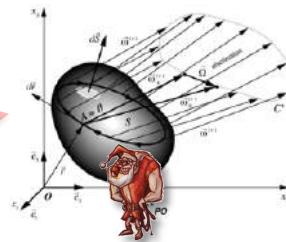
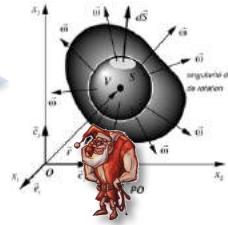
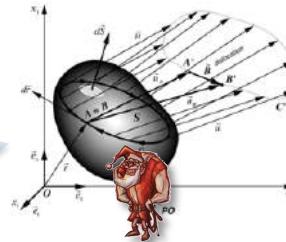
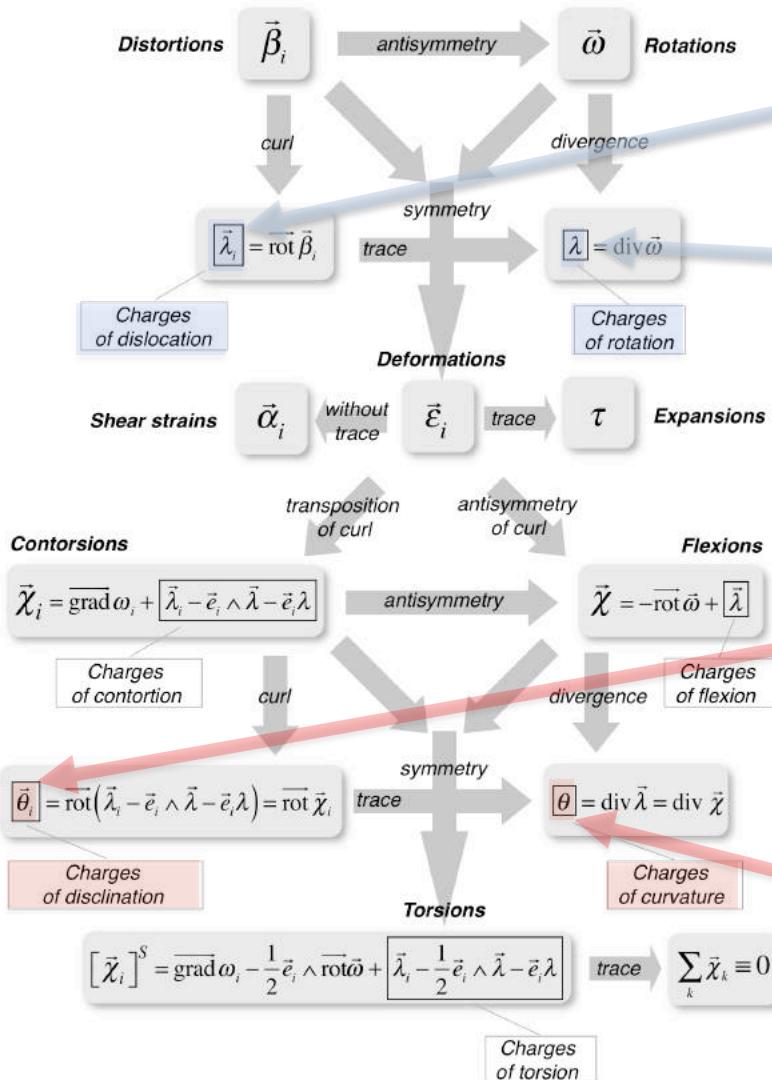
### Incompatibility equations and charge tensors



# Incompatibility charges

associated to the topological singularities (strings, membranes and loops) of a solid lattice

## Incompatibility equations and charge tensors



## Discontinuity of the displacement field

### Dislocation Burgers vector

$$\vec{B} = \vec{u}_B - \vec{u}_A = \oint_C \delta \vec{u} = - \sum_k \vec{e}_k \iint_S \text{rot } \vec{\beta}_k d\vec{S}$$

$$= - \sum_k \vec{e}_k \iint_S \vec{\lambda}_k d\vec{S} \neq 0$$

## Singularity of the divergence of the rotation field

$$Q_\lambda = \iint_S \vec{\omega} d\vec{S} = \iiint_V \text{div } \vec{\omega} dV = \iiint_V \lambda dV \neq 0$$

### Macroscopic scalar charge of rotation

## Discontinuity of the rotation field associated to the deformations

### Disclination Franck vector

$$\vec{\Omega} = \oint_C \delta \vec{\omega}^\varepsilon = \sum_k \vec{e}_k \iint_S \text{rot } \vec{\chi}_k d\vec{S} = \sum_k \vec{e}_k \iint_S \vec{\theta}_i d\vec{S}$$

$$= \sum_k \vec{e}_k \oint_C (\vec{\lambda}_k - \vec{e}_k \wedge \vec{\lambda} - \vec{e}_k \lambda) d\vec{r} \neq 0$$

## Singularity of the divergence of the flexion field

$$Q_\theta = \iint_S \vec{\chi} d\vec{S} = \iiint_V \text{div } \vec{\chi} dV = \iiint_V \theta dV \neq 0$$

### Macroscopic scalar charge of flexion

# The complete set of equations of spatio-temporal evolution of a charged lattice



## Fundamental equations

Tableau 20.2 - Équations fondamentales d'évolution des solides auto-diffusifs, élastiques et anélastiques, avec charges plastiques diélectriques	
Équations topologiques	
$J_i = -\frac{d\vec{J}_i}{dt} + \text{grad } \vec{\phi}_i$	(27)
$\vec{J} = -\frac{1}{n} \sum_i \vec{J}_i \wedge \vec{J}_{i-1} - \frac{d\vec{\omega}}{dt} - \frac{1}{2} \text{rot } \vec{\phi}$	(28)
$\vec{S}_i = \sum_j \vec{J}_j \vec{J}_{j-1} = \frac{d\vec{r}}{dt} + \text{div } \vec{\phi}$	(29)
$\vec{J}_i = \vec{J}_i^{(0)} + \vec{J}_i^{(1)} = \vec{J}_i^{(0)} + \vec{J}_i^{(2)}$	(30)
$\vec{J}_i^{(0)} = \vec{J}_i^{(0)} + \vec{J}_i^{(1)} = \vec{J}_i^{(0)} + \vec{J}_i^{(2)}$	(31)
$\vec{J}_i^{(1)} = \vec{J}_i^{(1)} + \vec{J}_i^{(2)} = \vec{J}_i^{(1)} + \vec{J}_i^{(2)}$	(32)
$d/dt = \partial/\partial t + (\vec{\phi} \cdot \vec{\nabla})$	(33)
$\vec{\phi} = \vec{\phi}_0(t) - \vec{\phi}_0(t) \wedge \vec{F}$	(34)
Équations dynamique	
$n \frac{d\vec{p}}{dt} = \vec{p} \vec{g} + \sum_i \vec{J}_i \text{div } \vec{\phi}_i - \frac{1}{2} \text{rot } \vec{m} - \text{grad } p - m \vec{\phi}_i \frac{dC_i}{dt}$	(35)
$p = 1/v = e^{-\vec{\phi}}$	(36)
$\vec{p} = m(\vec{\phi} + C_i \vec{\phi}_i - C_{i-1} \vec{\phi}_i) + \vec{\phi} + m(C_i - C_{i-1}) \vec{\phi} + \frac{m}{n}(\vec{J}_i - \vec{J}_{i-1}) = \frac{1}{n}(\rho \vec{\phi} + m(\vec{J}_i - \vec{J}_{i-1}))$	(37)
$\rho = m(1 + C_i - C_{i-1})$	(38)
Équations de diffusion	
$n \frac{dC_i}{dt} = (S_{i-1,i} + S_{i,i}) - C_i (\vec{J}_i \cdot \vec{J}_{i-1}) - \text{div } \vec{J}_i$	(39)
$n \frac{dC_i}{dt} = (S_{i-1,i} + S_{i,i}) - C_i (\vec{S}_{i-1,i} - \vec{S}_{i,i}) - \text{div } \vec{J}_i$	(40)
$\vec{J}_i = nC_i \vec{\phi}_i = nC_i (\vec{\phi}_i - \vec{\phi}) = nC_i (\vec{\phi}_i - \vec{\phi})$	(41)
$\vec{J}_i = nC_i \Delta \vec{\phi}_i = nC_i (\vec{\phi}_i - \vec{\phi}) = nC_i (\vec{\phi}_i - \vec{\phi})$	(42)

Dynamics	
$\frac{d\vec{p}}{dt} = \vec{p} \vec{g} + \sum_i \vec{J}_i \text{div } \vec{\phi}_i - \frac{1}{2} \text{rot } \vec{m} - \text{grad } p - m \vec{\phi}_i \frac{dC_i}{dt}$	(35)
$p = 1/v = e^{-\vec{\phi}}$	(36)
$\vec{p} = m(\vec{\phi} + C_i \vec{\phi}_i - C_{i-1} \vec{\phi}_i) + \vec{\phi} + m(C_i - C_{i-1}) \vec{\phi} + \frac{m}{n}(\vec{J}_i - \vec{J}_{i-1}) = \frac{1}{n}(\rho \vec{\phi} + m(\vec{J}_i - \vec{J}_{i-1}))$	(37)
$\rho = m(1 + C_i - C_{i-1})$	(38)
Selfdiffusion	
$n \frac{dC_i}{dt} = (S_{i-1,i} + S_{i,i}) - C_i (\vec{J}_i \cdot \vec{J}_{i-1}) - \text{div } \vec{J}_i$	(39)
$n \frac{dC_i}{dt} = (S_{i-1,i} + S_{i,i}) - C_i (\vec{S}_{i-1,i} - \vec{S}_{i,i}) - \text{div } \vec{J}_i$	(40)
$\vec{J}_i = nC_i \vec{\phi}_i = nC_i (\vec{\phi}_i - \vec{\phi}) = nC_i (\vec{\phi}_i - \vec{\phi})$	(41)

the topological singularities due to	
$\frac{d\vec{J}_i}{dt} = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(22)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(23)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(24)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(25)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(26)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(27)

Thermics	
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(22)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(23)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(24)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(25)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(26)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(27)
Equations thermiques	
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(22)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(23)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(24)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(25)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(26)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(27)
Equations phénoménologiques d'évolution des solides auto-diffusifs, élastiques et anélastiques, avec charges plastiques diélectriques	
Fonctions et équations d'état	
$f = f(\alpha_v^0, \alpha_v^1, \alpha_v^2, \alpha_v^3, t^0, C_i, C_j, T)$	(28)
$S_0 = \frac{n}{2} \left( \frac{\partial f}{\partial \alpha_v^0} + \frac{\partial f}{\partial \alpha_v^1} \right)$	(29)
$S_1 = \mu_i = \mu_i + \frac{1}{2} m (\vec{\phi}_i^2 - 2 \Delta \vec{\phi}_i^2)$	(30)
$\vec{X}_q = \text{grad } \frac{1}{T}$	(31)
$\vec{X}_q = \frac{1}{T} \left( -\text{grad } \mu_i^* + m \frac{d}{dt} (\vec{\phi}_i - 2 \Delta \vec{\phi}_i) - m \vec{g} \right)$	(32)
$\vec{X}_i = \frac{1}{T} \left( -\text{grad } \mu_i^* - m \frac{d}{dt} (\vec{\phi}_i + m \vec{g}) \right)$	(33)
$\vec{h} = f + T s + p v + \frac{1}{2} m \vec{v}^2 - \mu_i C_i - \mu_j C_j$	(34)
$\vec{h} = f + T s + p v + \frac{1}{2} m \vec{v}^2 - \mu_i C_i - \mu_j C_j$	(35)
Equations liées aux charges	
$\frac{d\vec{J}_i}{dt} = \vec{S}_{i-1,i} \vec{J}_i - (\vec{p} \vec{V}) \vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i - \vec{S}_{i,i} \vec{J}_i$	(36)
$\frac{d\vec{J}_i}{dt} = \vec{S}_{i-1,i} \vec{J}_i - (\vec{p} \vec{V}) \vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \text{rot } (\vec{V} \wedge \vec{J}_i) - \nabla \text{div } \vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i - 2 \text{rot } \vec{J}_{i-1} - \vec{p} \vec{g}$	(37)
$\frac{d\vec{J}_i}{dt} = \vec{S}_{i-1,i} \vec{J}_i - (\vec{p} \vec{V}) \vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i - \text{div } (\lambda \vec{V}) = \vec{S}_{i-1,i} \vec{J}_i$	(38)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(39)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(40)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(41)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(42)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(43)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(44)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(45)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(46)
Equations de dissipation: flux de charge plastiques diélectriques	
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(47)
$\vec{J} = -\frac{1}{n} \sum_i \vec{J}_i \wedge \vec{J}_i = \vec{\lambda} \vec{V} + \frac{1}{2} (\vec{\lambda} \wedge \vec{V}) = \vec{J} (\vec{m}, \vec{\lambda}, v, T, \dots)$	(48)
$\frac{S_i}{n} = \sum_i \vec{J}_i \vec{J}_i = -\vec{\lambda} \vec{V} = \frac{1}{n} (S_i^0 - S_i^0)$	(49)
$S_i^0 = S_i^0 \left[ (\mu_i^0 + g^*) p, \vec{\lambda}_i, v, T, C_i, C_j, \dots \right]$	(50)
$S_i^0 = S_i^0 \left[ (\mu_i^0 - g^*) p, \vec{\lambda}_i, v, T, C_i, C_j, \dots \right]$	(51)
$g^* = f + p v + n \vec{v} \cdot \vec{J}_i - \mu_i C_i$	(52)
State equations	
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(53)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(54)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(55)
$S_i^0 = S_i^0 \left[ (\mu_i^0 + g^*) p, \vec{\lambda}_i, v, T, C_i, C_j, \dots \right]$	(56)
$S_i^0 = S_i^0 \left[ (\mu_i^0 - g^*) p, \vec{\lambda}_i, v, T, C_i, C_j, \dots \right]$	(57)
$g^* = f + p v + n \vec{v} \cdot \vec{J}_i - \mu_i C_i$	(58)
Equations additionnelles d'évolution	
$\text{Continuité de la masse}$	
$\frac{\partial \vec{m}}{\partial t} = -\text{div} [\rho \vec{g} + m (\vec{J}_i - \vec{J}_{i-1})] = -\text{div} (\rho \vec{p}) \quad \text{dans } Q_m^0 \subset \Sigma$	(62)
$\text{Flux de travail et force de surface}$	
$\vec{J}_i = \mu_i \vec{J}_i + \mu_j \vec{J}_j - \theta_i \vec{s}_i - \frac{1}{2} (\vec{\phi} \wedge \vec{m}) + p \vec{\phi}$	(63)
$\vec{J}_i = \sum_i \vec{J}_i (\vec{s}_i \cdot \vec{J}_i) + \frac{1}{2} (\vec{m} \cdot \vec{J}_i) - \vec{m} \vec{p}$	(64)
$\text{Source d'entrée}$	
$S_i = -\frac{1}{T} (\mu_i^* + \mu_j^*) S_{i-1,i} - \frac{1}{T} (\mu_i^* - g^*) S_i^0 + \vec{J}_i \vec{R}_i$	(65)
$+ \vec{J}_i \vec{J}_i + \frac{1}{T} \left( \vec{s}_i \vec{m} - \vec{m} \vec{s}_i + \frac{d \vec{m}}{dt} + \vec{s}_i \vec{J}_i + \vec{J}_i \vec{m} \right) + \vec{J}_i \text{grad} \left( \frac{1}{T} \right)$	(66)
$\text{Bilan énergétique}$	
$\vec{s}_i = \vec{s}_i^{\text{ext}} (\vec{\alpha}_{i-1}^0, v, T, \dots) + \vec{s}_i^{\text{int}} (\vec{\alpha}_i^0, v, T, \dots)$	(67)
$\vec{m} = \vec{m}^{\text{ext}} (\vec{\alpha}_{i-1}^0, v, T, \dots) + \vec{m}^{\text{int}} (\frac{d \vec{m}}{dt}, v, T, \dots)$	(68)
$\vec{p} = \vec{p}^{\text{ext}} (\vec{\alpha}_i^0, v, T, \dots) + \vec{p}^{\text{int}} (\vec{\alpha}_i^0, v, T, \dots)$	(69)

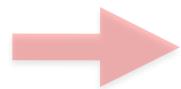
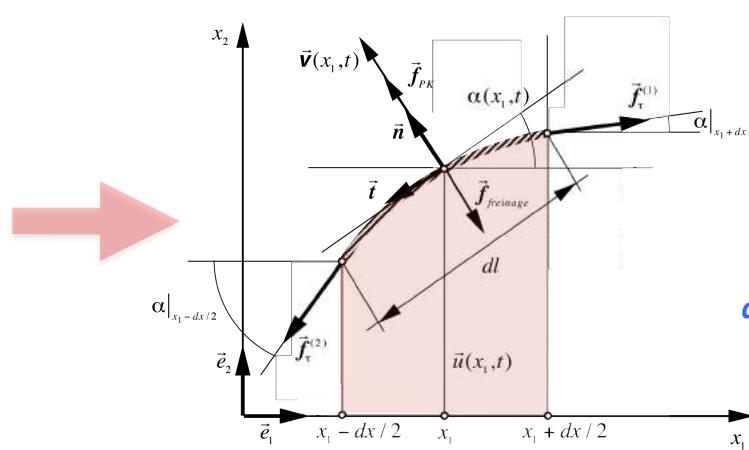
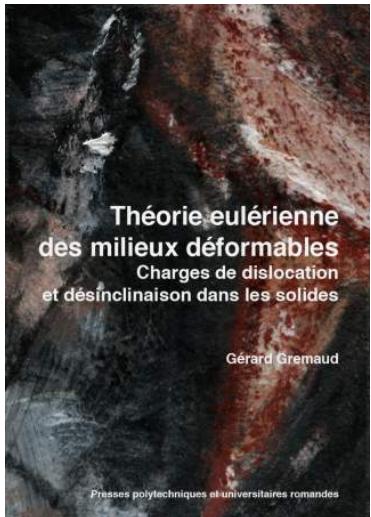
## Phenomenological equations

Additional equations	
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(60)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(61)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(62)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(63)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(64)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(65)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(66)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(67)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(68)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(69)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(70)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(71)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(72)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(73)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(74)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(75)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(76)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(77)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(78)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(79)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(80)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(81)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(82)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(83)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(84)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(85)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(86)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(87)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(88)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(89)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(90)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(91)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(92)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(93)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(94)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(95)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(96)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(97)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(98)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(99)
$\vec{J}_i = \vec{S}_{i-1,i} \vec{J}_i + \vec{S}_{i,i} \vec{J}_{i-1} - \text{div } \vec{J}_i$	(100)

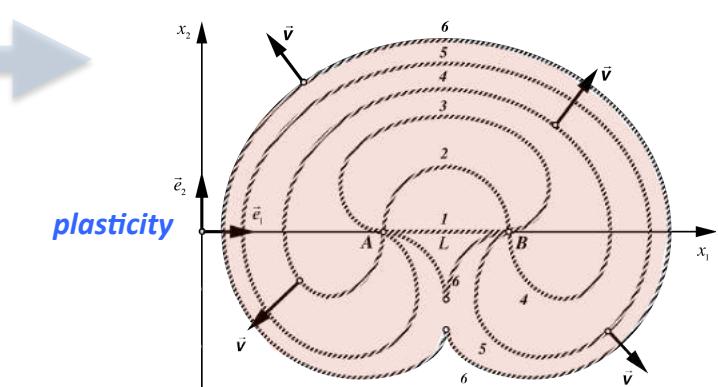
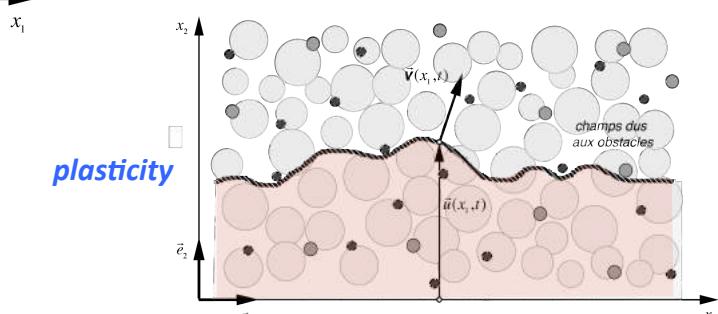
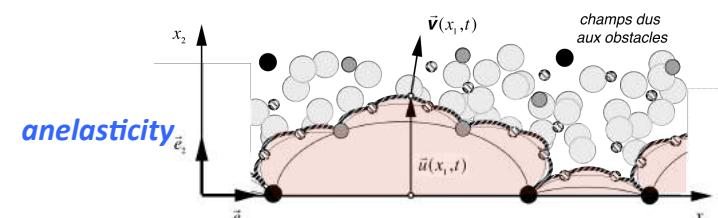
## Additional equations

# 1 D - Application: elements of dislocation theory in usual solids

## String model of a dislocation line



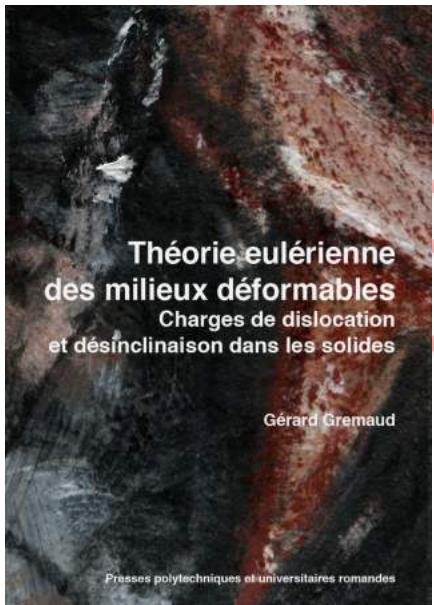
$$\left( M_0 \frac{\partial^2 u}{\partial t^2} + B_f \frac{\partial u}{\partial t} \right) \sqrt{1 + (\partial u / \partial x_1)^2} - \frac{\partial}{\partial x_1} \left[ \tau \frac{\partial u}{\partial x_1} / \sqrt{1 + (\partial u / \partial x_1)^2} \right] = B s_{23} + \sum_{n=1}^N f_n(x_1, u(x_1, t)) + F_{\text{fluctuation}}(x_1, u(x_1, t), t)$$



plasticity



## Other consequences



*Relativistic dynamics  
of the charges*

*Interactions  
of electrical type  
and  
of gravitational type  
between charges*

*String model  
of the dislocation line*

+

*Absence of particles  
analogue to magnetic monopoles*

*Possible solution of the famous paradox  
of the electron field energy*

*Existence of a small asymmetry  
between curvature charges of vacancy or interstitial type*

*Maxwell equations  
and  
Lorentz force  
at constant volumic expansion*

$$\begin{cases} -\frac{d(2\vec{\omega})}{dt} + \text{rot } \vec{\phi} = (2\vec{J}), \\ \text{div}(2\vec{\omega}) = (2\lambda), \end{cases}$$

$$\Leftrightarrow \begin{cases} -\frac{\partial \vec{D}}{\partial t} + \text{rot } \vec{H} = \vec{j} \\ \text{div } \vec{D} = \rho \end{cases}$$

$$\begin{cases} \frac{d(n\vec{p})}{dt} = -\text{rot } \frac{\vec{m}}{2}, \\ \text{div}(n\vec{p}) = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} \frac{\partial \vec{B}}{\partial t} = -\text{rot } \vec{E} \\ \text{div } \vec{B} = 0 \end{cases}$$

$$\begin{cases} (2\vec{\omega}) = \left(\frac{1}{nk_2}\right) \frac{\vec{m}}{2} + (2\vec{\omega}^{an}) + (2\vec{\omega}_0(t)), \\ (n\vec{p}) = nm \left[ \vec{\phi} + (C_I - C_L) \vec{\phi} + \left(\frac{1}{n} (\vec{J}_I - \vec{J}_L)\right) \right] \end{cases}$$

$$\Leftrightarrow \begin{cases} \vec{D} = \epsilon_0 \vec{E} + \vec{P} + \vec{P}_0(t) \\ \vec{B} = \mu_0 [\vec{H} + (\chi^{para} + \chi^{dia}) \vec{H} + \vec{M}] \end{cases}$$

$$\begin{cases} \frac{d(2\lambda)}{dt} = -\text{div}(2\vec{J}), \end{cases}$$

$$\Leftrightarrow \begin{cases} \frac{\partial \rho}{\partial t} = -\text{div } \vec{j} \end{cases}$$

$$\begin{cases} -\frac{\vec{m}}{2} (2\vec{J}) = \\ \vec{\phi} \frac{d(n\vec{p})}{dt} + \left(\frac{\vec{m}}{2}\right) \frac{d(2\vec{\omega})}{dt} - \text{div} \left( \vec{\phi} \wedge \left(\frac{\vec{m}}{2}\right) \right) \end{cases}$$

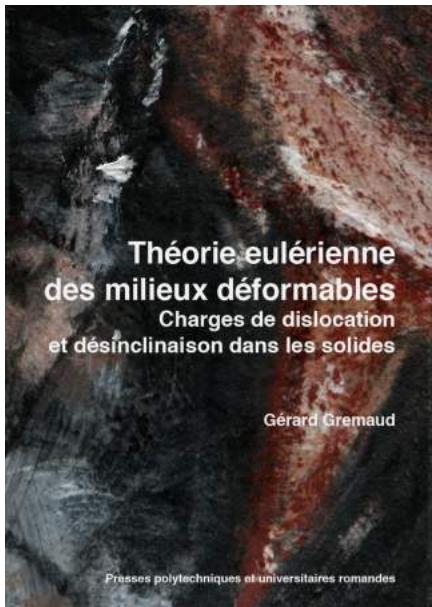
$$\Leftrightarrow \begin{cases} -\vec{E} \vec{j} = \\ \vec{H} \frac{\partial \vec{B}}{\partial t} + \vec{E} \frac{\partial \vec{D}}{\partial t} - \text{div}(\vec{H} \wedge \vec{E}) \end{cases}$$

$$\begin{cases} c_r = \sqrt{\frac{nk_2}{nm}} = \sqrt{\frac{k_2}{m}} \end{cases}$$

$$\Leftrightarrow \begin{cases} c = \sqrt{\frac{1}{\epsilon_0 \mu_0}} \end{cases}$$

$$\begin{cases} \vec{F}_{PK} = 2Q_\lambda \left( \frac{\vec{m}}{2} + \vec{v} \wedge n\vec{p} \right) \end{cases} \Leftrightarrow \begin{cases} \vec{F} = q(\vec{E} + \vec{v} \wedge \vec{B}) \end{cases}$$

# *Conclusion of the first part*



*Relativistic dynamics  
of the charges*

*Maxwell equations  
and  
Lorentz force  
at constant volumic expansion*

*Interactions  
of electrical type  
and  
of gravitational type  
between charges*

*String model  
of the dislocation line*

*The numerous analogies which appear between the eulerian theory of deformable media and the theories of electromagnetism, gravitation, special relativity, general relativity and even standard model of elementary particles, reinforced by the absence of particles analogue to magnetic monopoles, by a possible solution of the famous paradox of electron field energy and by the existence of a small asymmetry between curvature charges of vacancy or interstitial type, are sufficiently surprising and remarkable to alert any open and curious scientific spirit!*

*But it is also clear that these analogies are, by far, not perfect. It is then tantalizing to analyze much more carefully these analogies and to try to find how to perfect them.*



# **Part II – Could the universe be a 3D-lattice?**

***II A - The « cosmic lattice »***

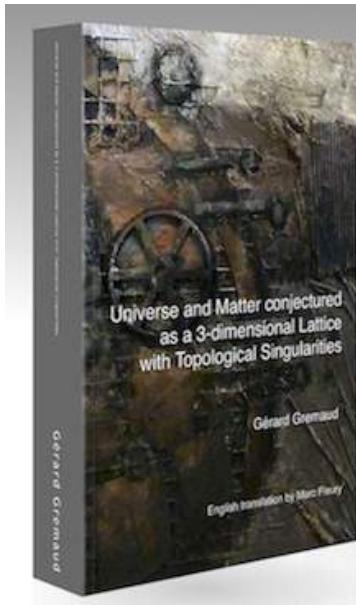
***II B - Maxwell equations and special relativity***

***II C - Gravitation and cosmology***

***II D - Quantum physics and standard model of particles***

***II E - Some other hypothetical consequences of the cosmic lattice***

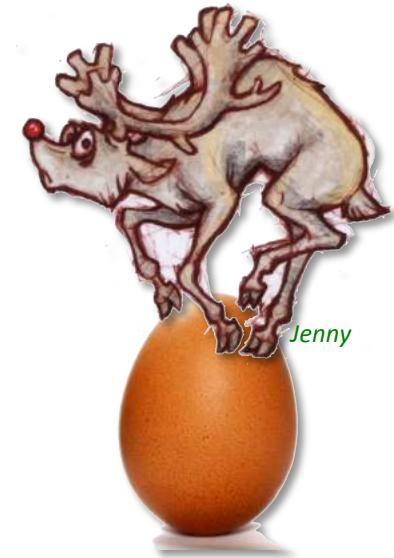
***Conclusion of the second part***



Amazon Press,  
Charleston (USA),  
2016, 650 pages  
(ISBN 978-2-8399-1934-0)



Amazon Press,  
Charleston (USA),  
2016, 664 pages  
(ISBN 978-2-8399-1940-1)



<http://gerardgremaud.ch>

## II A - The « cosmic lattice »

### Newton equation of usual isotropic solids

Elastic state function given per lattice site

$$f^{def} = -k_0\tau + k_1\tau^2 + k_2 \sum_i (\vec{\alpha}_i^{el})^2$$



Newton equation

$$\frac{d\vec{p}}{dt} = -2k_2 \vec{\text{rot}} \vec{\omega}^{el} - 2k_2 \sum_k (\vec{e}_k \vec{\text{grad}} \tau) \vec{\alpha}_k^{el} + \vec{\text{grad}} \left[ \left( \frac{4}{3}k_2 + 2k_1(1-\tau) + k_0 \right) \tau \right] + 2k_2 \vec{\lambda}$$

### Newton equation of a very special isotropic lattice: the « cosmic lattice »



Conjecture: elastic state function given per unit volume of lattice  
and depending also on the elastic rotation

$$F^{def} = -K_0\tau + K_1\tau^2 + K_2 \sum_i (\vec{\alpha}_i^{el})^2 + 2K_3(\vec{\omega}^{el})^2$$



Newton equation



Analogy with general relativity:  
expansion depends on  
the energy stored in the lattice

$$n \frac{d\vec{p}}{dt} = -2(K_2 + K_3) \vec{\text{rot}} \vec{\omega}^{el} + \left( \frac{4}{3}K_2 + 2K_1 \right) \vec{\text{grad}} \tau + \vec{\text{grad}} \underbrace{\left( K_2 \sum_i (\vec{\alpha}_i^{el})^2 + 2K_3(\vec{\omega}^{el})^2 + K_1\tau^2 - K_0\tau \right)}_{F^{def}} + 2K_2 \vec{\lambda}$$

## Circularely polarized transversal waves and longitudinal « local fluctuations »

Newton equation of the cosmic lattice

$$n \frac{d\vec{p}}{dt} = -2(K_2 + K_3) \vec{\text{rot}} \vec{\omega}^{\text{el}} + \left( \frac{4}{3} K_2 + 2K_1 \right) \vec{\text{grad}} \tau + \vec{\text{grad}} \underbrace{\left( K_2 \sum_i (\vec{\alpha}_i^{\text{el}})^2 + 2K_3 (\vec{\omega}^{\text{el}})^2 + K_1 \tau^2 - K_0 \tau \right)}_{F^{\text{def}}} + 2K_2 \vec{\lambda}$$

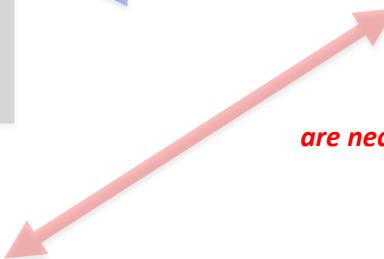


Analogy with  
the circular polarization  
of the photons in quantum physics

Purely transversal waves are necessarily  
circularely polarized

$$c_t = \frac{\omega}{k_t} \cong \sqrt{\frac{K_2 + K_3}{mn}} = e^{\tau_0/2} \sqrt{\frac{K_2 + K_3}{mn_0}}$$

( linearly polarized transversal waves  
are necessarily coupled with longitudinal wavelets )



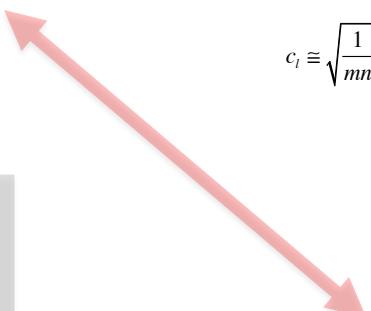
Conjectures:

$$\begin{cases} K_2 + K_3 > 0 \\ \tau_0 < \tau_{0cr} = \frac{K_0}{2K_1} - \frac{2K_2}{3K_1} - 1 \end{cases}$$

$$\text{if } \tau_0 > \tau_{0cr} = \frac{K_0}{2K_1} - \frac{2K_2}{3K_1} - 1$$

Pure longitudinal waves can exist

$$c_l \cong \sqrt{\frac{1}{mn} \left[ \frac{4}{3} K_2 + 2K_1 (1 + \tau_0) - K_0 \right]} = e^{\tau_0/2} \sqrt{\frac{1}{mn_0} \left[ \frac{4}{3} K_2 + 2K_1 (1 + \tau_0) - K_0 \right]}$$



1/ Analogy with the absence  
of longitudinal waves  
in general relativity

2/ Analogy with the vacuum fluctuations  
in quantum physics

$$\text{if } \tau_0 < \tau_{0cr} = \frac{K_0}{2K_1} - \frac{2K_2}{3K_1} - 1$$

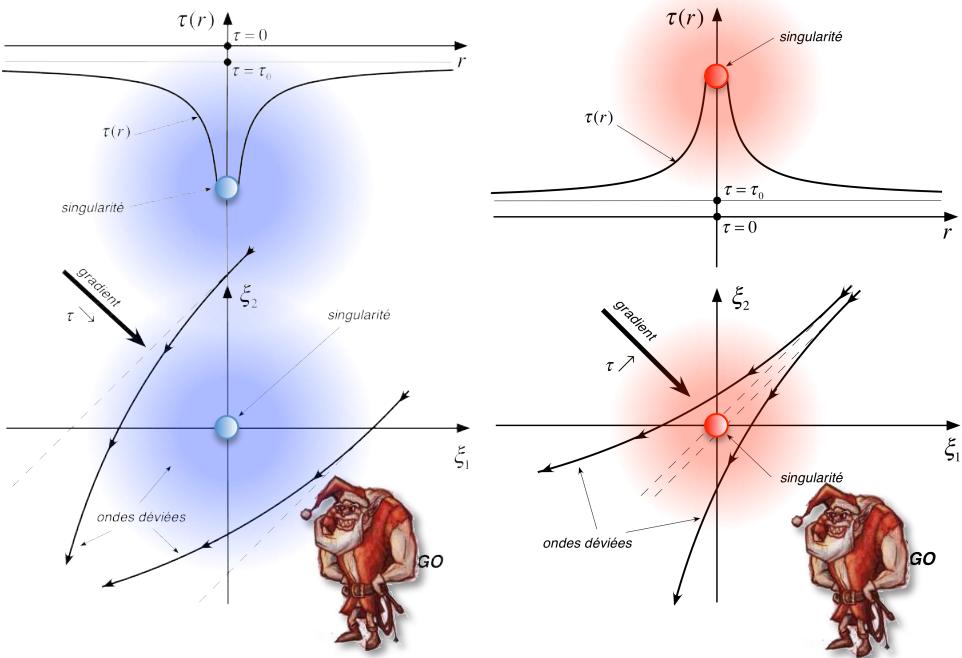
Only longitudinal « local fluctuations »  
of the expansion can exist



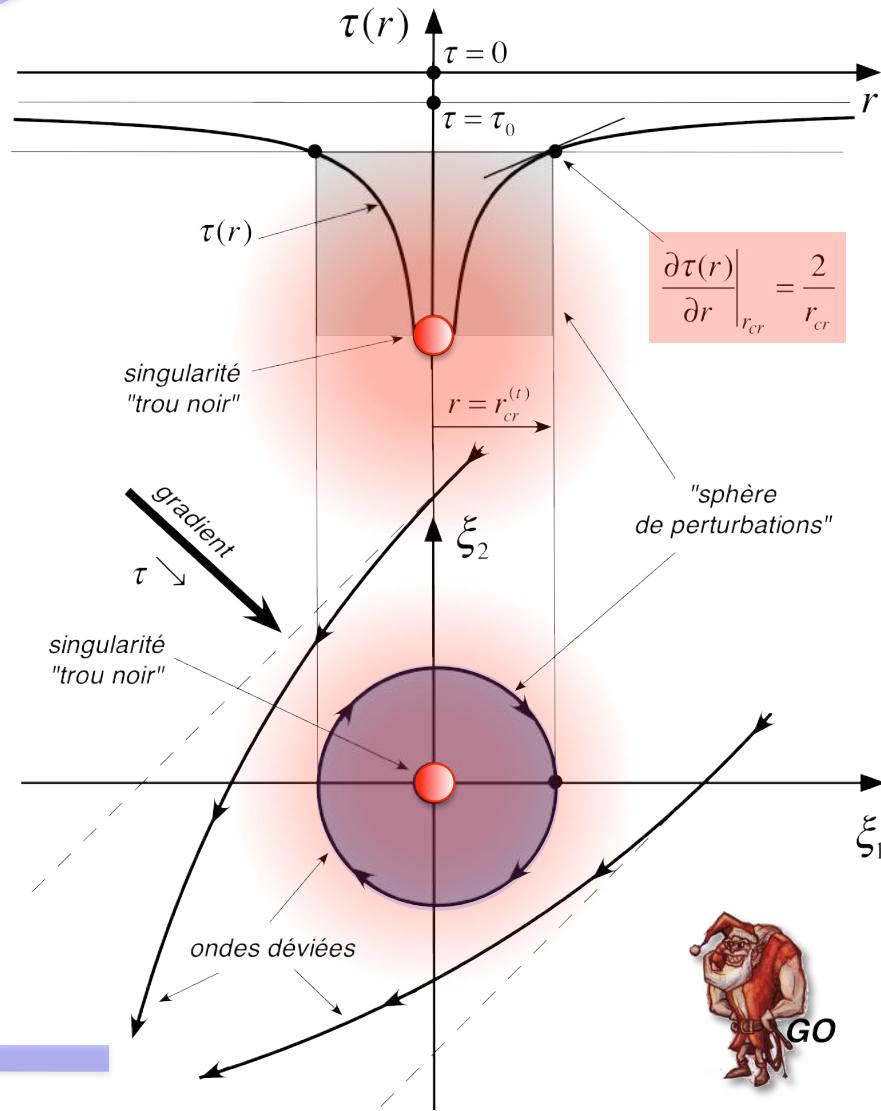
## Curvature of the wave rays and « perturbation sphere »

**Curvature of the wave rays  
in the presence of an expansion singularity**

$$c_r = \frac{\omega}{k_r} \equiv \sqrt{\frac{K_2 + K_3}{mn}} = e^{\tau_0/2} \sqrt{\frac{K_2 + K_3}{mn_0}}$$



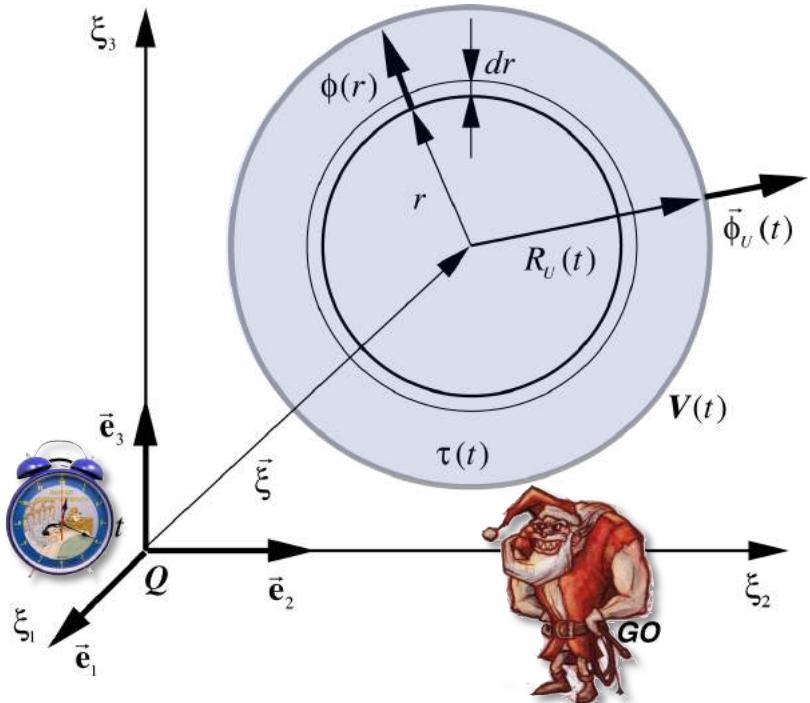
**Appearance of a « perturbation sphere »**



Analogy with the « photon sphere »  
of a black hole in general relativity

# Cosmological behaviours of a finite cosmic lattice

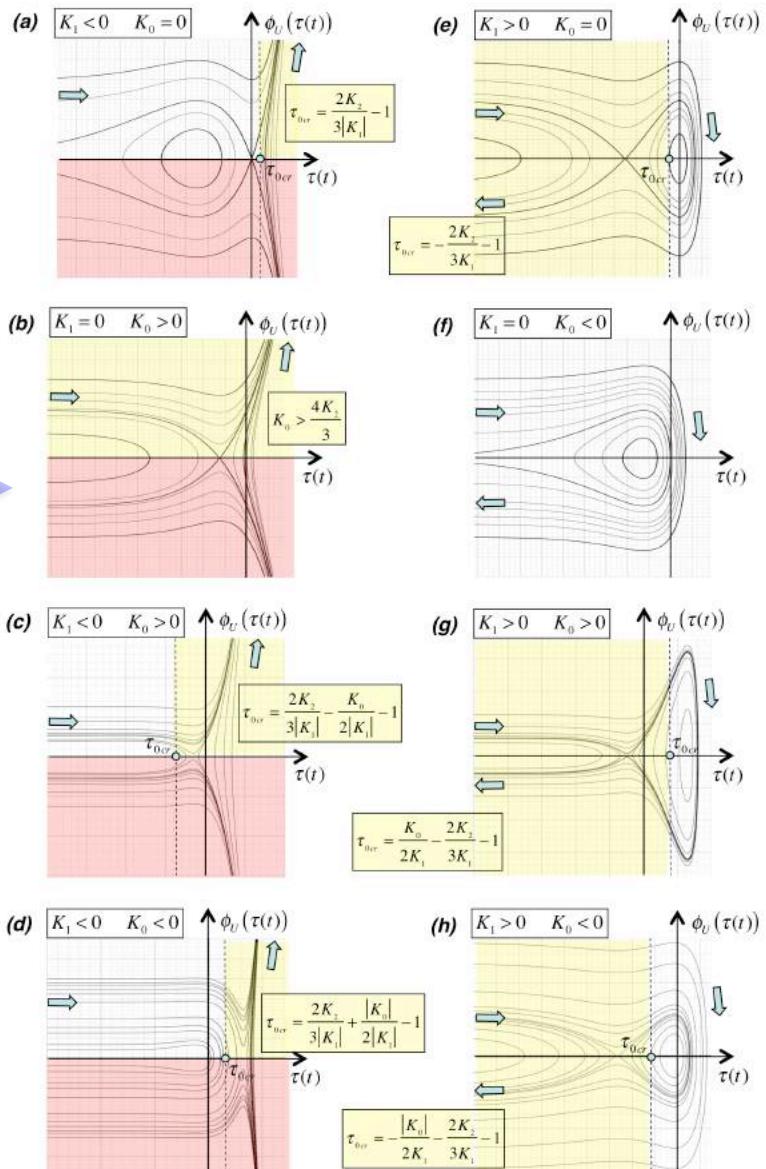
**Cosmological expansion  
of a spheric lattice with a given total energy**



$$\phi_U(\tau) = \sqrt{\frac{10}{3Nm} T(\tau)} = \sqrt{\frac{10}{3Nm} (E - F(\tau))}$$

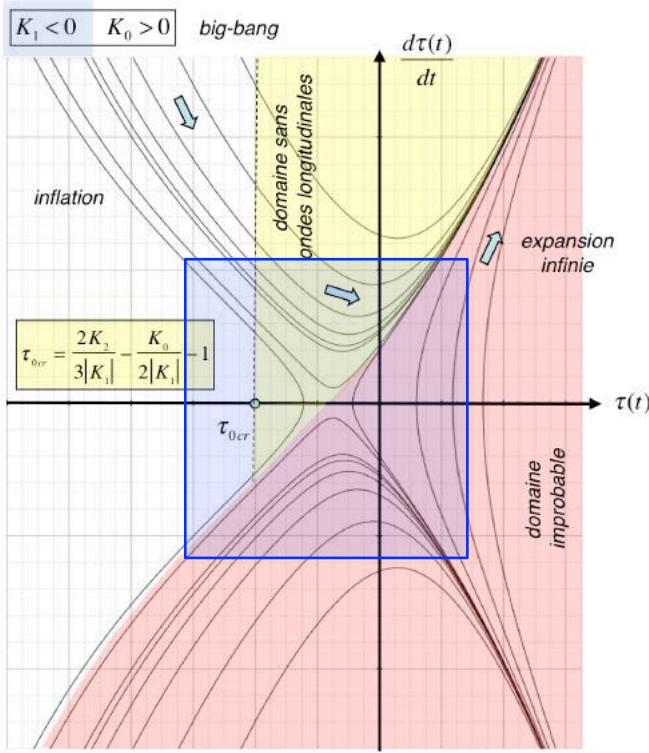
$$F = \frac{N}{n_0} (K_1 \tau - K_0) \tau e^\tau$$

**8 possible cosmological models**

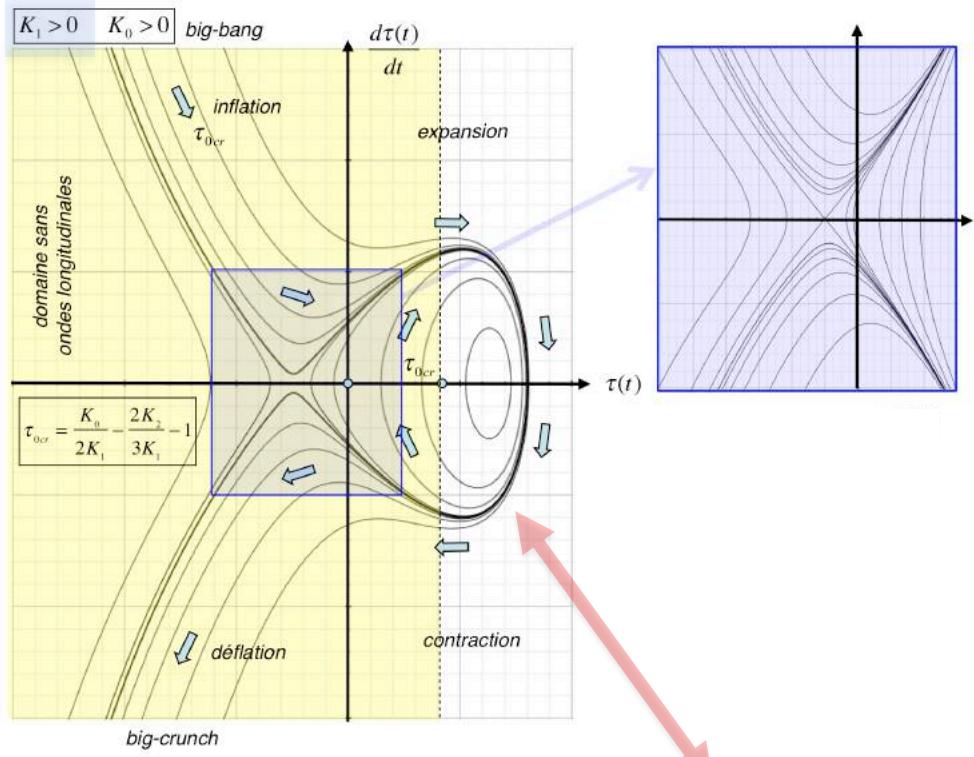


# Two types of pleasant cosmological models!

## Model without «big-crunch»



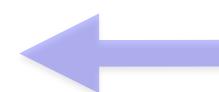
## Model with «big-crunch»



1/ Analogy with the cosmological expansion of the universe:  
«big-bang», inflation, then slowing down  
followed by an acceleration of the expansion

2/ Possible model with «big-crunch» and «big-bounce»

3/ Origin of the «dark energy»:  $F = \frac{N}{n_0}(K_1\tau - K_0)\tau e^\tau$



**Conjecture:**  $K_1 > 0$  ;  $K_0 > 0$

# II B - Maxwell equations and special relativity

## Maxwell equations

*Equations of the cosmic lattice  
(at constant expansion)*

$$\left\{ \begin{array}{l} -\frac{\partial(2\vec{\omega}^{el})}{\partial t} + \text{rot } \vec{\phi}^{rot} \equiv (2\vec{J}) \\ \text{div}(2\vec{\omega}^{el}) = (2\lambda) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial(n\vec{p}^{rot})}{\partial t} \equiv -\text{rot}\left(\frac{\vec{m}}{2}\right) + 2K_2\vec{\lambda}^{rot} \\ \text{div}(n\vec{p}^{rot}) = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} (2\vec{\omega}^{el}) = \frac{1}{(K_2 + K_3)}\left(\frac{\vec{m}}{2}\right) + (2\vec{\omega}^{an}) + (2\vec{\omega}_0(t)) \\ (n\vec{p}^{rot}) = (nm)\left[\vec{\phi}^{rot} + (C_I - C_L)\vec{\phi}^{rot} + \left(\frac{1}{n}(\vec{J}_I^{rot} - \vec{J}_L^{rot})\right)\right] \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial(2\lambda)}{\partial t} \equiv -\text{div}(2\vec{J}) \end{array} \right.$$

$$\left\{ \begin{array}{l} -\left(\frac{\vec{m}}{2}\right)(2\vec{J}) \equiv \\ \vec{\phi}^{rot} \frac{\partial(n\vec{p}^{rot})}{\partial t} + \left(\frac{\vec{m}}{2}\right) \frac{\partial(2\vec{\omega}^{el})}{\partial t} - \text{div}\left(\vec{\phi}^{rot} \wedge \left(\frac{\vec{m}}{2}\right)\right) \end{array} \right.$$

$$\left\{ \begin{array}{l} c_t = \sqrt{\frac{K_2 + K_3}{mn}} \end{array} \right.$$

$$\left\{ \vec{F}_{PK} = 2Q_\lambda \left( \frac{\vec{m}}{2} + \vec{v} \wedge n\vec{p} \right) \right.$$

*Maxwell equations  
of electromagnetism*

$$\left\{ \begin{array}{l} -\frac{\partial \vec{D}}{\partial t} + \text{rot } \vec{H} = \vec{j} \\ \text{div } \vec{D} = \rho \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial \vec{B}}{\partial t} = -\text{rot } \vec{E} \\ \text{div } \vec{B} = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} \vec{D} = \epsilon_0 \vec{E} + \vec{P} + \vec{P}_0(t) \\ \vec{B} = \mu_0 \left[ \vec{H} + (\chi^{para} + \chi^{dia}) \vec{H} + \vec{M} \right] \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial t} = -\text{div } \vec{j} \end{array} \right.$$

$$\left\{ \begin{array}{l} -\vec{E} \vec{j} = \\ \vec{H} \frac{\partial \vec{B}}{\partial t} + \vec{E} \frac{\partial \vec{D}}{\partial t} - \text{div}(\vec{H} \wedge \vec{E}) \end{array} \right.$$

$$\left\{ \begin{array}{l} c = \sqrt{\frac{1}{\epsilon_0 \mu_0}} \end{array} \right.$$

$$\left\{ \vec{F} = q(\vec{E} + \vec{v} \wedge \vec{B}) \right.$$



James Clerk Maxwell  
(1831-1879)



$$\begin{aligned} \vec{D} &\Leftrightarrow \vec{\omega} \\ \vec{E} &\Leftrightarrow \vec{m} \\ \vec{B} &\Leftrightarrow n\vec{p} \\ \vec{H} &\Leftrightarrow \vec{\phi} \\ \vec{P} &\Leftrightarrow \vec{\omega}^{an} \\ \rho &\Leftrightarrow \lambda \\ \vec{j} &\Leftrightarrow \vec{J} \end{aligned}$$

$$\begin{aligned} \vec{M} &\Leftrightarrow \frac{1}{n}(\vec{J}_I - \vec{J}_L) \\ (\chi^{para} + \chi^{dia})\vec{H} &\Leftrightarrow (C_I - C_L)\vec{\phi} \end{aligned}$$

$$\epsilon_0 \Leftrightarrow \frac{1}{K_2}$$

$$\mu_0 \Leftrightarrow nm$$

$$c = \sqrt{\frac{1}{\epsilon_0 \mu_0}} \Leftrightarrow c_t = \sqrt{\frac{K_2}{mn}}$$



1/ Complete analogy  
with the Maxwell equations  
of electromagnetism  
(with dielectric polarisation,  
para- and dia-magnetism,  
magnetisation,  
electrical charges and currents,  
Lorentz forces)

2/ Magnetic monopoles cannot exist!

# Separability of the Newton equation in the presence of topological singularities

## Newton equation of the cosmic lattice

$$n \frac{d\vec{p}}{dt} = -2(K_2 + K_3) \vec{\text{rot}} \vec{\omega}^{\text{el}} + \left( \frac{4}{3}K_2 + 2K_1 \right) \vec{\text{grad}} \tau + \vec{\text{grad}} \underbrace{\left( K_2 \sum_i (\vec{\alpha}_i^{\text{el}})^2 + 2K_3 (\vec{\omega}^{\text{el}})^2 + K_1 \tau^2 - K_0 \tau \right)}_{F^{\text{def}}} + 2K_2 \vec{\lambda}$$

**First partial Newton equation  
for the elastic distortions  
associated with the topological singularities**

**Second partial Newton equation  
for the perturbations of the expansion  
associated with the topological singularities**

$$nm \frac{d\vec{\phi}^{\text{ch}}}{dt} = -2(K_2 + K_3) \vec{\text{rot}}(\vec{\omega}^{\text{ch}}) + (4K_2/3 + 2K_1(1+\tau_0) - K_0) \vec{\text{grad}} \tau^{\text{ch}} + 2K_2 \vec{\lambda}^{\text{ch}}$$

$$nm \frac{d\vec{\phi}^{(p)}}{dt} = \vec{\text{grad}} \left[ \begin{array}{l} \left( 4K_2/3 + 2K_1(1+\tau_0 + \tau^{\text{ext}} + \tau^{\text{ch}}) - K_0 \right) \tau^{(p)} + K_1 (\tau^{(p)})^2 \\ + \left( K_2 \sum_i (\vec{\alpha}_i^{\text{ch}})^2 + 2K_3 (\vec{\omega}^{\text{ch}})^2 + K_1 (\tau^{\text{ch}})^2 \right) \\ + \left( 2K_2 \sum_i \vec{\alpha}_i^{\text{ext}} \vec{\alpha}_i^{\text{ch}} + 4K_3 \vec{\omega}^{\text{ext}} \vec{\omega}^{\text{ch}} + 2K_1 \tau^{\text{ext}} \tau^{\text{ch}} \right) \end{array} \right]$$

**Static case:**

$$\begin{aligned} \Delta(\tau_{\text{statique}}^{\text{ch}}) &= -\frac{2K_2}{4K_2/3 + 2K_1(1+\tau_0) - K_0} \text{div} \vec{\lambda}^{\text{ch}} \\ &= -\frac{2K_2}{4K_2/3 + 2K_1(1+\tau_0) - K_0} \theta^{\text{ch}} \end{aligned}$$

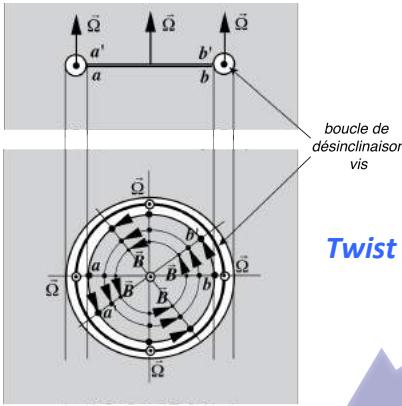
**Calculation of the elastic distortions  
associated with the topological singularities  
(dislocation and disclination loops)**

**Static case:**

$$K_1 (\tau^{(p)}(\vec{r}))^2 + \left[ 4K_2/3 + 2K_1(1+\tau_0 + \tau^{\text{ext}}(\vec{r}) + \tau^{\text{ch}}(\vec{r})) - K_0 \right] \tau^{(p)}(\vec{r}) + (F_{\text{dist}}^{\text{ch}}(\vec{r}) + F_{\text{pot}}^{\text{ch}}(\vec{r})) = \text{cste} = 0$$

**Calculation of the perturbations of the volumic expansion  
associated with the topological singularities  
(dislocation and disclination loops)**

# Twist disclination loop and edge dislocation loop

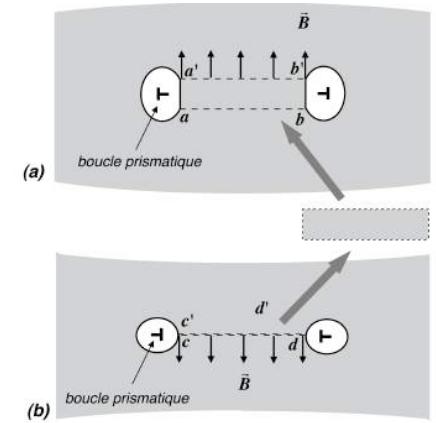


First partial Newton equation

$$nm \frac{d\vec{\phi}^{ch}}{dt} = -2(K_2 + K_3) \text{rot}(\vec{\omega}^{ch}) + (4K_2/3 + 2K_1(1+\tau_0) - K_0) \text{grad} \tau^{ch} + 2K_2 \vec{\lambda}^{ch}$$

Twist disclination loop

Edge dislocation loop



Rotation charge (analogous to electrical charge)

$$\mathbf{q}_{\lambda BV} = 2\pi R_{BV} \Lambda_{BV} = -\pi R_{BV} \vec{B}_{BV} \vec{t} \quad \& \quad \mathbf{q}_{\theta BV} = 0$$

$$\vec{\omega}_{ext}^{BV} = \frac{\mathbf{q}_{\lambda BV}}{4\pi} \frac{\vec{r}}{r^3} \quad \text{Source of a divergent rotation field (analogous to an electrical field)}$$

$$E_{dist}^{BV} \equiv E_{distore}^{BV} \equiv 2(K_2 + K_3) \zeta_{BV} R_{BV} \Lambda_{BV}^2 = \frac{1}{2} (K_2 + K_3) \zeta_{BV} R_{BV} \vec{B}_{BV}^2$$

$$E_{cin}^{BV} \equiv E_{cintore}^{BV} \equiv mn \zeta_{BV} R_{BV} \Lambda_{BV}^2 \mathbf{v}^2 = \frac{1}{4} mn \zeta_{BV} R_{BV} \vec{B}_{BV}^2 \mathbf{v}^2$$

$$M_0^{BV} = \frac{E_{dist}^{BV}}{c_t^2} = \frac{2}{c_t^2} (K_2 + K_3) \zeta_{BV} R_{BV} \Lambda_{BV}^2 = \frac{1}{2c_t^2} (K_2 + K_3) \zeta_{BV} R_{BV} \vec{B}_{BV}^2$$

$$\zeta_{BV} = \ln(A_{BV} R_{BV} / a)$$



1/ Perfect analogy between the rotation charge  
and a localized electrical charge

2/ No analogy in all other theories  
for the localized curvature charge !!!

Flexion charge (analogous to spatial curvature charge)

$$\left\{ \begin{array}{l} \mathbf{q}_{\lambda BC} = 0 \quad \& \quad \mathbf{q}_{\theta BC} = -2\pi \vec{n} (\vec{t} \wedge \vec{\Lambda}_{BC}) = 2\pi \vec{\Lambda}_{BC} \vec{m} = -2\pi \vec{n} \vec{B}_{BC} \\ \vec{\chi}_{ext}^{BC} = \frac{\mathbf{q}_{\theta BC}}{4\pi} \frac{\vec{r}}{r^3} \quad \text{Source of a divergent flexion field (analogous to a spatial curvature field)} \end{array} \right.$$

$$\left\{ \begin{array}{l} E_{dist}^{BC} \equiv E_{distore}^{BC} \equiv \left( \frac{K_2}{K_3} \right)^2 K_3 \zeta_{BC} R_{BC} \vec{\Lambda}_{BC}^2 \equiv \left( \frac{K_2}{K_3} \right)^2 K_3 \zeta_{BC} R_{BC} \vec{B}_{BC}^2 \\ E_{cin}^{BC} \equiv E_{cintore}^{BC} \equiv \frac{1}{2} \left( \frac{K_2}{K_3} \right)^2 mn \zeta_{BC} R_{BC} \vec{\Lambda}_{BC}^2 \mathbf{v}^2 = \frac{1}{2} \left( \frac{K_2}{K_3} \right)^2 mn \zeta_{BC} R_{BC} \vec{B}_{BC}^2 \mathbf{v}^2 \\ M_0^{BC} = \frac{E_{dist}^{BC}}{c_t^2} = \left( \frac{K_2}{K_3} \right)^2 \frac{1}{c_t^2} K_3 \zeta_{BC} R_{BC} \vec{\Lambda}_{BC}^2 = \left( \frac{K_2}{K_3} \right)^2 \frac{1}{c_t^2} K_3 \zeta_{BC} R_{BC} \vec{B}_{BC}^2 \\ \zeta_{BC} \equiv \ln(A_{BC} R_{BC} / a) \end{array} \right.$$



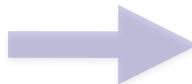
# Relativistic dynamics of the topological singularities



Hendrik Anton Lorentz  
(1853-1928)



**Conjecture:**  $\left\{ \begin{array}{l} K_0 = K_3 > 0, \\ 0 < K_1 \ll K_0 = K_3 \\ 0 \leq K_2 \ll K_3 = K_0 \end{array} \right.$



**Same Lorentz transformations  
for all topological singularities**

$$\left\{ \begin{array}{l} x_1' = \frac{x_1 - \mathbf{v}t}{\gamma_t} \\ x_2' = x_2'' = x_2 \\ x_3' = x_3'' = x_3 \\ t' = \frac{t - \mathbf{v}x_1/c_t^2}{\gamma_t} \end{array} \right. \quad \gamma = \sqrt{1 - \frac{\mathbf{v}^2}{c_s^2}}$$

**Relativistic energy of  
the twist disclination loop**

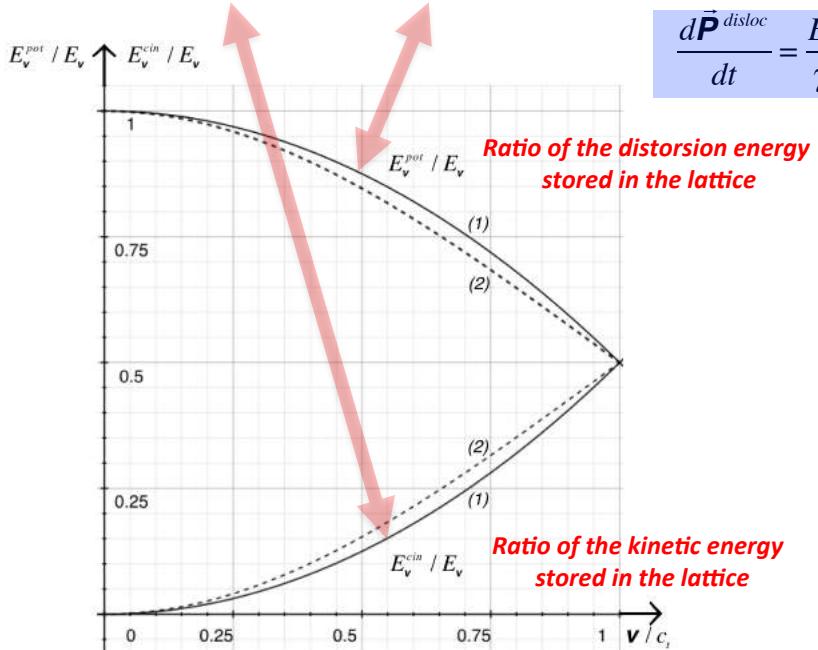
**Relativistic dynamics equation  
for the topological singularities**

**Relativistic energy  
of the edge dislocation loop**

$$E_{\mathbf{v}}^{BV} = \underbrace{\frac{1}{\gamma_t} \left( 1 - \frac{\mathbf{v}^2}{2c_t^2} \right) E_{dist}^{BV}}_{E_{\mathbf{v}}^{dist}} + \underbrace{\frac{1}{\gamma_t} \frac{1}{2} M_0^{BV} \mathbf{v}^2}_{E_{\mathbf{v}}^{cin}} = \frac{E_{dist}^{BV}}{\gamma_t} = \frac{M_0^{BV} c_t^2}{\gamma_t}$$

$$E_{\mathbf{v}}^{BC} = \underbrace{\frac{1}{\gamma_t} \left( 1 - \frac{\mathbf{v}^2}{2c_t^2} \right) E_{dist}^{BC}}_{E_{\mathbf{v}}^{dist}} + \underbrace{\frac{1}{\gamma_t} \frac{1}{2} M_0^{BC} \mathbf{v}^2}_{E_{\mathbf{v}}^{cin}} = \frac{E_{dist}^{BC}}{\gamma_t} = \frac{M_0^{BC} c_t^2}{\gamma_t}$$

$$\frac{d\vec{\mathbf{P}}^{disloc}}{dt} = \frac{E_{dist}^{disloc}}{\gamma_t^3 c_t^2} \vec{\mathbf{a}} = \frac{M_0^{disloc}}{\gamma_t^3} \vec{\mathbf{a}} = \vec{\mathbf{F}}_{PK}$$



**Ratio of the distortion energy  
stored in the lattice**

**Ratio of the kinetic energy  
stored in the lattice**

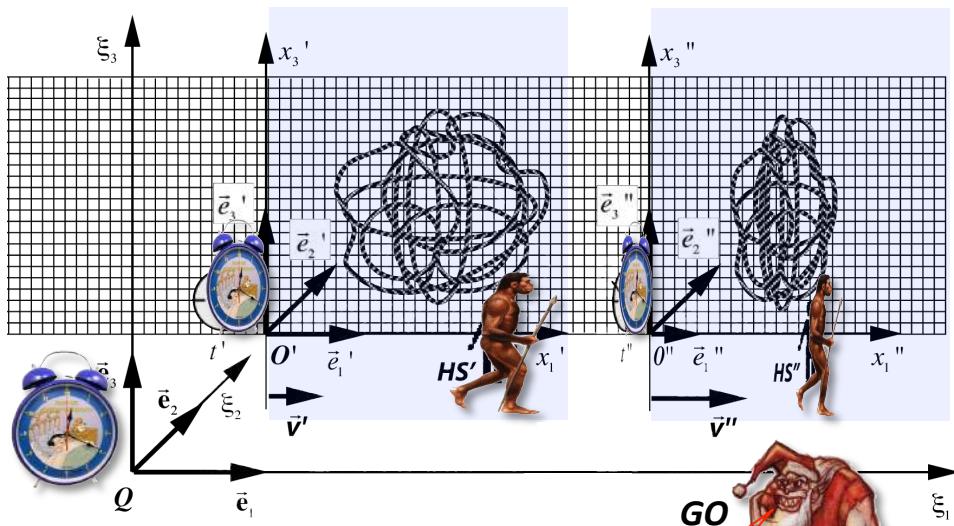


**All the topological singularities  
(of dislocation or disclination types)  
follow exactly  
the theory of special relativity**

## Effects of the Lorentz transformation of the special relativity

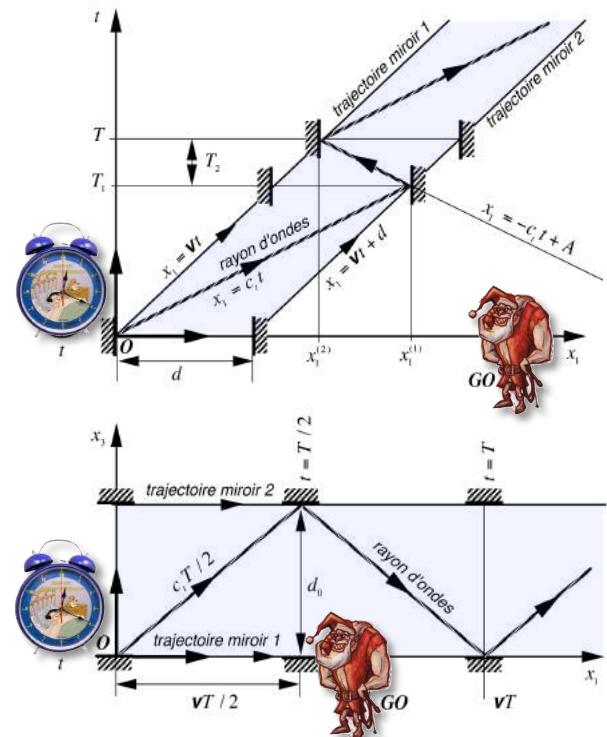
Albert Einstein  
(1879-1955)

Measuring rods contraction and clock slowing down  
for the local observers HS



$$\left\{ \begin{array}{l} x_1' = \frac{x_1 - vt}{\gamma_t} \\ x_2' = x_2'' = x_2 \\ x_3' = x_3'' = x_3 \\ t' = \frac{t - vx_1/c_t^2}{\gamma_t} \end{array} \right. \quad \gamma = \sqrt{1 - \frac{\bar{v}^2}{c_t^2}}$$

Verification of  
the Michelson-Morley experiments

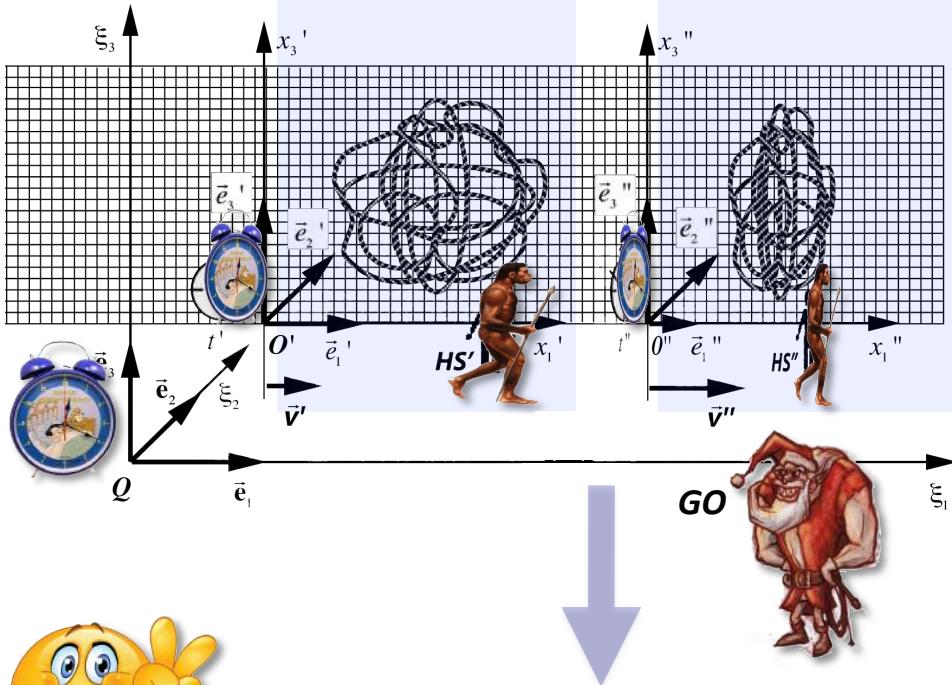


The new  
« aether »  
is arrived!



## Effects of the Lorentz transformation of the special relativity

*Impossibility for the local observers HS to measure their own velocity with regard to the lattice*

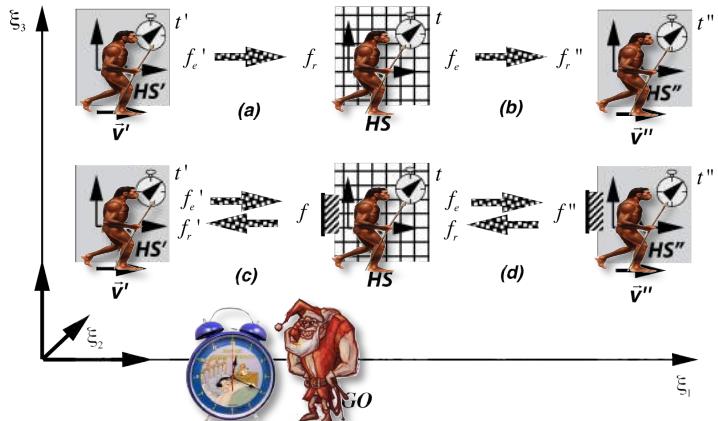


1/ Complete analogy with the Lorentz transformation and the special relativity

2/ The cosmological lattice behaves as an « aether » which verifies the Michelson-Morley experiment and the Doppler-Fizeau effects, and which explains very simply the twin paradox.

3 / The local observers HS cannot measure their own velocity with regard to the lattice!

*Verification of all the Doppler-Fizeau experiments*



*Simple explanation of the famous twin paradox of the special relativity*



# II C - Gravitation and cosmology

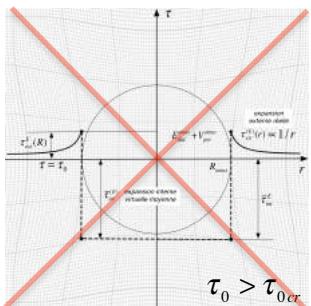
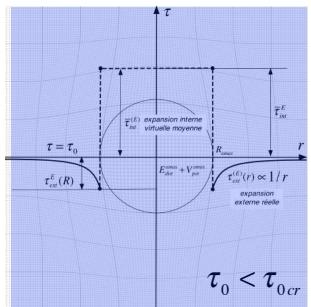
## Perturbation of the external expansion field of a topological singularity

$$K_1 \left( \tau^{(p)}(\vec{r}) \right)^2 + \left[ 4K_2 / 3 + 2K_1 (1 + \tau_0 + \tau^{ext}(\vec{r}) + \tau^{ch}(\vec{r})) - K_0 \right] \tau^{(p)}(\vec{r}) + \left( F_{dist}^{ch}(\vec{r}) + F_{pot}^{ch}(\vec{r}) \right) = cste = 0$$

**Second partial Newton equation  
(in the static case)**

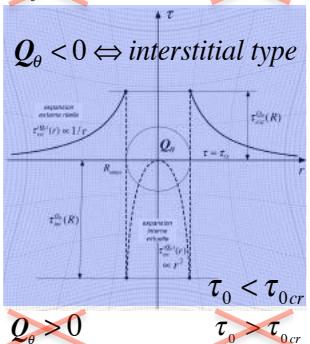
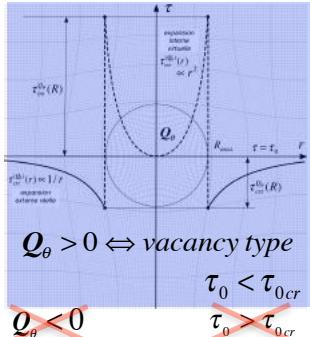
**Effect of the energy  
of a singularity**

$$E_{dist}^{amas} + V_{pot}$$



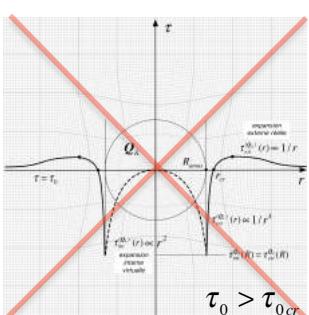
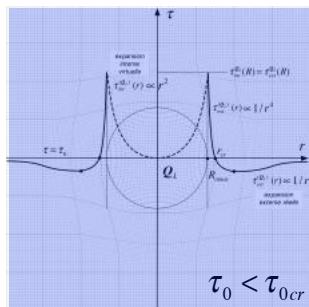
**Effect of the flexion charge  
of a singularity**

$$Q_\theta$$



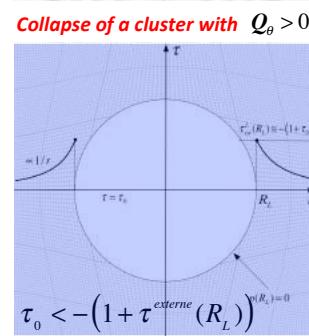
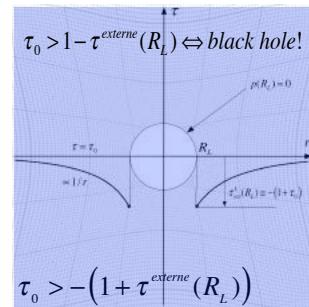
**Effect of the rotation charge  
of a singularity**

$$Q_\lambda$$



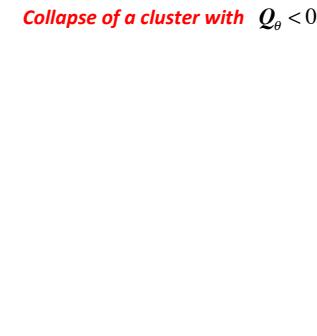
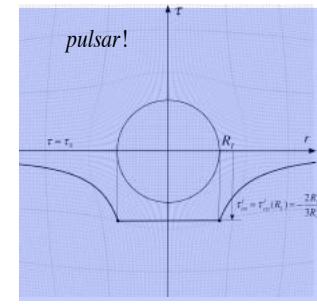
**Effect of a macroscopic  
vacancy singularity**

$$R_L = \sqrt[3]{\frac{3N_L}{4\pi n_0 e}}$$



**Effect of a macroscopic  
interstitial singularity**

$$R_I \equiv \sqrt[3]{\frac{3N_I}{4\pi n_0}} e^{\frac{\tau_0 + \tau^{extreme}(R_I)}{3}}$$



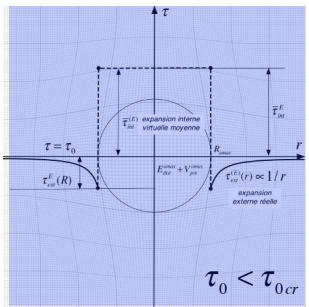
## External expansion field of a topological singularity of vacancy or interstitial type

$$K_1 \left( \tau^{(p)}(\vec{r}) \right)^2 + \left[ 4K_2 / 3 + 2K_1 \left( 1 + \tau_0 + \tau^{ext}(\vec{r}) + \tau^{ch}(\vec{r}) \right) - K_0 \right] \tau^{(p)}(\vec{r}) + \left( F_{dist}^{ch}(\vec{r}) + F_{pot}^{ch}(\vec{r}) \right) = cste = 0$$

**Second partial Newton equation  
(in the static case)**

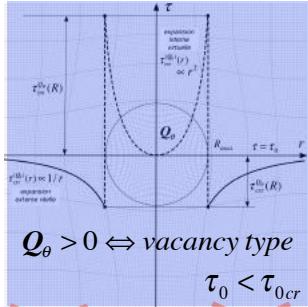
**Effect of the energy  
of the singularity**

$$E_{dist}^{amas} + V_{pot}^{amas}$$



**Effect of the flexion charge  
of the singularity**

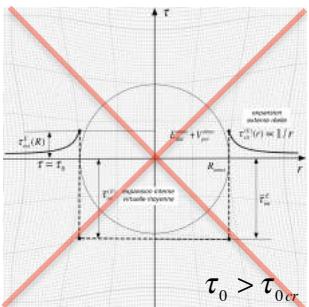
$$Q_\theta$$



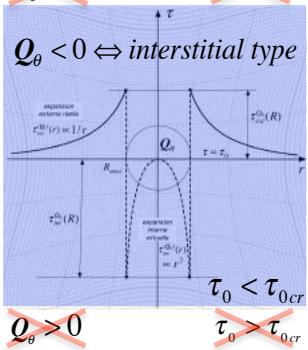
$$Q_\theta > 0 \Leftrightarrow \text{vacancy type}$$

**Conjecture:**

flexion charge :  $\begin{cases} Q_\theta > 0 \Leftrightarrow \text{vacancy type} \Leftrightarrow \text{analogous to anti-matter} \\ Q_\theta < 0 \Leftrightarrow \text{interstitial type} \Leftrightarrow \text{analogous to matter} \end{cases}$



$$Q_\theta < 0 \Leftrightarrow \text{interstitial type}$$



$$Q_\theta < 0 \quad r_0 > r_{0,cr}$$

$$|\tau_{ext}^{Q_\theta}| \ll |\tau_{ext}^E|$$

1/ The gravitational field  
of a vacancy type cluster (anti-matter)  
is slightly higher than that  
of an interstitial type cluster (matter)



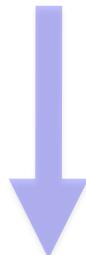
## Collapse of clusters of vacancy or interstitial type: black holes and pulsars

$$K_1 \left( \tau^{(p)}(\vec{r}) \right)^2 + \left[ 4K_2 / 3 + 2K_1 \left( 1 + \tau_0 + \tau^{ext}(\vec{r}) + \tau^{ch}(\vec{r}) \right) - K_0 \right] \tau^{(p)}(\vec{r}) + \left( F_{dist}^{ch}(\vec{r}) + F_{pot}^{ch}(\vec{r}) \right) = cste = 0$$

**Second partial Newton equation  
(in the static case)**

### Conjecture:

flexion charge :  $\begin{cases} Q_\theta > 0 \Leftrightarrow \text{vacancy type} \Leftrightarrow \text{analogous to anti-matter} \\ Q_\theta < 0 \Leftrightarrow \text{interstitial type} \Leftrightarrow \text{analogous to matter} \end{cases}$



1/ The collapse of a cluster with  $Q_\theta > 0$  (anti-matter)  
leads to a macroscopic vacancy singularity

2/ If  $\tau_0 > 1 - \tau^{extreme}(R_L)$ , the macroscopic vacancy becomes a black hole

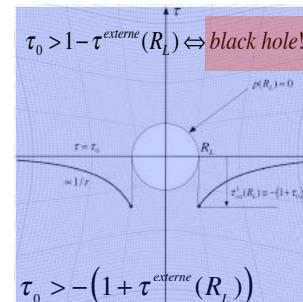
3/ The collapse of a cluster with  $Q_\theta < 0$  (matter)  
leads to a macroscopic interstitial singularity

4/ The macroscopic interstitial has to correspond  
to a pulsar !!!



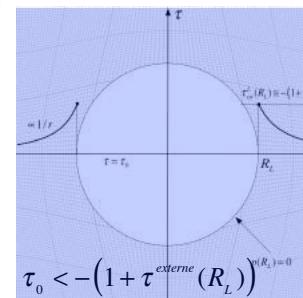
### **Effect of a macroscopic vacancy singularity**

$$R_L = \sqrt[3]{\frac{3N_L}{4\pi n_0 e}}$$



$\tau_0 > - (1 + \tau^{extreme}(R_L))$

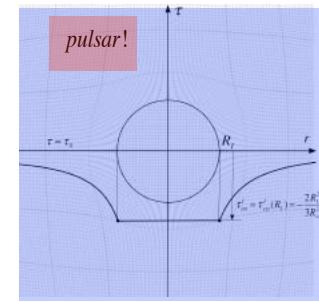
**Collapse of a cluster with  $Q_\theta > 0$**



$\tau_0 < - (1 + \tau^{extreme}(R_L))$

### **Effect of a macroscopic interstitial singularity**

$$R_I \equiv \sqrt[3]{\frac{3N_I}{4\pi n_0 e}} e^{\frac{\tau_0 + \tau^{extreme}(R_I)}{3}}$$



$\tau_0 = \tau^{extreme}(R_I) - \frac{2R_I}{3R_0}$

**Collapse of a cluster with  $Q_\theta < 0$**

# « Gravitational » interaction between elementary topological singularities

Calculations of the interaction forces between two elementary singularities due to their expansion perturbations

$$\begin{aligned} F_{\text{grav}}^{BV-BV} &\equiv \bar{G}_{\text{grav}} \frac{M_{0(1)}^{BV} M_{0(2)}^{BV}}{d^2} \\ F_{\text{grav}}^{BC-BC} &\equiv (\alpha_{BC} + 2\beta_{BC}) \bar{G}_{\text{grav}} \frac{M_{\text{courbure}(1)}^{BC} M_{0(2)}^{BC} + M_{\text{courbure}(2)}^{BC} M_{0(1)}^{BC}}{d^2} + 2(\alpha_{BC} + 2\beta_{BC}) \bar{G}_{\text{grav}} \frac{M_{0(1)}^{BC} M_{0(2)}^{BC}}{d^2} \\ F_{\text{grav}}^{BM-BM} &\equiv 2(\alpha_{BM} + 2\beta_{BM}) \bar{G}_{\text{grav}} \frac{M_{0(1)}^{BM} M_{0(2)}^{BM}}{d^2} \end{aligned}$$

Predominant interaction

$$\begin{aligned} F_{\text{grav}}^{BV-BC} &\equiv \frac{1}{2} \bar{G}_{\text{grav}} \frac{M_{\text{courbure}}^{BC} M_0^{BV}}{d^2} + \left( \frac{1}{2} + 4(\alpha_{BC} + 2\beta_{BC}) \right) \bar{G}_{\text{grav}} \frac{M_0^{BV} M_0^{BC}}{d^2} \\ F_{\text{grav}}^{BV-BM} &\equiv \left( \frac{1}{2} + 4(\alpha_{BM} + 2\beta_{BM}) \right) \bar{G}_{\text{grav}} \frac{M_0^{BV} M_0^{BM}}{d^2} \\ F_{\text{grav}}^{BC-BM} &\equiv 4(\alpha_{BM} + 2\beta_{BM}) \bar{G}_{\text{grav}} \frac{M_{\text{courbure}}^{BM} M_0^{BM}}{d^2} + 4(\alpha_{BC} + 2\beta_{BC} + \alpha_{BM} + 2\beta_{BM}) \bar{G}_{\text{grav}} \frac{M_0^{BC} M_0^{BM}}{d^2} \end{aligned}$$

$$\begin{aligned} F_{\text{grav}}^{BV-L} &\equiv \frac{1}{2} \bar{G}_{\text{grav}} \frac{9 + \tau_0}{1 + \tau_0} \frac{M_0^{BV} M_{\text{grav}}^{(L)}}{d^2} \equiv \frac{c_t^2}{8} (9 + \tau_0) \frac{M_0^{BV} R_L}{d^2} \\ F_{\text{grav}}^{BC-L} &\equiv 4 \bar{G}_{\text{grav}} \frac{1}{1 + \tau_0} \frac{M_{\text{courbure}}^{BC} M_{\text{grav}}^{(L)}}{d^2} + 4 \bar{G}_{\text{grav}} \frac{1 + (\alpha_{BC} + 2\beta_{BC})(1 + \tau_0)}{1 + \tau_0} \frac{M_0^{BC} M_{\text{grav}}^{(L)}}{d^2} \\ &\equiv c_t^2 \frac{M_{\text{courbure}}^{BC} R_L}{d^2} + c_t^2 [1 + (\alpha_{BC} + 2\beta_{BC})(1 + \tau_0)] \frac{M_0^{BC} R_L}{d^2} \\ F_{\text{grav}}^{BM-L} &\equiv 4 \bar{G}_{\text{grav}} \frac{1 + (\alpha_{BM} + 2\beta_{BM})(1 + \tau_0)}{1 + \tau_0} \frac{M_0^{BM} M_{\text{grav}}^{(L)}}{d^2} \equiv c_t^2 [1 + (\alpha_{BM} + 2\beta_{BM})(1 + \tau_0)] \frac{M_0^{BM} R_L}{d^2} \end{aligned}$$

$$\begin{aligned} F_{\text{grav}}^{BV-I} &\equiv \frac{9}{2} \bar{G}_{\text{grav}} \frac{M_0^{BV} M_{\text{grav}}^{(I)}}{d^2} \equiv \frac{3c_t^2}{4R_\infty^2} \frac{M_0^{BV} R_I^3}{d^2} \\ F_{\text{grav}}^{BC-I} &\equiv 4 \bar{G}_{\text{grav}} \frac{M_{\text{courbure}}^{BC} M_{\text{grav}}^{(I)}}{d^2} + 4 \bar{G}_{\text{grav}} (1 + \alpha_{BC} + 2\beta_{BC}) \frac{M_0^{BC} M_{\text{grav}}^{(I)}}{d^2} \\ &\equiv \frac{2c_t^2}{3R_\infty^2} \frac{M_{\text{courbure}}^{BC} R_I^3}{d^2} + \frac{2c_t^2}{3R_\infty^2} (1 + \alpha_{BC} + 2\beta_{BC}) \frac{M_0^{BC} R_I^3}{d^2} \\ F_{\text{grav}}^{BM-I} &\equiv 4 \bar{G}_{\text{grav}} [1 + \alpha_{BM} + 2\beta_{BM}] \frac{M_0^{BM} M_{\text{grav}}^{(I)}}{d^2} \equiv \frac{2c_t^2}{3R_\infty^2} [1 + \alpha_{BM} + 2\beta_{BM}] \frac{M_0^{BM} R_I^3}{d^2} \end{aligned}$$

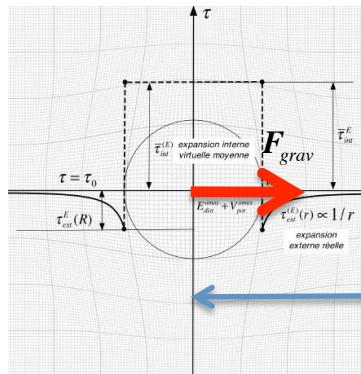
$$\begin{aligned} F_{\text{grav}}^{L-L} &\equiv \frac{8 \bar{G}_{\text{grav}}}{(1 + \tau_0)} \frac{M_{\text{grav}(1)}^{(L)} M_{\text{grav}(2)}^{(L)}}{d^2} \equiv \frac{c_t^4 (1 + \tau_0)}{2 \bar{G}_{\text{grav}}} \frac{R_{L(1)} R_{L(2)}}{d^2} \\ F_{\text{grav}}^{I-I} &\equiv 2 \bar{G}_{\text{grav}} \frac{M_{\text{grav}(1)}^{(I)} M_{\text{grav}(2)}^{(I)}}{d^2} \equiv \frac{c_t^4}{18 G_{\text{grav}} R_\infty^4} \frac{R_{I(1)}^3 R_{I(2)}^3}{d^2} \\ F_{\text{grav}}^{L-I} &\equiv 4 \bar{G}_{\text{grav}} \frac{2 + \tau_0}{1 + \tau_0} \frac{M_{\text{grav}}^{(L)} M_{\text{grav}}^{(I)}}{d^2} \equiv \frac{c_t^4}{6R_\infty^2} \frac{2 + \tau_0}{G_{\text{grav}}} \frac{R_I R_L^3}{d^2} \end{aligned}$$

BV=screw disclination loop  
BC=edge dislocation loop  
BM=mixed dislocation loop  
  
L=macroscopic vacancy  
I=macorscopic interstitial



Gotlib

Gravitational interaction force between two clusters of elementary singularities



$$F_{\text{grav}} \equiv \bar{G}_{\text{grav}} \frac{M_{0(1)}^{\text{amas}} M_{0(2)}^{\text{amas}}}{d^2} \left( 1 - \frac{\bar{G}_{\text{grav}} (M_{0(1)} + M_{0(2)})}{4c_t^2 d} + \dots \right)$$

$$\bar{G}_{\text{grav}} = \frac{c_t^4}{8\pi(K_0 - 4K_2/3 - 2K_1(1 + \tau_0))R_\infty^2} \begin{cases} > 0 & \text{si } \tau_0 < \tau_{0\text{cr}} \\ < 0 & \text{si } \tau_0 > \tau_{0\text{cr}} \end{cases}$$

$$\tau_{\text{ext}}(r) \equiv -\frac{4\bar{G}_{\text{grav}} M_0^{\text{amas}}}{c_t^2 r}$$



1/ Analogy with Newton gravitation

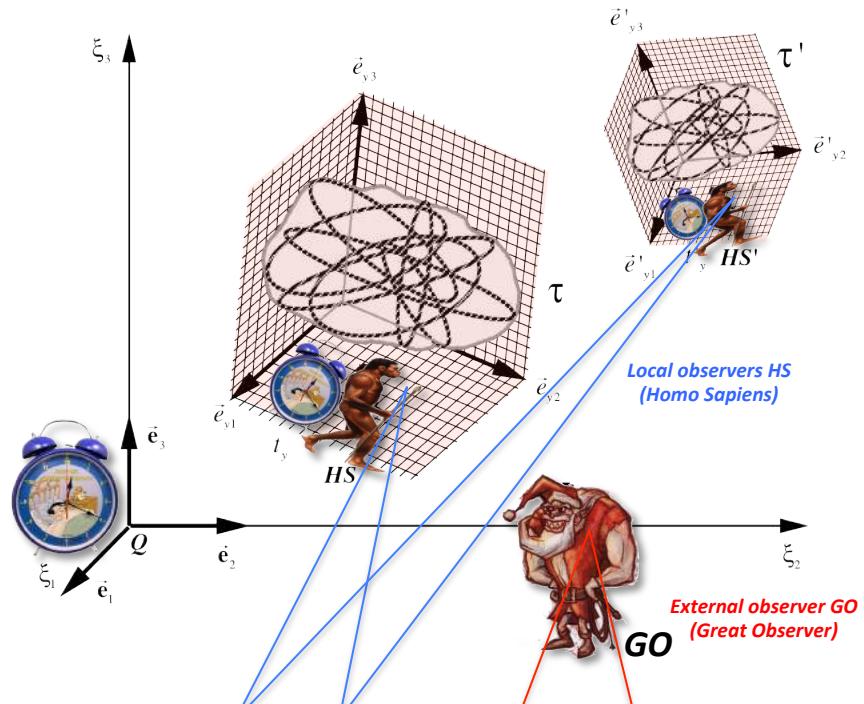
2/ Small corrections at very short distances as in general relativity, but different!

3/ Gravitaonnal parameter G is not a constant. It depends on the expansion background

# Invariance of the Maxwellian formulation of the physics laws for the local observers HS

Absolute frame of the external observer GO and local frames of the observers HS

Behaviours of the measuring rods and local clock of the HS observers insuring the invariance of their physics laws



$$\left\{ \begin{array}{l} -\frac{\partial(2\vec{\omega}_{(y)}^d)}{\partial t_y} + \text{rot}_y \vec{\phi}_{(y)}^{\text{rot}} \cong (2\vec{J}_{(y)}) \\ \text{div}_y(2\vec{\omega}_{(y)}^d) = (2\lambda_{(y)}) \\ \frac{\partial(n_y \vec{p}_{(y)}^{\text{rot}})}{\partial t_y} \cong -\text{rot}_y \left( \frac{\vec{m}_{(y)}}{2} \right) + 2K_2 \vec{\lambda}_{(y)}^{\text{rot}} \\ \text{div}_y(n_y \vec{p}_{(y)}^{\text{rot}}) = 0 \\ (2\vec{\omega}_{(y)}^d) = \frac{1}{(K_2 + K_3)} \left( \frac{\vec{m}_{(y)}}{2} \right) + (2\vec{\omega}_{(y)}^m) \\ (n_y \vec{p}_{(y)}^{\text{rot}}) = (n_y \vec{p}) \left[ \vec{\phi}_{(y)}^{\text{rot}} + (C_{I(y)} - C_{L(y)}) \vec{\phi}_{(y)}^{\text{rot}} + \left( \frac{1}{n_y} (\vec{J}_{I(y)}^{\text{rot}} - \vec{J}_{L(y)}^{\text{rot}}) \right) \right] \\ \frac{\partial(2\lambda_{(y)})}{\partial t_y} \cong -\text{div}_y(2\vec{J}_{(y)}) \\ c_{t0} = \sqrt{\frac{K_2 + K_3}{mn_0}} = \text{cste} \end{array} \right.$$

Invariant Maxwell equations

Maxwell equations depending on the local expansion

$$\left\{ \begin{array}{l} -\frac{\partial(2\vec{\omega}^d)}{\partial t} + \text{rot} \vec{\phi}^{\text{rot}} \cong (2\vec{J}) \\ \text{div}(2\vec{\omega}^d) = (2\lambda) \\ \frac{\partial(n\vec{p}^{\text{rot}})}{\partial t} \cong -\text{rot} \left( \frac{\vec{m}}{2} \right) + 2K_2 \vec{\lambda}^{\text{rot}} \\ \text{div}(n\vec{p}^{\text{rot}}) = 0 \\ (2\vec{\omega}^d) = \frac{1}{(K_2 + K_3)} \left( \frac{\vec{m}}{2} \right) + (2\vec{\omega}^m) + (2\vec{\omega}_0(t)) \\ (n\vec{p}^{\text{rot}}) = (nm) \left[ \vec{\phi}^{\text{rot}} + (C_I - C_L) \vec{\phi}^{\text{rot}} + \left( \frac{1}{n} (\vec{J}_I^{\text{rot}} - \vec{J}_L^{\text{rot}}) \right) \right] \\ \frac{\partial(2\lambda)}{\partial t} \cong -\text{div}(2\vec{J}) \\ c_t = \sqrt{\frac{K_2 + K_3}{mn}} = \sqrt{\frac{K_2 + K_3}{mn_0}} e^{\tau_0} \neq \text{cste} \end{array} \right.$$



1/ Analogy with the Schwarzschild metric of the general relativity

2/ Measuring rods and clocks of the HS observers depend on local expansion of the lattice

3/ Physics laws are invariant for the local observers HS

4/ Only an external observer GO can describe the effects of the local expansion, because he owns universal measuring rods and clock

$$\left\{ \begin{array}{l} y_i = e^{\frac{G_{\text{grav}} M_0^{\text{amas}}}{c_t^2 r}} \xi_i \cong \left( 1 + \frac{G_{\text{grav}} M_0^{\text{amas}}}{c_t^2 r} \right) \xi_i \\ t_y = e^{-\frac{G_{\text{grav}} M_0^{\text{amas}}}{c_t^2 r}} t \cong \left( 1 - \frac{G_{\text{grav}} M_0^{\text{amas}}}{c_t^2 r} \right) t \end{array} \right.$$

Relations of our theory

Relations of the Schwarzschild metric in general relativity

## Agreement and disagreement with the general relativity

$$\left\{ \begin{array}{l} y_i = e^{-\frac{G_{grav}M_0^{amas}}{c_t^2 r}} \xi_i \equiv \left( 1 + \frac{G_{grav}M_0^{amas}}{c_t^2 r} \right) \xi_i \\ t_y = e^{-\frac{G_{grav}M_0^{amas}}{c_t^2 r}} t \equiv \left( 1 - \frac{G_{grav}M_0^{amas}}{c_t^2 r} \right) t \end{array} \right.$$

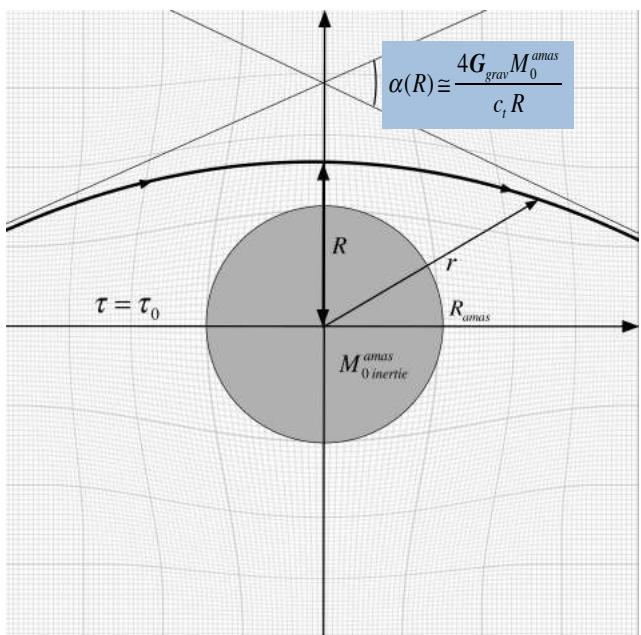
Relations of  
our theory

Relations of  
the Schwarzschild metric  
in general relativity



Karl Schwarzschild  
(1873-1916)

At long distances, perfect agreement with general relativity: example of the light rays curvature



At very short distances, disagreement with general relativity: example of the characteristic radii of black holes

Our theory	General relativity
$R_{Schwarzschild} = \frac{2G_{grav}M_0^{amas}}{c_t^2}$	$R_{Schwarzschild} = \frac{2G_{grav}M_0^{amas}}{c_t^2}$
$R_{photon} = \frac{2G_{grav}M_0^{amas}}{c_t^2}$	$R_{photon} = \frac{3G_{grav}M_0^{amas}}{c_t^2}$
$R_{time \ dilatation \rightarrow \infty} \rightarrow 0$	$R_{time \ dilatation \rightarrow \infty} \equiv \frac{G_{grav}M_0^{amas}}{c_t^2}$



The characteristic radii of a black hole obtained by our theory seem much more satisfactory than those obtained from the Schwarzschild metric of general relativity

# Spatial curvature of the lattice as seen by the observer GO compared to the spatio-temporal curvature of the general relativity

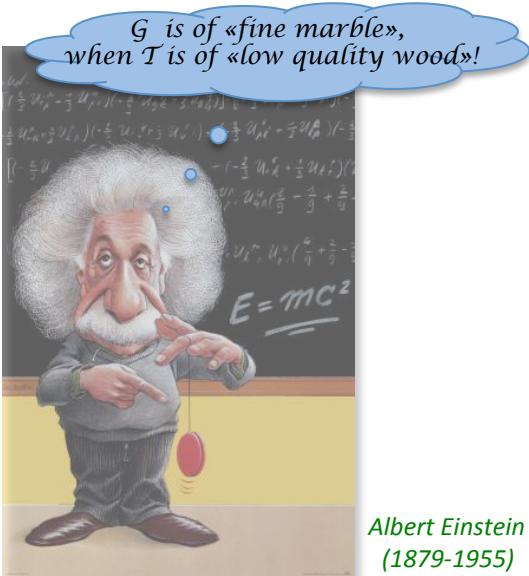
Einstein equations of the 4D curvature of space-time in general relativity

$$G = 8\pi T$$

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R$$

$$\vec{\nabla} \cdot G = \vec{\nabla} \cdot T = \vec{\nabla} \cdot T [ \dots ] = 0$$

*Motion equation*



Equations of the 3D space curvature of the lattice as seen by the external observer GO

$$\vec{\chi} = \frac{1}{2K_2} \left[ n \frac{d\vec{p}}{dt} - \left( \frac{4K_2}{3} + 2K_1 \right) \overrightarrow{\text{grad}} \tau - \overrightarrow{\text{grad}} F^{\ell} \right]$$

Energy-momentum tensors

$$\vec{\chi} = -\overrightarrow{\text{rot}} \vec{\omega}^{\ell} + \vec{\lambda}$$

Curvature charge

$$\text{div } \vec{\chi} = \frac{1}{2K_2} \left[ \text{div} \left( n \frac{d\vec{p}}{dt} \right) - \left( \frac{4K_2}{3} + 2K_1 \right) \Delta \tau - \Delta F^{\ell} \right] = \text{div } \vec{\lambda} = \theta$$

*Newton equation of the lattice!*

1/ Analogy with the general relativity:

- curvature equations with curvature tensors and energy-momentum tensors

- divergence of the curvature tensors -> motion equations

2/ For the external observer GO, who owns an universal clock, the lattice curvature is purely spatial

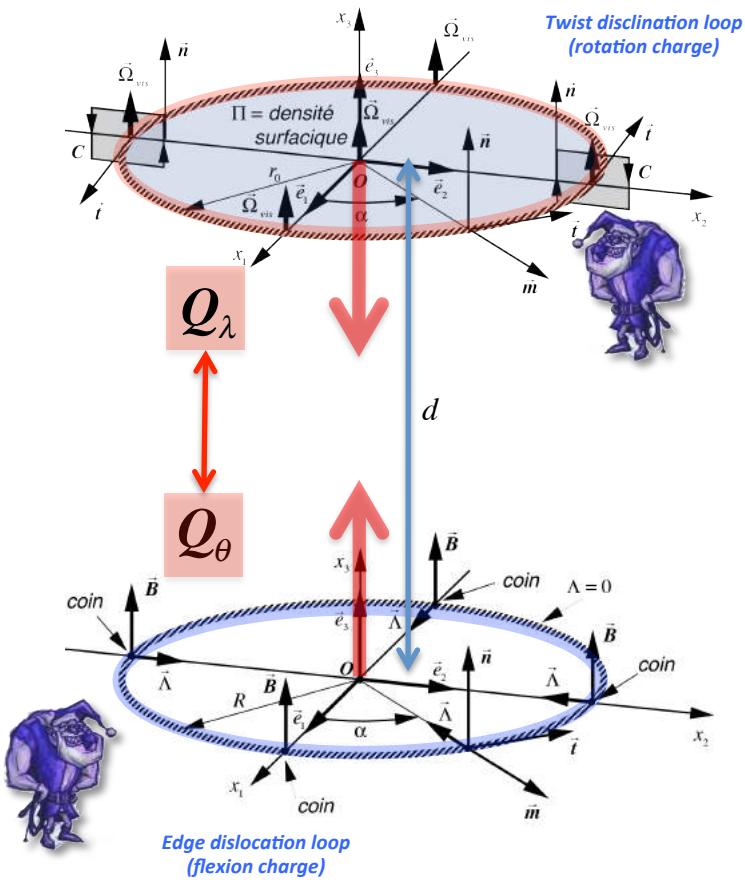
3/ For the local observers HS, who own local clocks, the curvature has to be a space-time curvature

4/ The concept of curvature charge is COMPLETELY NEW, as it does not exist in general relativity

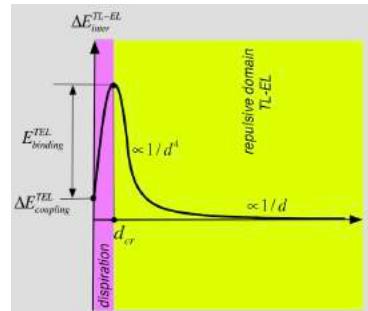


# Weak interaction in the case of a dispiration formed by a twist disclination loop associated to an edge dislocation loop

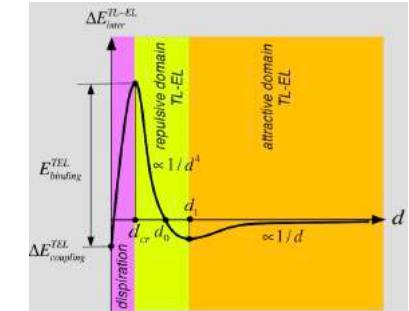
Combination of a twist disclination loop with an edge dislocation loop to form a dispiration loop



Weak interaction capture potential between  $Q_\lambda$  and  $Q_\theta$  with a very short range



Twist disclination loop with interstitial type edge dislocation loop

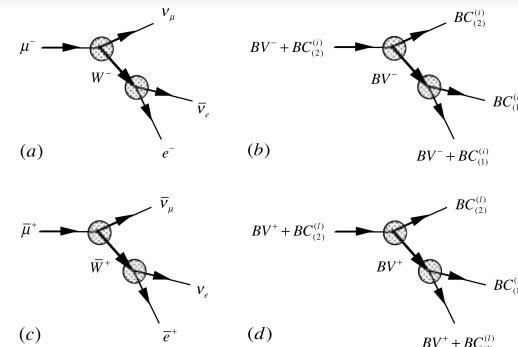


Twist disclination loop with vacancy type edge dislocation loop

1/ Analogy with the weak interaction force of the standard model of particles

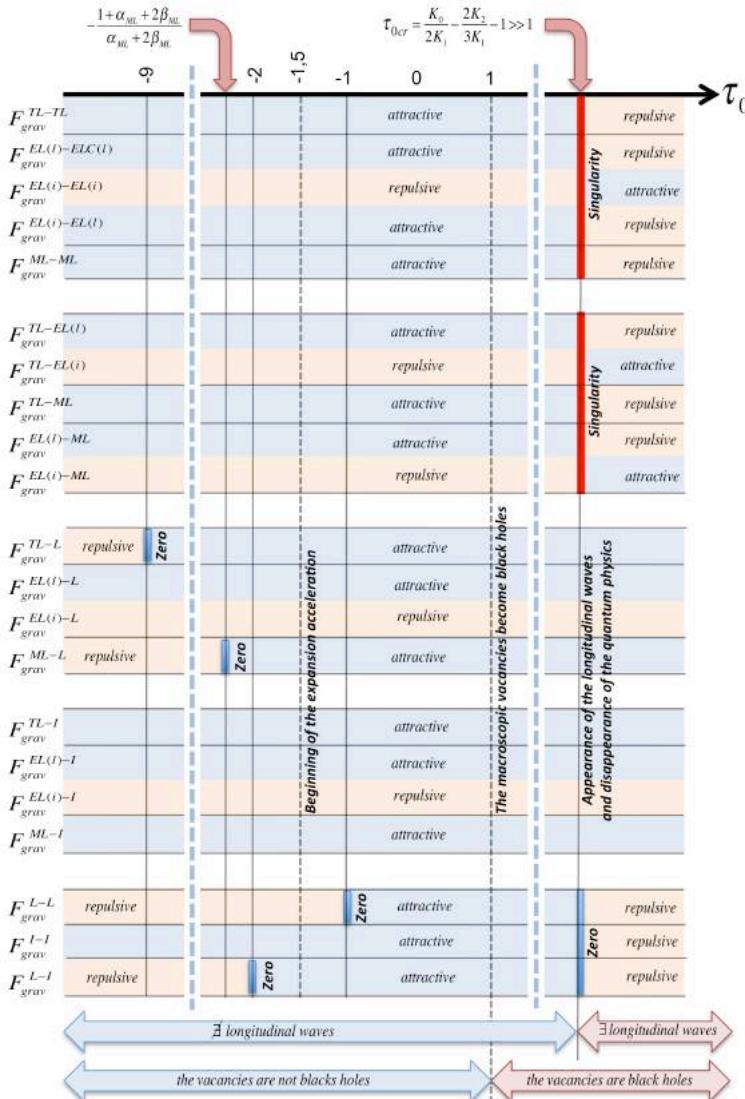


2/ The weak interaction is strongly associated to the gravitational interaction between a flexion charge and a rotation charge



# Hierarchy of the gravitational interactions

Behaviours of the gravitational interaction forces as a function of the lattice expansion background



Hierarchy of the gravitational interactions  
(effects of the curvature mass  
associated to the flexion charge)



$X \Rightarrow$  particles (dispirations containing interstitial edge dislocation loop)  
 $\bar{X} \Rightarrow$  anti-particle (dispirations containing vacancy edge dislocation loop)

$v^0 \Rightarrow$  neutrino (pure interstitial edge dislocation loop)

$\bar{v}^0 \Rightarrow$  anti-neutrino (pure vacancy edge dislocation loop)

$$\left\{ \begin{array}{l} M_0^X = M_0^{\bar{X}} > 0 \\ M_{courbure}^{\bar{X}} > 0 ; M_{courbure}^X < 0 \\ |M_{courbure}^X| = M_{courbure}^{\bar{X}} \ll M_0^X = M_0^{\bar{X}} \end{array} \right. \quad \left\{ \begin{array}{l} M_0^{v^0} = M_0^{\bar{v}^0} > 0 \\ M_{courbure}^{v^0} > 0 ; M_{courbure}^{\bar{v}^0} < 0 \\ |M_{courbure}^{v^0}| = M_{courbure}^{\bar{v}^0} \gg M_0^{v^0} = M_0^{\bar{v}^0} \end{array} \right.$$

$$\left\{ \begin{array}{l} F_{grav}^{X-X} \sim F_{grav}^{X-\bar{X}} \sim F_{grav}^{\bar{X}-\bar{X}} \\ F_{grav}^{X-Y} \sim F_{grav}^{\bar{X}-Y} \equiv F_{grav}^{X-\bar{Y}} \sim F_{grav}^{\bar{X}-\bar{Y}} \\ F_{grav}^{v^0-v^0} < 0 ; F_{grav}^{\bar{v}^0-\bar{v}^0} > 0 ; F_{grav}^{v^0-\bar{v}^0} \equiv 0 ; F_{grav}^{v^0-v^0} = -F_{grav}^{\bar{v}^0-\bar{v}^0} \\ F_{grav}^{X-v^0} < 0 ; F_{grav}^{X-\bar{v}^0} \equiv 0 ; F_{grav}^{\bar{X}-v^0} \equiv 0 ; F_{grav}^{\bar{X}-\bar{v}^0} > 0 \end{array} \right.$$



1/ The interactions  $v^0-v^0$  and  $X-\bar{v}^0$  with a neutrino are repulsive!!!

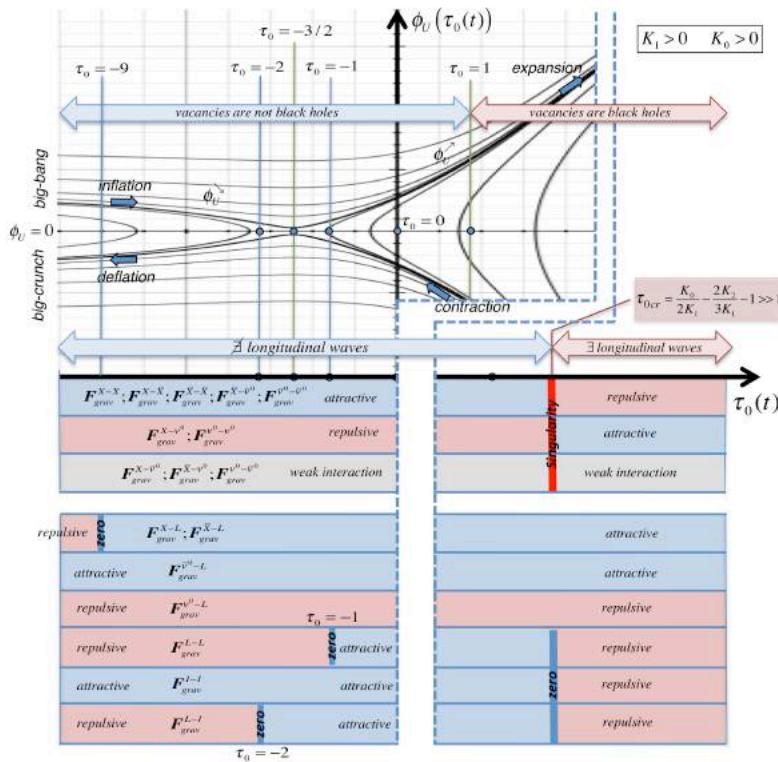
2/ All the other interactions are attractive (or very small)

3/ Attractive interaction between particles is slightly lower than attractive interaction between anti-particles

4/ The slight asymmetry existing between matter and anti-matter is due to the flexion charge of the edge dislocation loops (which DOES NOT EXIST in all other theories!)

# Plausible scenario of cosmological evolution of matter in our universe

## Stages of cosmologic expansion of the lattice



1/ big-bang

2/ inflation and hypothetic solidification of the lattice with formation of numerous topological singularities

3/ annihilation of topological singularities with formation of photons coupled to the topological singularities

4/ condensation of the remaining topological loops in particles and anti-particles

5/ decoupling of matter and photons to form the cosmic microwave background

6/ phase transition by precipitation of clusters of particles and anti-particles to form galaxies inside a sea of repulsive neutrinos

7/ segregation of the anti-matter in the center of the galaxies due to the slightly higher gravity of anti-matter

8/ under gravity, collapse of the anti-matter nucleus in gigantic black holes (macroscopic vacancies) in the center of galaxies

9/ evolution of the remaining matter to form the stars and planet systems

10/ under gravity, collapse of stars of matter to form pulsars (macroscopic interstitial clusters)

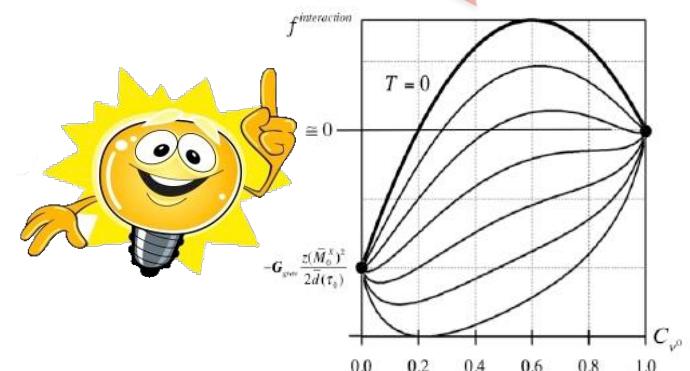


1/ Explains the formation of the galaxies and of gigantic black holes in the center of the galaxies

2/ Explains the disappearance of anti-matter inside the universe

3/ Explains the «dark matter»: the repulsive neutrino sea acts as a strong pressure on the galaxy periphery

4/ Explains simply the Hubble constant, the galaxy redshift and the cooling of the cosmic microwave background

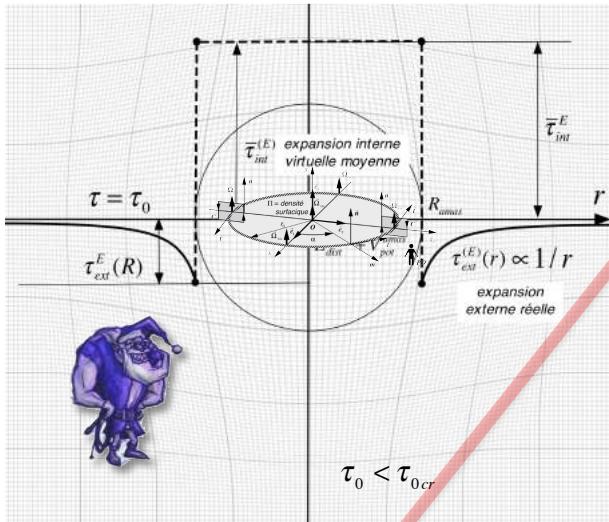


## II D - Quantum physics and standard model of particles

### Gravitational fluctuations of the expansion field associated to a mobile singularity

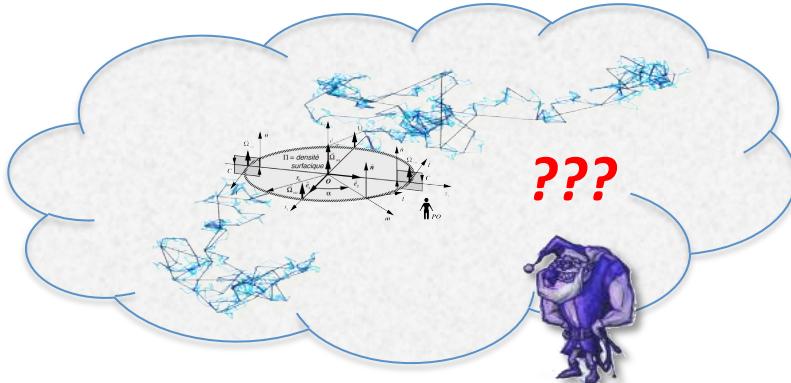
**Immobile singularity**

=> static external gravitational field



**Mobile singularity**

=> dynamic external gravitational field



**Second partial Newton equation  
(in the dynamic case)**

$$\frac{\partial^2 \tau^{(p)}}{\partial t^2} \equiv -\frac{K_0}{mn} \Delta \tau^{(p)} = -c_t^2 \Delta \underline{\tau}^{(p)}$$

**Dynamic solution**

$$\underline{\tau}^{(p)}(\vec{r}, t) \equiv \underline{\psi}(\vec{r}, t) e^{\pm i \omega_f(\vec{r}, t) t}$$

Wave equation for the amplitude and phase of the dynamic fluctuations of the gravitational field, which should contain information on relativistic energy and relativistic momentum of the singularity

$$\frac{\partial^2 \underline{\psi}}{\partial t^2} \pm 2i\omega_f \frac{\partial \underline{\psi}}{\partial t} - \omega_f^2 \underline{\psi} \equiv -c_t^2 \Delta \underline{\psi}$$



**Conjecture:**

Use « *a priori* » the quantum physics operators with the relativistic dynamic relations

$$\begin{cases} -\hbar^2 \frac{\partial^2}{\partial t^2} \underline{\psi} \rightarrow E_v \underline{\psi} \\ -\hbar^2 \Delta \underline{\psi} \rightarrow \vec{P}_v \underline{\psi} \end{cases}$$

$$\left\{ \begin{array}{l} E_v = \frac{M_0 c_t^2}{\gamma} = \frac{E_0^{dist} + V(\vec{r}, t)}{\gamma} \\ M_0 c_t^2 = E_0^{dist} + V(\vec{r}, t) \\ \vec{P}_v = \frac{M_0}{\gamma} \vec{v} = \frac{E_0^{dist} + V(\vec{r}, t)}{\gamma c_t^2} \vec{v} \end{array} \right. \quad \gamma = \sqrt{1 - \frac{\vec{v}^2}{c_t^2}}$$

$$\hbar \underline{\omega}_f = \pm \frac{E_0^{dist} + V(\vec{r}, t)}{\gamma} \left( 1 \pm i \frac{\vec{v}}{c_t} \right)$$

Complex frequency of the gravitational fluctuations, and relativistic wave equation (different from Dirac equation!)

$$\hbar^2 \frac{\partial^2 \underline{\psi}}{\partial t^2} + 2 \frac{E_0^{dist} + V(\vec{r}, t)}{\gamma} \left( 1 \pm i \frac{\vec{v}}{c_t} \right) i \hbar \frac{\partial \underline{\psi}}{\partial t} - \frac{(E_0^{dist} + V(\vec{r}, t))^2}{\gamma^2} \left( 1 \pm i \frac{\vec{v}}{c_t} \right)^2 \underline{\psi} \equiv -c_t^2 \hbar^2 \Delta \underline{\psi}$$

## Solution for a relativistic quasi-free singularity

$$\tau_{\text{rel}}^{(p)}(\vec{r}, t) \equiv \psi_0 e^{-\frac{1}{\hbar c_t \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) |x_2 \mp \mathbf{v}|} \cos \left[ \frac{1}{\hbar \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) t \right] \cos \left[ \frac{1}{\hbar \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) \frac{\mathbf{v}}{c_t^2} x_2 \right] \mp \psi_0 e^{-\frac{1}{\hbar c_t \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) |x_2 \mp \mathbf{v}|} \sin \left[ \frac{1}{\hbar \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) t \right] \sin \left[ \frac{1}{\hbar \gamma} (E_0^{\text{dist}} + V(\vec{r}, t)) \frac{\mathbf{v}}{c_t^2} x_2 \right]$$

Oscillations with a frequency, a wave length and a range which depend on the relativistic velocity:

$$f = \frac{E_0^{\text{dist}} + V(\vec{r}, t)}{2\pi\hbar\gamma} = \frac{E_0^{\text{dist}} + V(\vec{r}, t)}{2\pi\hbar\sqrt{1 - \vec{\mathbf{v}}^2/c_t^2}}$$

$$\lambda = \frac{2\pi\hbar c_t^2 \gamma}{(E_0^{\text{dist}} + V(\vec{r}, t)) \mathbf{v}} = \frac{2\pi\hbar c_t^2}{(E_0^{\text{dist}} + V(\vec{r}, t)) \mathbf{v}} \sqrt{1 - \vec{\mathbf{v}}^2/c_t^2}$$

$$\delta = \frac{\hbar c_t \gamma}{E_0^{\text{dist}} + V(\vec{r}, t)} = \frac{\hbar c_t}{E_0^{\text{dist}} + V(\vec{r}, t)} \sqrt{1 - \vec{\mathbf{v}}^2/c_t^2}$$

## Schrödinger equation for a non-relativistic singularity submitted to a potential

$$\gamma = \sqrt{1 - \frac{\vec{\mathbf{v}}^2}{c_t^2}} \rightarrow 1 \quad \& \quad \hbar^2 \frac{\partial^2 \underline{\psi}}{\partial t^2} = -E_{\mathbf{v}}^2 \underline{\psi} \rightarrow - (E_0^{\text{dist}} + V(\vec{r}, t))^2 \underline{\psi} \quad \Rightarrow \quad \text{Schrödinger equation}$$

$$i\hbar \frac{\partial \underline{\psi}}{\partial t} \equiv -\frac{\hbar^2}{2M_0} \Delta \underline{\psi} + (E_0^{\text{dist}} + V(\vec{r}, t)) \underline{\psi}$$

Justify « *a fortiori* » the conjecture of using the quantum physics operators with the relativistic dynamic relations

$$\underline{\tau}^{(p)}(\vec{r}, t) \equiv \underline{\psi}(\vec{r}, t) e^{\pm i\omega_f(\vec{r}, t)t} \equiv \underline{\psi}(\vec{r}, t) e^{\frac{i(E_0^{\text{dist}} + V(\vec{r}, t))t}{\hbar}}$$

Oscillations of the dynamic gravitational field



Erwin Schrödinger  
(1887-1961)



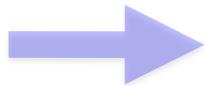
1/ The schrödinger equation is a wave equation deduced from the second partial Newton equation of the cosmic lattice

2/ It allows one to calculate the amplitude and the phase of the gravitational fluctuations of frequency  $\omega_f(\vec{r}, t)$  associated to a non-relativistic moving singularity submitted to a potential

3/ All the well known consequences of quantum physics can be applied:  
stationnary wave equation, commutators, uncertainty principle of Heisenberg, probabilistic interpretation of the wave function, etc.

## Stationary state of two coupled mobile singularities

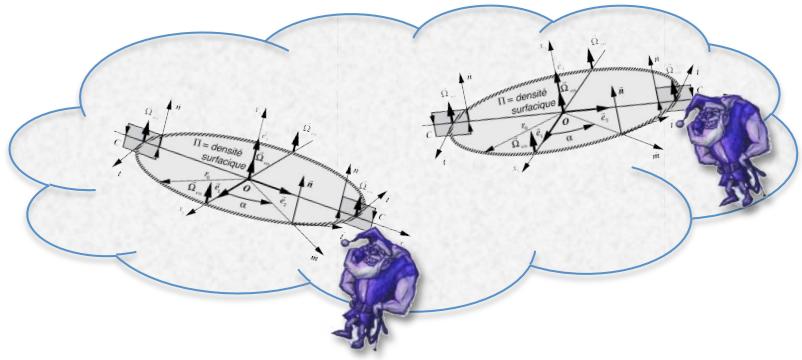
$$\begin{cases} -\frac{\hbar^2}{2M_0}\Delta \underline{\psi}_n(\vec{r}_a) + V(\vec{r}_a)\underline{\psi}_n(\vec{r}_a) = E_n \underline{\psi}_n(\vec{r}_a) \\ -\frac{\hbar^2}{2M_0}\Delta \underline{\psi}_m(\vec{r}_b) + V(\vec{r}_b)\underline{\psi}_m(\vec{r}_b) = E_m \underline{\psi}_m(\vec{r}_b) \end{cases}$$



**Stationary coupled Schrödinger equation**

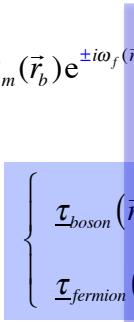
$$-\frac{\hbar^2}{2M_0}\Delta [\underline{\psi}_n(\vec{r}_a)\underline{\psi}_m(\vec{r}_b)] + [V(\vec{r}_a) + V(\vec{r}_b)]\underline{\psi}_n(\vec{r}_a)\underline{\psi}_m(\vec{r}_b) = (E_n + E_m)\underline{\psi}_n(\vec{r}_a)\underline{\psi}_m(\vec{r}_b)$$

**Stationary Schrödinger equations**



**Two possible solutions for the gravitational fluctuations with frequency oscillations:**

$$\begin{cases} \underline{\tau}_{boson}(\vec{r}_a, \vec{r}_b, t) = \underline{\psi}_n(\vec{r}_a)\underline{\psi}_m(\vec{r}_b)e^{\pm i\frac{1}{\hbar}(2E_0^{dist} + V(\vec{r}_a) + V(\vec{r}_b))t} \\ \underline{\tau}_{fermion}(\vec{r}_a, \vec{r}_b, t) = \underline{\psi}_n(\vec{r}_a)\underline{\psi}_m(\vec{r}_b)e^{\pm i\frac{1}{\hbar}(V(\vec{r}_a) - V(\vec{r}_b))t} \end{cases}$$



$$\begin{cases} \omega_{boson}(\vec{r}_a, \vec{r}_b) = \pm \frac{1}{\hbar}(2E_0^{dist} + V(\vec{r}_a) + V(\vec{r}_b)) \rightarrow \pm \frac{2E_0^{dist}}{\hbar} \text{ si } \vec{r}_a \rightarrow \vec{r}_b \\ \omega_{fermion}(\vec{r}_a, \vec{r}_b) = \pm \frac{1}{\hbar}(V(\vec{r}_a) - V(\vec{r}_b)) \rightarrow 0 \text{ si } \vec{r}_a \rightarrow \vec{r}_b \rightarrow \text{impossible} \end{cases}$$



1/ There are two possible solutions for the gravitational perturbations of two coupled singularities: the bosons solution and the fermions solution



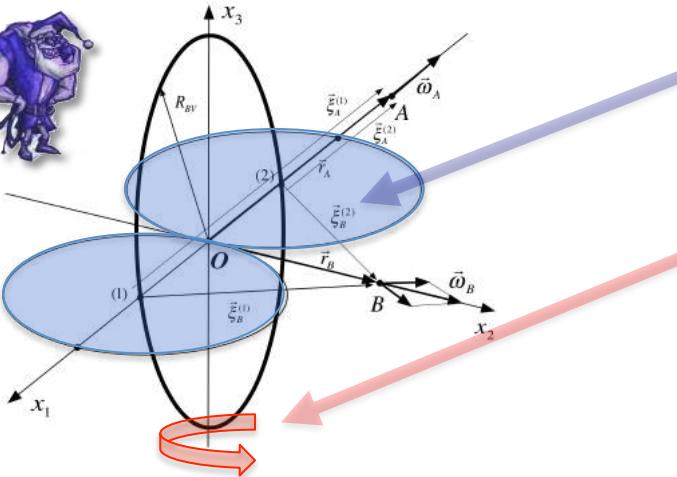
2/ For the fermions solution, superposition of the two singularities is impossible because the gravitational fluctuations will disappear in this case!  
=> Pauli exclusion principle for the fermions solution

3/ All the well known consequences of quantum physics can be applied: indiscernability principle, symmetric and antisymmetric solutions, etc.

# Dynamic internal gravitational field of a singularity: the spin of the singularity

**Second partial Newton equation  
(in the static case)**

$$K_1(\tau^{(p)}(\vec{r}))^2 + [4K_2/3 + 2K_1(1 + \tau_0 + \tau^{ext}(\vec{r}) + \tau^{ch}(\vec{r})) - K_0]\tau^{(p)}(\vec{r}) + (F_{dist}^{ch}(\vec{r}) + F_{pot}^{ch}(\vec{r})) = cste = 0$$



**Quantification of the angular momentum  
and the magnetic momentum of the loop,  
with right value of the Bohr magneton!**

**There is no static solution  
in the heart of the singularity if:**

$$K_1 > K_{1cr} = K_0 \frac{2\pi^4 R_{BV}^2}{q_{\lambda BV}^2} \approx 10^{-21}$$

**Need for a dynamic solution:  
rotation of the loop around a diameter**



**Solution of the stationary  
Schrödinger equation:**

$$\begin{cases} \epsilon_j = \frac{\hbar^2}{2I} j(j+1) \\ m_z = j, j-1, \dots, 1-j, -j \end{cases}$$

$$\begin{cases} E_{rotation BV}^{cin} = \hbar^2 j(j+1)/2I_{BV} \\ |\vec{L}_{BV}| = \sqrt{2I_{BV} E_{rotation BV}^{cin}} = \hbar \sqrt{j(j+1)} \\ L_z = \hbar m_z \end{cases}$$

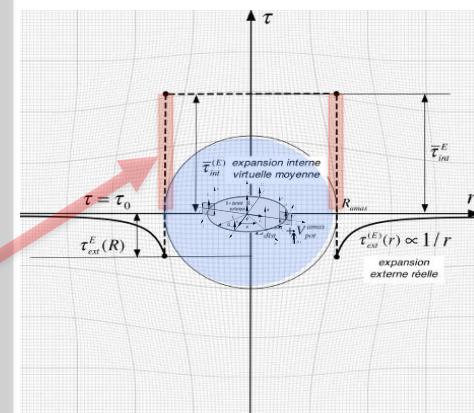
$$\Leftrightarrow \begin{cases} I_{BV} = \delta_1 \frac{M_0^{BV} R_{BV}^2}{4} \\ \vec{\mu}_{BVz} \equiv g_{BV} \frac{\hbar q_{\lambda BV}}{2M_0} m_z \vec{e}_z \end{cases}$$



1/ No static solution for the internal gravitational field of a singularity loop if  $K_1 > 10^{-21}$   
=> the singularity loop has really to turn around an axis

2/ Solution of the stationary Schrödinger equation:  
=> quantified spin of the singularity loop, with  $j=1/2, 1, \dots$

3/ The argument of the pioneers of quantum physics against a real rotation of the charge  
based on the fact that the equatorial velocity of the charge would be higher  
than the light velocity is wrong if  $K_1 < 1,8 \cdot 10^9$   
due to the enormous static expansion in the vicinity of the loop.



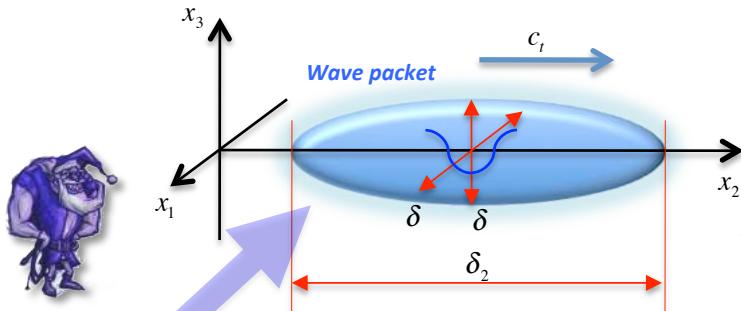
## Transversal wave packets: the photons

Transversal wave packets needs helicity  
to present a constant energy



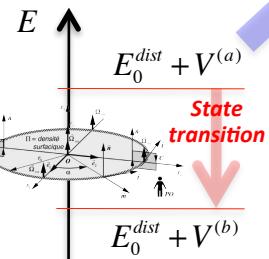
$$\left\{ \begin{array}{l} \underline{\omega}_1(x_2,t) = \omega_{10} e^{\frac{|x_1|}{\delta}} e^{\frac{|x_3|}{\delta}} e^{-\frac{|x_2-c_t t|}{\delta_2}} e^{i \frac{\omega}{c_t} (x_2 - c_t t)} \\ \underline{\omega}_3(x_2,t) = \pm i \omega_{10} e^{\frac{|x_1|}{\delta}} e^{\frac{|x_3|}{\delta}} e^{-\frac{|x_2-c_t t|}{\delta_2}} e^{i \frac{\omega}{c_t} (x_2 - c_t t)} \end{array} \right.$$

$$\left\{ \begin{array}{l} \underline{\phi}_3(x_2,t) = -2c_t \omega_{10} e^{\frac{|x_1|}{\delta}} e^{\frac{|x_3|}{\delta}} e^{-\frac{|x_2-c_t t|}{\delta_2}} e^{i \frac{\omega}{c_t} (x_2 - c_t t)} \\ \underline{\phi}_1(x_2,t) = \pm i 2c_t \omega_{10} e^{\frac{|x_1|}{\delta}} e^{\frac{|x_3|}{\delta}} e^{-\frac{|x_2-c_t t|}{\delta_2}} e^{i \frac{\omega}{c_t} (x_2 - c_t t)} \end{array} \right.$$



$$E^{fluctuation} = 4K_3 \omega_{10}^2 \delta^2 \delta_2$$

Constant energy of  
the wave packet  
with helicity



$$\Delta E_{perdue} = E_0^{\text{dist}} + V^{(a)} - (E_0^{\text{dist}} + V^{(b)}) = V^{(a)} - V^{(b)} = \hbar \underline{\omega}_f^{(a)} - \hbar \underline{\omega}_f^{(b)} = \hbar (\underline{\omega}_f^{(a)} - \underline{\omega}_f^{(b)})$$

Energy of formation



$$E^{fluctuation} = 4K_3 \omega_{10}^2 \delta^2 \delta_2 = \hbar (\underline{\omega}_f^{(a)} - \underline{\omega}_f^{(b)}) = \hbar \underline{\omega}_{\text{fluctuation}}$$

1/ A constant energy of the wave packet needs helicity

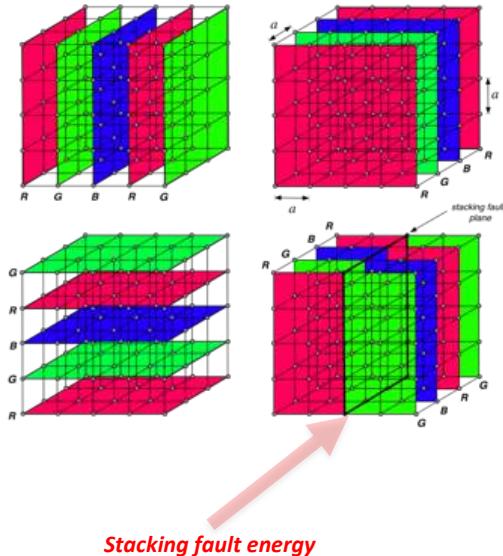
=> energy of the wave packet depends on packet physical dimensions and wave amplitude



2/ The energy of formation is related to a state transition of a topological singularity  
=> quantified energy of the wave packet proportional to the frequency of the wave

3/ there is a « plasticity » of the physical dimensions of the wave packet  
=> explanations of non-locality, momentum, wave-particle duality, diffraction, interference,  
entanglement, decoherence, etc.

## Standard model of elementary particles: a « coloured » cubic lattice



1/ Introduce a « coloured » cubic lattice with three simple rules concerning the alternance and the rotation of the coloured planes

G

The three rules

Rule 1: the alternation of planes R, G, B cannot be broken (either by impossibility or by a very large energy associated with a surface stacking fault energy ).

Rule 2: in a given direction of space, there may appear a stacking fault corresponding to a shift in the alternation of planes R, G, B, which possesses a surface stacking fault energy which is not null.

Rule 3: if a plane with a given color undergoes a rotation by an angle, or it changes color according to table 31.1, which corresponds to the existence of a given axial property of the lattice.

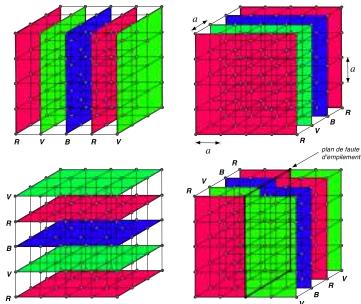


rotation angle $\Omega_{TL}$	color change	colors R, G, B and complementary colors $\bar{R}$ , $\bar{G}$ , $\bar{B}$
$\left\{ \begin{array}{l} +3\pi/2 \\ 0 \\ -3\pi/2 \end{array} \right.$	$\left\{ \begin{array}{l} R \rightarrow R \\ G \rightarrow G \\ B \rightarrow B \end{array} \right.$	
	$\left\{ \begin{array}{l} R \rightarrow G \\ G \rightarrow B \\ B \rightarrow R \end{array} \right.$	
$\left\{ \begin{array}{l} +\pi/2 \\ -\pi \end{array} \right.$	$\left\{ \begin{array}{l} R \rightarrow G \\ G \rightarrow B \\ B \rightarrow R \end{array} \right.$	
	$\left\{ \begin{array}{l} R \rightarrow B \\ G \rightarrow R \\ B \rightarrow G \end{array} \right.$	

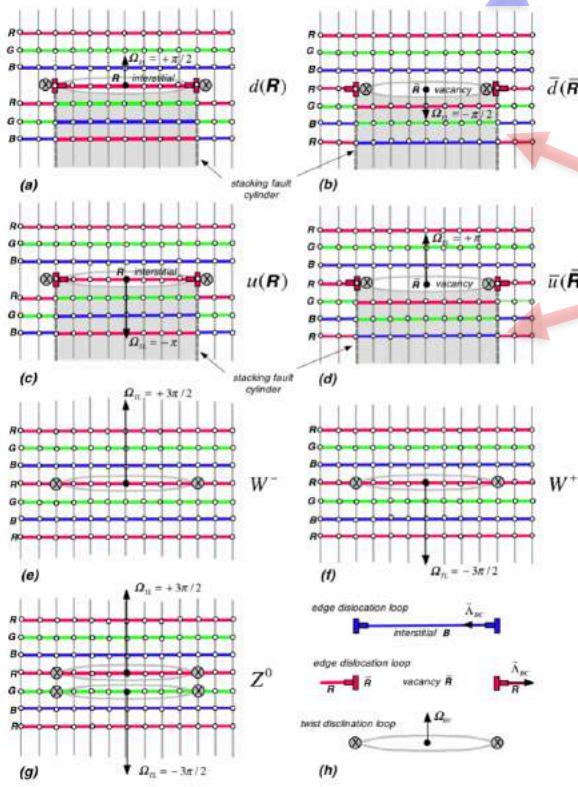


Steven Weinberg, Abdus Salam and Sheldon Glashow

# Standard model of elementary particles: quarks and leptons



2/ Combine edge dislocation loops and screw disclination loops

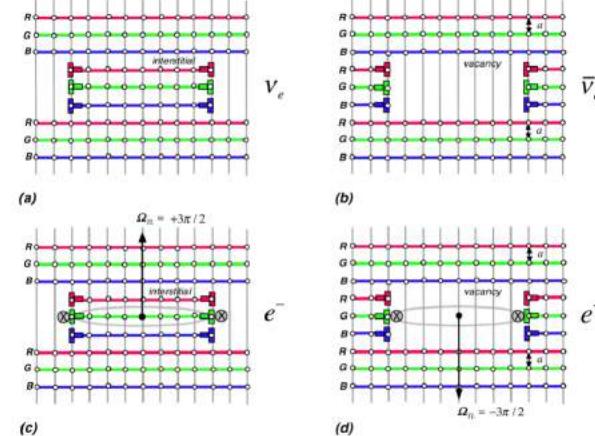


name	$\Omega_{TL}$	$q_{\lambda_{TL}}$	edge loop	$q_{\theta_{EL}}$	color
$d$	$+\pi/2$	$-\pi^2 R_{TL}^2 / 2$	interstitial	$-2\pi a$	$R, G$ or $B$
$u$	$-\pi$	$+\pi^2 R_{TL}^2$	interstitial	$-2\pi a$	$R, G$ or $B$
$\bar{d}$	$-\pi/2$	$+\pi^2 R_{TL}^2 / 2$	vacancy	$+2\pi a$	$\bar{R}, \bar{G}$ or $\bar{B}$
$\bar{u}$	$+\pi$	$-\pi^2 R_{TL}^2$	vacancy	$+2\pi a$	$\bar{R}, \bar{G}$ or $\bar{B}$
$W^-$	$+3\pi/2$	$-3\pi^2 R_{TL}^2$	-	$0$	-
$W^+$	$-3\pi/2$	$+3\pi^2 R_{TL}^2$	-	$0$	-
$Z^0$	$(+3\pi/2) + (-3\pi/2)$	$0$	-	$0$	-

quarks  
gauge bosons

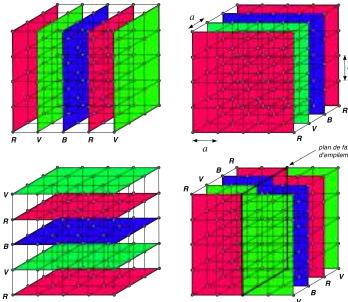


leptons



symbol	$\Omega_{TL}$	$q_{\lambda_{TL}}$	edge loop	$q_{\theta_{EL}}$
$V_e$	$+3\pi/2$	$0$	interstitial	$-6\pi a$
$e^-$	$0$	$-3\pi^2 R_{TL}^2 / 2$	interstitial	$-6\pi a$
$\bar{V}_e$	$-3\pi/2$	$0$	vacancy	$6\pi a$
$e^+$	$-3\pi$	$+3\pi^2 R_{TL}^2 / 2$	vacancy	$6\pi a$
$W^-$	$+3\pi/2$	$-3\pi^2 R_{TL}^2 / 2$	-	$0$
$W^+$	$-3\pi/2$	$+3\pi^2 R_{TL}^2 / 2$	-	$0$
$Z^0$	$(+3\pi/2) + (-3\pi/2)$	$0$	-	$0$

# Standard model of elementary particles: baryons, mesons and strong interaction

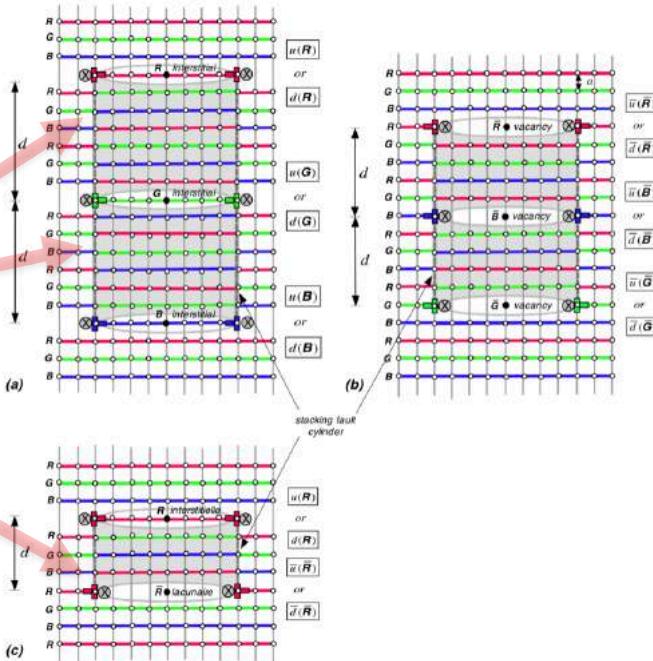


3/ Combine two or three dispiration loops (quarks)

baryons and mesons  
strong interactions



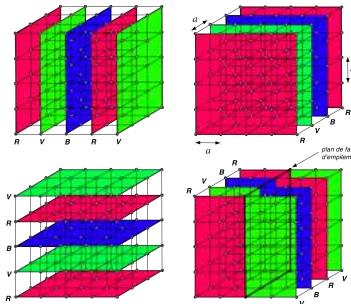
Stacking fault energy  
=> strong interaction



combination	symbol	$\Omega_{TL}$	$q_{\lambda TL}$	edge loop	$q_{\theta EL}$
$ddd$	$\Delta^-$	$+3\pi/2$	$-3\pi^2 R_{TL}^2/2$	interstitial	$-6\pi a$
$du d$	$n, \Delta^0$	0	0	interstitial	$-6\pi a$
$udu$	$p, \Delta^+$	$-3\pi/2$	$+3\pi^2 R_{TL}^2/2$	interstitial	$-6\pi a$
$uuu$	$\Delta^{++}$	$-3\pi$	$+3\pi^2 R_{TL}^2$	interstitial	$-6\pi a$
$\bar{d} \bar{d} \bar{d}$	$\bar{\Delta}^+$	$-3\pi/2$	$+3\pi^2 R_{TL}^2/2$	vacancy	$6\pi a$
$\bar{d} \bar{u} \bar{d}$	$\bar{n}, \bar{\Delta}^0$	0	0	vacancy	$6\pi a$
$\bar{u} \bar{d} \bar{u}$	$\bar{p}, \bar{\Delta}^-$	$+3\pi/2$	$-3\pi^2 R_{TL}^2/2$	vacancy	$6\pi a$
$\bar{u} \bar{u} \bar{u}$	$\bar{\Delta}^-$	$+3\pi$	$-3\pi^2 R_{TL}^2$	vacancy	$6\pi a$

combination	symbol	$\Omega_{TL}$	$q_{\lambda TL}$	edge loop	$q_{\theta EL}$
$d\bar{d}$	$\pi^0, \rho^0$	0	0	-	0
$d\bar{u}$	$\pi^-, \rho^-$	$+3\pi/2$	$-3\pi^2 R_{TL}^2/2$	-	0
$\bar{d} u$	$\pi^+, \rho^+$	$-3\pi/2$	$+3\pi^2 R_{TL}^2/2$	-	0
$u\bar{u}$	$\eta^0, \omega^0$	0	0	-	0

# Standard model of elementary particles: gluons, strong and weak interactions

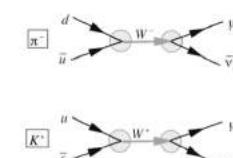
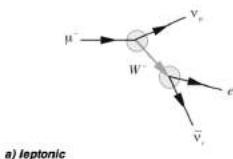
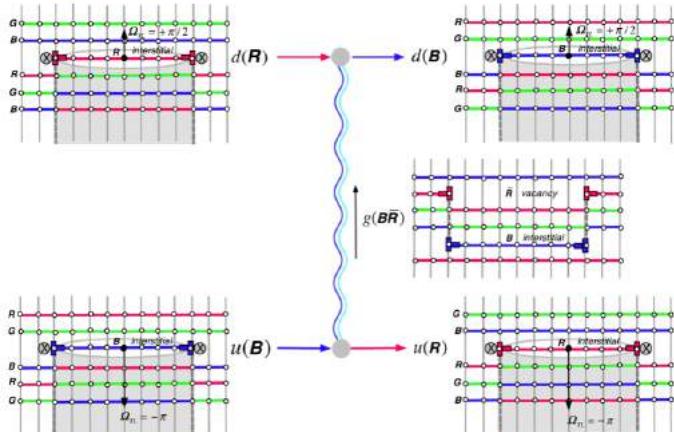


4/ Exchange edge dislocation loops or twist disclination loops

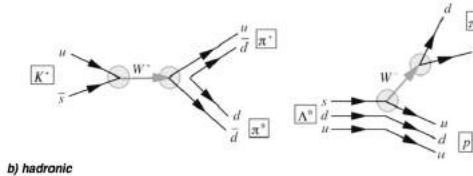


gluons  
strong interactions

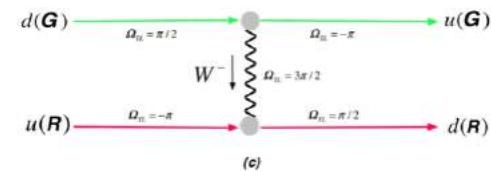
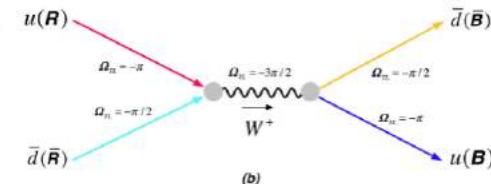
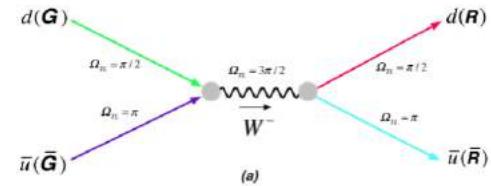
gauge bosons  
weak interactions



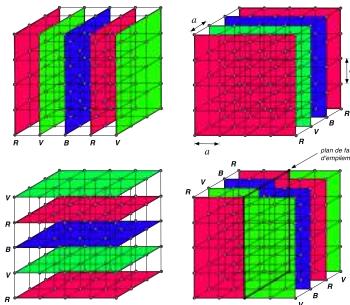
b) semi-leptonic



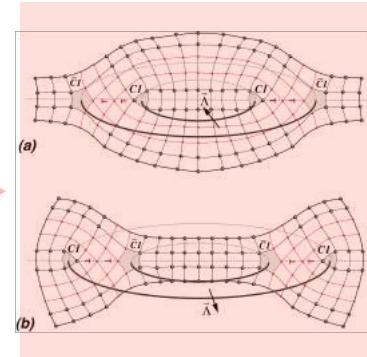
b) hadronic



# Standard model of elementary particles: the three families of particles



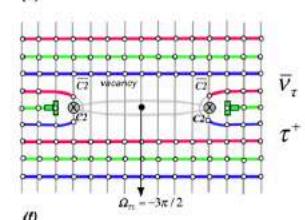
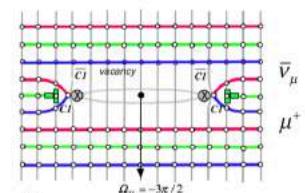
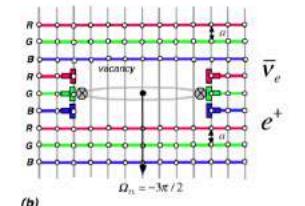
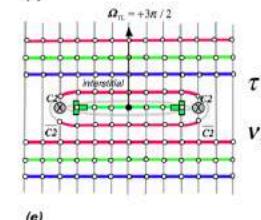
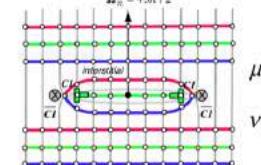
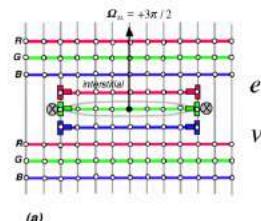
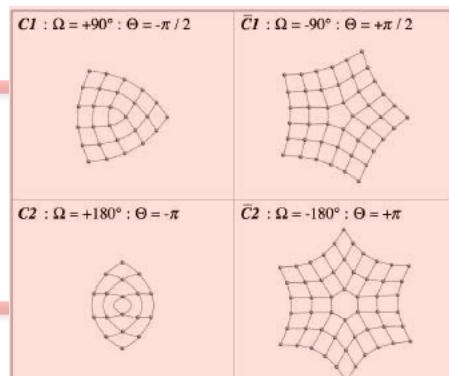
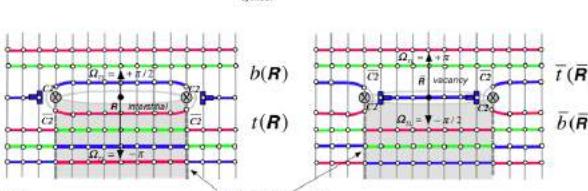
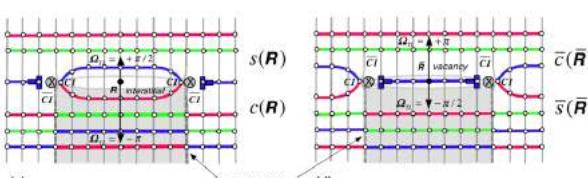
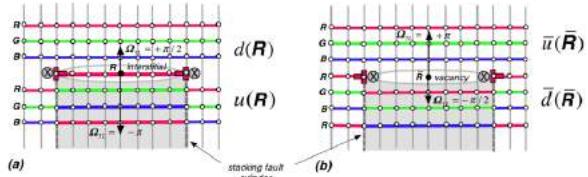
5/ Replace edge dislocation loops  
by wedge disclination loops



three families  
of quarks

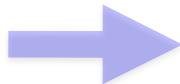
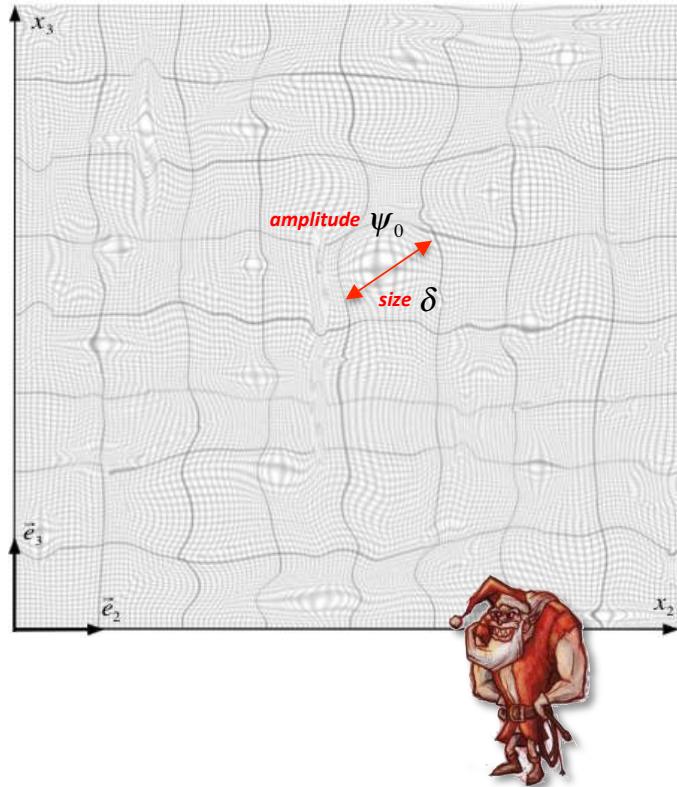


three families  
of leptons



## II E - Some other hypothetical consequences of the cosmic lattice

### Gravitational fluctuations of the expansion: quantum vacuum state



Distortion energy  
of each fluctuation

$$E^{\text{fluctuation}}(t) \equiv E^{\text{dist}}(t) \equiv -8K_0\psi_0\delta^3 \cos\omega t$$

Superposition of  
numerous fluctuations

$$\tau^{(p)}(\vec{r}, t) = \sum_k \psi_{0k} e^{-\frac{|x_1-x_{1k}|}{\delta_{1k}}} e^{-\frac{|x_2-x_{2k}|}{\delta_{2k}}} e^{-\frac{|x_3-x_{3k}|}{\delta_{3k}}} e^{-i(\omega_k t + \varphi_k)}$$

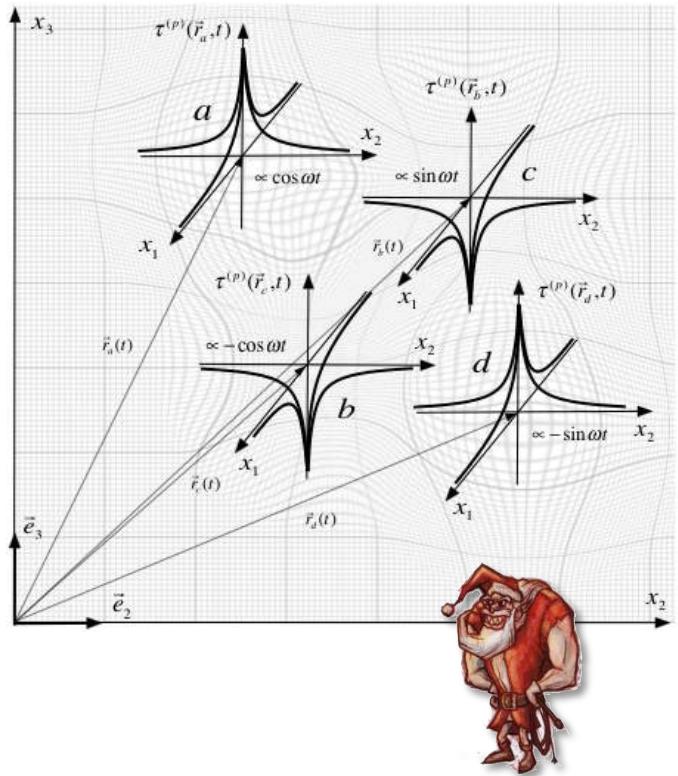
Zero average energy  
of all fluctuations

$$\langle E^{\text{fluctuation}}(t) \rangle = 0$$



1/ It could exist gravitational fluctuations of the expansion field with zero average energy (corresponding to distortion energy)  
=> analogy with quantum vacuum state

## Stable gravitational fluctuations of the expansion: multiverses and gravitons



Coupling of four gravitational fluctuations

$$\tau^{(p)}(\vec{r}, t) \equiv \left[ +\psi_{0a} e^{\frac{|x_1-x_{a1}(t)|}{\delta_{a1}}} e^{\frac{|x_2-x_{a2}(t)|}{\delta_{a2}}} e^{\frac{|x_3-x_{a3}(t)|}{\delta_{a3}}} \cos \omega t - \psi_{0b} e^{\frac{|x_1-x_{b1}(t)|}{\delta_{b1}}} e^{\frac{|x_2-x_{b2}(t)|}{\delta_{b2}}} e^{\frac{|x_3-x_{b3}(t)|}{\delta_{b3}}} \cos \omega t \right. \\ \left. \pm \psi_{0c} e^{\frac{|x_1-x_{c1}(t)|}{\delta_{c1}}} e^{\frac{|x_2-x_{c2}(t)|}{\delta_{c2}}} e^{\frac{|x_3-x_{c3}(t)|}{\delta_{c3}}} \sin \omega t \mp \psi_{0d} e^{\frac{|x_1-x_{d1}(t)|}{\delta_{d1}}} e^{\frac{|x_2-x_{d2}(t)|}{\delta_{d2}}} e^{\frac{|x_3-x_{d3}(t)|}{\delta_{d3}}} \sin \omega t \right]$$

$$\psi_{a0} = \psi_{b0} = \psi_{c0} = \psi_{d0} = \psi_0$$

Conditions for stable gravitational fluctuations with a constant energy

$$\begin{cases} \delta_{a1}\delta_{a2}\delta_{a3} = \delta_{b1}\delta_{b2}\delta_{b3} = \delta_{c1}\delta_{c2}\delta_{c3} = \delta_{d1}\delta_{d2}\delta_{d3} = ABC \\ \frac{1}{\delta_{a1}^2} + \frac{1}{\delta_{a2}^2} + \frac{1}{\delta_{a3}^2} = \frac{1}{\delta_{b1}^2} + \frac{1}{\delta_{b2}^2} + \frac{1}{\delta_{b3}^2} = \frac{1}{\delta_{c1}^2} + \frac{1}{\delta_{c2}^2} + \frac{1}{\delta_{c3}^2} = \frac{1}{\delta_{d1}^2} + \frac{1}{\delta_{d2}^2} + \frac{1}{\delta_{d3}^2} = \frac{1}{A^2} + \frac{1}{B^2} + \frac{1}{C^2} \\ \delta_{a1}^2 + \delta_{a2}^2 + \delta_{a3}^2 = \delta_{b1}^2 + \delta_{b2}^2 + \delta_{b3}^2 = \delta_{c1}^2 + \delta_{c2}^2 + \delta_{c3}^2 = \delta_{d1}^2 + \delta_{d2}^2 + \delta_{d3}^2 = A^2 + B^2 + C^2 \end{cases}$$

Constant kinetic energy of the four fluctuations

$$\begin{cases} E^{\text{fluctuation}} \cong E^{\text{kin}} \cong \frac{K_0}{9} \psi_0^2 ABC (A^2 + B^2 + C^2) \left( \frac{1}{A^2} + \frac{1}{B^2} + \frac{1}{C^2} \right) \\ \omega \cong c \sqrt{\frac{1}{A^2} + \frac{1}{B^2} + \frac{1}{C^2}} \end{cases}$$

1/ It could exist coupled gravitational fluctuations of the expansion field with a constant energy (corresponding to kinetic energy)



2/ At macroscopic scale, could explain « multiverses » in an infinite cosmological lattice

2/ At microscopic scale, could correspond to stable « gravitons »

## *Conclusion of the second part*



**Newton equation  
of cosmological lattice**

$$n \frac{d\vec{p}}{dt} = -2(K_2 + K_3) \vec{\text{rot}} \vec{\omega}^{\text{el}} + \left( \frac{4}{3}K_2 + 2K_1 \right) \vec{\text{grad}} \tau + 2K_2 \vec{\lambda} + nm\vec{\phi}_I \frac{dC_I}{dt} - nm\vec{\phi}_L \frac{dC_L}{dt}$$
$$+ \vec{\text{grad}} \underbrace{\left[ K_2 \sum_i (\vec{\alpha}_i^{\text{el}})^2 + K_1^{\text{an}} \sum_i (\vec{\alpha}_i^{\text{an}})^2 + 2K_3 (\vec{\omega}^{\text{el}})^2 + 2K_2^{\text{an}} (\vec{\omega}^{\text{an}})^2 + K_1 \tau^2 - K_0 \tau \right]}_{F^{\text{def}}}$$

**+ special coloured structure  
of cosmological lattice**

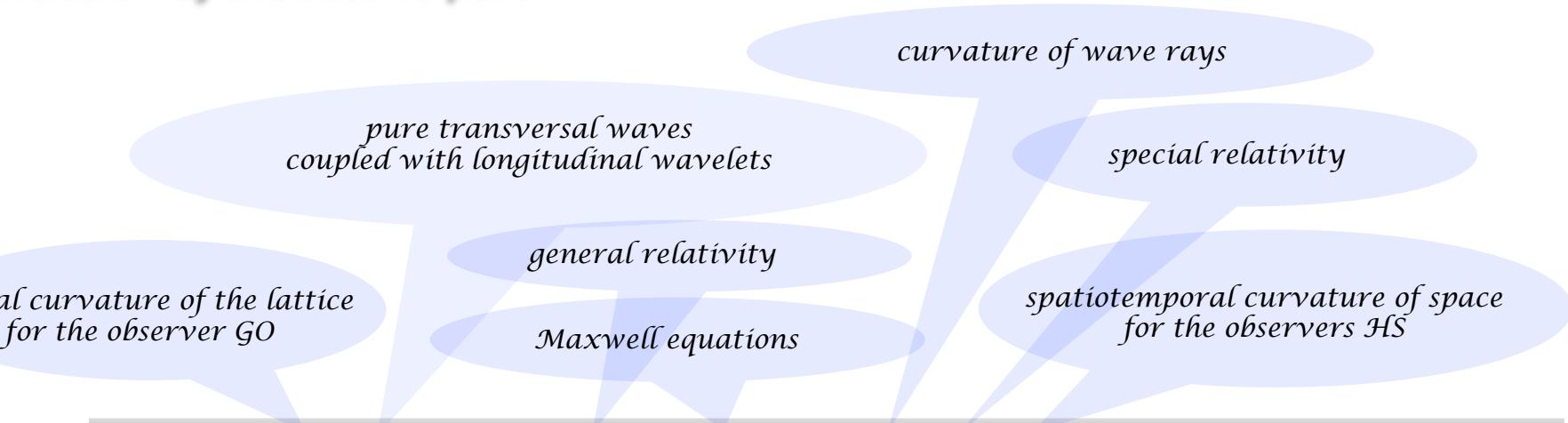
*Newtonian gravity*

*standard model of elementary particles,  
quarks, leptons, strong and weak interactions*

*modern cosmology*

*black holes, black matter, black energy*

*exclusion principle*



*bosons, fermions, uncertainty principle,  
photons, gravitons, multiverses, quantum vacuum state*